# P20 <br> P30 <br> P45 <br> P50 P65 

## Gas burners

MANUAL OF INSTALLATION - USE - MAINTENANCE

## CIB HITIGAS

# DANGERS, WARNINGS AND NOTES OF CAUTION <br> THIS MANUAL IS SUPPLIED AS AN INTEGRAL AND ESSENTIAL PART OF THE PRODUCT AND MUST BE DELIVERED TO THE USER. 

## INFORMATION INCLUDED IN THIS SECTION ARE DEDICATED BOTH TO THE USER AND TO PERSONNEL FOLLOWING PRODUCT INSTALLATION AND MAINTENANCE.

## THE USER WILL FIND FURTHER INFORMATION ABOUT OPERATING AND USE RESTRICTIONS, IN THE SECOND SECTION OF THIS MANUAL. WE HIGHLY RECOMMEND TO READ IT. CAREFULLY KEEP THIS MANUAL FOR FUTURE REFERENCE.

## 1) GENERAL INTRODUCTION

- The equipment must be installed in compliance with the regulations in force, following the manufacturer's instructions, by qualified personnel.
- Qualified personnel means those having technical knowledge in the field of components for civil or industrial heating systems, sanitary hot water generation and particularly service centres authorised by the manufacturer
- Improper installation may cause injury to people and animals, or damage to property, for which the manufacturer cannot be held liable.
- Remove all packaging material and inspect the equipment for integrity. In case of any doubt, do not use the unit - contact the supplier.
The packaging materials (wooden crate, nails, fastening devices, plastic bags, foamed polystyrene, etc), should not be left within the reach of children, as they may prove harmful.
- Before any cleaning or servicing operation, disconnect the unit from the mains by turning the master switch OFF, and/or through the cutout devices that are provided.
- Make sure that inlet or exhaust grilles are unobstructed.
- In case of breakdown and/or defective unit operation, disconnect the unit. Make no attempt to repair the unit or take any direct action.
Contact qualified personnel only.
Units shall be repaired exclusively by a servicing centre, duly authorised by the manufacturer, with original spare parts and accessories
Failure to comply with the above instructions is likely to impair the unit's safety.
To ensure equipment efficiency and proper operation, it is essential that maintenance operations are performed by qualified personnel at regular intervals, following the manufacturer's instructions
- When a decision is made to discontinue the use of the equipment, those parts likely to constitute sources of danger shall be made harmless.
- In case the equipment is to be sold or transferred to another user, or in case the original user should move and leave the unit behind, make sure that these instructions accompany the equipment at all times so that they can be consulted by the new owner and/or the installer.
- This unit shall be employed exclusively for the use for which it is meant. Any other use shall be considered as improper and, therefore, dangerous.
The manufacturer shall not be held liable, by agreement or otherwise, for damages resulting from improper installation, use and failure to comply with the instructions supplied by the manufacturer. The occurrence of any of the following circustances may cause explosions, polluting unburnt gases (example: carbon monoxide CO), burns, serious harm to people, animals and things:
- Failure to comply with one of the WARNINGS in this chapter
- Incorrect handling, installation, adjustment or maintenance of the burner
- Incorrect use of the burner or incorrect use of its parts or optional supply


## 2) SPECIAL INSTRUCTIONS FOR BURNERS

- The burner should be installed in a suitable room, with ventilation openings complying with the requirements of the regulations in force, and sufficient for good combustion.
- Only burners designed according to the regulations in force should be used.
- This burner should be employed exclusively for the use for which it was designed.
- Before connecting the burner, make sure that the unit rating is the same as delivery mains (electricity, gas oil, or other fuel).
- Observe caution with hot burner components. These are, usually, near to the flame and the fuel pre-heating system, they become hot during the unit operation and will remain hot for some time after the burner has stopped.

When the decision is made to discontinue the use of the burner, the use shall have qualified personnel carry out the following operations:
a Remove the power supply by disconnecting the power cord from the mains
b Disconnect the fuel supply by means of the hand-operated shut-off valve and remove the control handwheels from their spindles.

## Special warnings

- Make sure that the burner has, on installation, been firmly secured to the appliance, so that the flame is generated inside the appliance firebox.
- Before the burner is started and, thereafter, at least once a year, have qualified personnel perform the following operations:
a set the burner fuel flow rate depending on the heat input of the appliance;
b set the flow rate of the combustion-supporting air to obtain a combustion efficiency level at least equal to the lower level required by the regulations in force;
c check the unit operation for proper combustion, to avoid any harmful or polluting unburnt gases in excess of the limits permitted by the regulations in force;
d make sure that control and safety devices are operating properly;
e make sure that exhaust ducts intended to discharge the products of combustion are operating properly;
f on completion of setting and adjustment operations, make sure that all mechanical locking devices of controls have been duly tightened;
$g$ make sure that a copy of the burner use and maintenance instructions is available in the boiler room.
- In case of a burner shut-down, reser the control box by means of the RESET pushbutton. If a second shut-down takes place, call the Technical Service, without trying to RESET further
- The unit shall be operated and serviced by qualified personnel only, in compliance with the regulations in force.


## 3) GENERAL INSTRUCTIONS DEPENDING ON FUEL USED

## 3a) ELECTRICAL CONNECTION

- For safety reasons the unit must be efficiently earthed and installed as required by current safety regulations.
- It is vital that all saftey requirements are met. In case of any doubt, ask for an accurate inspection of electrics by qualified personnel, since the manufacturer cannot be held liable for damages that may be caused by failure to correctly earth the equipment
- Qualified personnel must inspect the system to make sure that it is adequate to take the maximum power used by the equipment shown on the equipment rating plate. In particular, make sure that the system cable cross section is adequate for the power absorbed by the unit.
- No adaptors, multiple outlet sockets and/or extension cables are permitted to connect the unit to the electric mains.
- An omnipolar switch shall be provided for connection to mains, as required by the current safety regulations.
- The use of any power-operated component implies observance of a few basic rules, for example:
-do not touch the unit with wet or damp parts of the body and/or with bare feet;
- do not pull electric cables;
- do not leave the equipment exposed to weather (rain, sun, etc.) unless expressly required to do so;
- do not allow children or inexperienced persons to use equipment;
- The unit input cable shall not be replaced by the user.

In case of damage to the cable, switch off the unit and contact qualified personnel to replace.
When the unit is out of use for some time the electric switch supplying all the power-driven components in the system (i.e. pumps, burner, etc.) should be switched off.

## 3b) FIRING WITH GAS, LIGHT OIL OR OTHER FUELS

## GENERAL

- The burner shall be installed by qualified personnel and in compliance with regulations and provisions in force; wrong installation can cause injuries to people and animals, or damage to property, for which the manufacturer cannot be held liable.
- Before installation, it is recommended that all the fuel supply system pipes be carefully cleaned inside, to remove foreign matter that might impair the burner operation.
- Before the burner is commissioned, qualified personnel should inspect the following:
a the fuel supply system, for proper sealing;
b the fuel flow rate, to make sure that it has been set based on the firing rate required of the burner;
c the burner firing system, to make sure that it is supplied for the designed fuel type;
d the fuel supply pressure, to make sure that it is included in the range shown on the rating plate;
e the fuel supply system, to make sure that the system dimensions are adequate to the burner firing rate, and that the system is equipped with all the safety and control devices required by the regulations in force.
- When the burner is to remain idle for some time, the fuel supply tap or taps should be closed.


## SPECIAL INSTRUCTIONS FOR USING GAS

Have qualified personnel inspect the installation to ensure that:
a the gas delivery line and train are in compliance with the regulations and provisions in force;
b all gas connections are tight;
c the boiler room ventilation openings are such that they ensure the air supply flow required by the current regulations, and in any case are sufficient for proper combustion.

- Do not use gas pipes to earth electrical equipment.
- Never leave the burner connected when not in use. Always shut the gas valve off.
- In case of prolonged absence of the user, the main gas delivery valve to the burner should be shut off.


## Precautions if you can smell gas

a do not operate electric switches, the telephone, or any other item likely to generate sparks;
b immediately open doors and windows to create an air flow to purge the room;
c close the gas valves;
d contact qualified personnel.

- Do not obstruct the ventilation openings of the room where gas appliances are installed, to avoid dangerous conditions such as the development of toxic or explosive mixtures.


## DIRECTIVES AND STANDARDS

## European directives

-Regulation 2016/426/UE (appliances burning gaseous fuels)
-2014/35/UE (Low Tension Directive)
-2014/30/UE (Electromagnetic compatibility Directive)
-2006/42/EC (Machinery Directive)

## Harmonized standards

-UNI EN 676 (Automatic forced draught burners for gaseous fuels)
-EN 55014-1 (Electromagnetic compatibility- Requirements for house hold appliances, electric tools and similar apparatus)
-EN 60204-1:2006 (Safety of machinery - Electrical equipment of machines.)
-CEI EN 60335-1 (Specification for safety of household and similar electrical appliances);
-CEI EN 60335-2-102 (Household and similar electrical appliances. Safety. Particular requirements for gas, oil and solid-fuel burning appliances having electrical connections).
-UNI EN ISO 12100:2010 (Safety of machinery - General principles for design - Risk assessment and risk reduction);

## Light oil burners

## European directives

-2014/35/UE (Low Tension Directive)
-2014/30/UE (Electromagnetic compatibility Directive)
-2006/42/EC (Machinery Directive)

## Harmonized standards

-UNI EN 267-2011(Automatic forced draught burners for liquid fuels)
-EN 55014-1 (Electromagnetic compatibility- Requirements for house hold appliances, electric tools and similar apparatus)
-EN 60204-1:2006 (Safety of machinery - Electrical equipment of machines.)
-CEI EN 60335-1 (Specification for safety of household and similar electrical appliances);
-CEI EN 60335-2-102 (Household and similar electrical appliances. Safety. Particular requirements for gas, oil and solid-fuel burning appliances having electrical connections).
-UNI EN ISO 12100:2010 (Safety of machinery - General principles for design - Risk assessment and risk reduction);

## Heavy oil burners

## European Directives

-2014/35/UE (Low Tension Directive)
-2014/30/UE (Electromagnetic compatibility Directive)
-2006/42/EC (Machinery Directive)

## Harmonized standards

-UNI EN 267 (Automatic forced draught burners for liquid fuels)
-EN 55014-1 (Electromagnetic compatibility- Requirements for house hold appliances, electric tools and similar apparatus)
-EN 60204-1:2006 (Safety of machinery - Electrical equipment of machines.)
-CEI EN 60335-1 (Specification for safety of household and similar electrical appliances);
-CEI EN 60335-2-102 (Household and similar electrical appliances.
Safety. Particular requirements for gas, oil and solid-fuel burning appliances having electrical connections).
-UNI EN ISO 12100:2010 (Safety of machinery - General principles for design - Risk assessment and risk reduction);

## Gas - Light oil burners

## European Directives

-Regulation 2016/426/UE (appliances burning gaseous fuels) -2014/35/UE (Low Tension Directive)
-2014/30/UE (Electromagnetic compatibility Directive)
-2006/42/EC (Machinery Directive)

## Harmonized standards

-UNI EN 676 (Automatic forced draught burners for gaseous fuels)
-UNI EN 267(Automatic forced draught burners for liquid fuels)
-EN 55014-1 (Electromagnetic compatibility- Requirements for house hold appliances, electric tools and similar apparatus)
-EN 60204-1:2006 (Safety of machinery - Electrical equipment of machines.)
-CEI EN 60335-1 (Specification for safety of household and similar electrical appliances);
-CEI EN 60335-2-102 (Household and similar electrical appliances. Safety. Particular requirements for gas, oil and solid-fuel burning appliances having electrical connections).
-UNI EN ISO 12100:2010 (Safety of machinery - General principles for design - Risk assessment and risk reduction);

## Gas - Heavy oil burners

## European directives:

-Regulation 2016/426/UE (appliances burning gaseous fuels)
-2014/35/UE (Low Tension Directive)
-2014/30/UE (Electromagnetic compatibility Directive)
-2006/42/EC (Machinery Directive)

## Harmonized standards

-UNI EN 676 (Automatic forced draught burners for gaseous fuels)
-EN 55014-1 (Electromagnetic compatibility- Requirements for house hold appliances, electric tools and similar apparatus)
-EN 60204-1:2006 (Safety of machinery - Electrical equipment of machines.)
-CEI EN 60335-1 (Specification for safety of household and similar electrical appliances);
-CEI EN 60335-2-102 (Household and similar electrical appliances. Safety. Particular requirements for gas, oil and solid-fuel burning appliances having electrical connections).
-UNI EN ISO 12100:2010 (Safety of machinery - General principles for design - Risk assessment and risk reduction);

## Industrial burners

## European directives

-Regulation 2016/426/UE (appliances burning gaseous fuels)
-2014/35/UE (Low Tension Directive)
-2014/30/UE (Electromagnetic compatibility Directive)
-2006/42/EC (Machinery Directive)

## Harmonized standards

-EN 55014-1 (Electromagnetic compatibility- Requirements for house hold appliances, electric tools and similar apparatus)
-EN 746-2 (Industrial thermoprocessing equipment - Part 2: Safety requirements for combustion and fuel handling systems)
-UNI EN ISO 12100:2010 (Safety of machinery - General principles for design - Risk assessment and risk reduction);
-EN 60204-1:2006 (Safety of machinery - Electrical equipment of machines.)
-EN 60335-2 (Electrical equipment of non-electric appliances for household and similar purposes. Safety requirements)

## Burner data plate

For the following information, please refer to the data plate:

- burner type and burner model: must be reported in any communication with the supplier
- burner ID (serial number): must be reported in any communication with the supplier
- date of production (year and month)
- information about fuel type and network pressure

| Type | -- |
| :---: | :---: |
| Model | -- |
| Year | -- |
| S.Number | -- |
| Output | -- |
| Oil Flow | -- |
| Fuel | -- |
| Category | -- |
| Gas Pressure | -- |
| Viscosity | -- |
| El.Supply | -- |
| El.Consump. | -- |
| Fan Motor | -- |
| Protection | -- |
| Drwaing $\mathrm{n}^{\circ}$ | -- |
| P.I.N. | -- |

## SYMBOLS USED

Failure to observe the warning may result in irreparable damage to the unit or damage to the environment

## DANGER!

Failure to observe the warning may result in serious injuries or death.

Failure to observe the warning may result in electric shock with lethal consequences

Figures, illustrations and images used in this manual may differ in appearance from the actual product.

## BURNER SAFETY

The burners - and the configurations described below - comply with the regulations in force regarding health, safety and the environment. For more in-depth information, refer to the declarations of conformity that are an integral part of this Manual.

DANGER! Incorrect motor rotation can seriously damage property and injure people.

## Residual risks deriving from misuse and prohibitions

The burner has been built in order to make its operation safe; there are, however, residual risks.

Do not touch any mechanical moving parts with your hands or any other part of your body. Injury hazard
Do not touch any parts containing fuel (i.e. tank and pipes). Scalding hazard
Do not use the burner in situations other than the ones provided for in the data plate.
Do not use fuels other than the ones stated.
Do not use the burner in potentially explosive environments.
Do not remove or by-pass any machine safety devices. Do not remove any protection devices or open the burner or any other component while the burner is running.
Do not disconnect any part of the burner or its components while the burner is running.
Untrained staff must not modify any linkages.


After any maintenance, it is important to restore the protection devices before restarting the machine.
All safety devices must be kept in perfect working order. Personnel authorized to maintain the machine must always be provided with suitable protections.

ATTENTION: while running, the parts of the burner near the generator (coupling flange) are subject to overheating. Where necessary, avoid any contact risks by wearing suitable PPE.

## PART I: INSTALLATION

## TECHNICAL DATA

## SINGLE STAGE BURNERS

| BURNERS TYPE/MODEL |  | P20 M-... 25 | P20 M-... 40 | P30 M-... 40 | P45 M-... 40 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Input | min. kW | 80 | 80 | 150 | 240 |
|  | max. kW | 230 | 280 | 350 | 520 |
|  | min. kcal/h | 68.800 | 68.800 | 129.000 | 206.400 |
|  | max. kcal/h | 197.800 | 240.800 | 301.000 | 447.200 |
| Fuel |  | Natural gas | Natural gas | Natural gas | Natural gas |
| Category |  | $\mathrm{I}_{2 \mathrm{~h}}$ | $\mathrm{I}_{2 \mathrm{~h}}$ | $\mathrm{I}_{2 \mathrm{~h}}$ | $\mathrm{I}_{2 \mathrm{~h}}$ |
| Gas flow rate min.- max. | ( $\mathrm{Stm}^{3} / \mathrm{h}$ ) | 8.5-24.3 | 8.5-29.6 | 15.9-37 | 25.4-55 |
| Gas pressure min.* | mbar | ** | *** | *** | *** |
| Gas pressure max. | mbar | 200 | 200 | 200 | 200 |
| Power supply |  | $230 \mathrm{~V} 3 \sim-50 \mathrm{~Hz}$ | $230 \mathrm{~V} 3 \sim-50 \mathrm{~Hz}$ | $230 \mathrm{~V} 3 \sim-50 \mathrm{~Hz}$ | $230 \mathrm{~V} 3 \sim-50 \mathrm{~Hz}$ |
| Power consumption | W | 650 | 650 | 650 | 900 |
| Electric motor (2800 rpm) | W | 370 | 370 | 370 | 620 |
| Protection |  | IP40 | IP40 | IP40 | IP40 |
| Weight | Kg | 30 | 30 | 30 | 58 |
| Gas train size |  | 1 " | $1 "_{1 / 2}$ | $1{ }_{1 / 2}$ | $1{ }_{1 / 2}$ |
| Gas connections |  | Rp 1 | Rp $1_{1 / 4}$ | Rp $1_{1 / 4}$ | Rp $1_{1 / 2}$ |
| Operation |  | single stage | single stage | single stage | single stage |
| Destination country |  | * | * | * | * |


| BURNERS TYPE/MODEL |  | P45 M-... 50 | P50 M-... 40 | P50 M-... 50 | P50 M-.... 65 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Input | min. kW | 240 | 350 | 350 | 350 |
|  | max. kW | 520 | 523 | 860 | 860 |
|  | $\mathrm{min} . \mathrm{kcal} / \mathrm{h}$ | 206.400 | 301.000 | 301.000 | 301.000 |
|  | max. kcal/h | 447.200 | 449.700 | 739.600 | 739.600 |
| Fuel |  | Natural gas | Natural gas | Natural gas | Natural gas |
| Category |  | $\mathrm{I}_{2 \mathrm{~h}}$ | $\mathrm{I}_{2 \mathrm{~h}}$ | $\mathrm{I}_{2 \mathrm{~h}}$ | $\mathrm{I}_{2}$ |
| Gas flow rate min.- max. | ( $\mathrm{Stm}^{3} / \mathrm{h}$ ) | 25.4-55 | 37-55 | 37-91 | 37-91 |
| Gas pressure min.* | mbar | *** | *** | *** | *** |
| Gas pressure max. | mbar | 200 | 200 | 200 | 500 |
| Power supply |  | $230 \mathrm{~V} 3 \sim-50 \mathrm{~Hz}$ | $\begin{gathered} 230 \mathrm{~V} 3 \sim / 400 \mathrm{~V} \\ 3 \mathrm{~N} \sim 50 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 230 \mathrm{~V} 3 \sim / 400 \mathrm{~V} \\ 3 \mathrm{~N} \sim 50 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 230 \mathrm{~V} 3 \sim / 400 \mathrm{~V} \\ 3 \mathrm{~N} \sim 50 \mathrm{~Hz} \end{gathered}$ |
| Power consumption | W | 900 | 1.600 | 1.600 | 1.600 |
| Electric motor (2800 rpm) | W | 620 | 1.100 | 1.100 | 1.100 |
| Protection |  | IP40 | IP40 | IP40 | IP40 |
| Weight | Kg | 58 | 58 | 58 | 65 |
| Gas train size |  | 2" | $1{ }_{1 / 2}$ | $2 "$ | $2{ }^{1 / 2}$ |
| Gas connections |  | Rp 2 | $\mathrm{Rp} 1_{1 / 2}$ | Rp 2 | DN 65 |
| Operation |  | single stage | single stage | single stage | single stage |
| Destination country |  | * | * | * | * |

Note: all gas flow rates ( $\mathrm{Stm}^{3} / \mathrm{h}$ ) are referred to standard gas conditions: 1013 mbar pressure, $15^{\circ} \mathrm{C}$ temperature.
Flow rates are referred to G20 natural gas (nett calorific value: $34.02 \mathrm{MJ}^{(S t m}{ }^{3}$ ), if G25 is used (n.c.v.: $29.25 \mathrm{MJ} / \mathrm{Stm}^{3}$ ), flow rates must be multiplied by 1.16 factor.

* Minimum pressure to get the maximum rate with any value of back pressure in combustion chamber. The burner operates correctly also with lower pressures but these must guarantee the needed rate.

[^0]| BURNERS TYPE/MODEL |  | P20 M-.... 25 | P20 M-.... 40 | P30 M-.... 40 | P45 M-.... 40 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Input | min. low flame kW | 85 | 85 | 65 | 145 |
|  | min. high flame kW | 120 | 120 | 100 | 220 |
|  | max. kW | 230 | 280 | 350 | 520 |
|  | min. low flame kcal/h | 73.100 | 73.100 | 55.900 | 124.700 |
|  | min . high flame kcal/h | 103.200 | 103.200 | 86.000 | 189.200 |
|  | max. kcal/h | 197.800 | 240.800 | 301.000 | 447.200 |
| Fuel |  | Natural gas | Natural gas | Natural gas | Natural gas |
| Category |  | $\mathrm{I}_{2}$ | $\mathrm{I}_{2 \mathrm{~h}}$ | $\mathrm{I}_{2 \mathrm{~h}}$ | $\mathrm{I}_{2 \mathrm{~h}}$ |
| Gas flow rate min.- max. | (Stm ${ }^{3} / \mathrm{h}$ ) | 9-24.3 | 9-29.6 | 6.9-37 | 15.3-55 |
| Gas pressure min.* | mbar | *** | *** | *** | *** |
| Gas pressure max. | mbar | 200 | 200 | 200 | 200 |
| Power supply |  | $230 \mathrm{~V} 3 \sim 50 \mathrm{~Hz}$ | $230 \mathrm{~V} 3 \sim 50 \mathrm{~Hz}$ | $230 \mathrm{~V} 3 \sim 50 \mathrm{~Hz}$ | $230 \mathrm{~V} 3 \sim 50 \mathrm{~Hz}$ |
| Power consumption | W | 650 | 650 | 650 | 900 |
| Electric motor (2800 rpm) | W | 370 | 370 | 370 | 620 |
| Protection |  | IP40 | IP40 | IP40 | IP40 |
| Weight | Kg | 30 | 30 | 30 | 58 |
| Gas train size |  | $1 "$ | $1{ }_{1 / 2}$ | $1{ }_{1 / 2}$ | $1{ }_{1 / 2}$ |
| Gas connections |  | Rp 1 | Rp $1_{1 / 4}$ | Rp $1_{1 / 4}$ | Rp $1_{1 / 2}$ |
| Operation |  | double stage progressive fully modulating | double stage progressive fully modulating | double stage progressive fully modulating | double stage progressive fully modulating |
| Destination country |  | * | * | * | * |


| BURNERS TYPE/MODEL |  | P45 M-.... 50 | P65 M-.... 50 | P65 M-.... 65 |
| :---: | :---: | :---: | :---: | :---: |
| Input | min. low flame kW | 145 | 270 | 270 |
|  | min. high flame kW | 220 | 480 | 480 |
|  | max. kW | 520 | 970 | 970 |
|  | min. low flame kcal/h | 124.700 | 232.200 | 232.200 |
|  | min. high flame kcal/h | 189.200 | 412.800 | 412.800 |
|  | max. kcal/h | 447.200 | 834.200 | 834.200 |
| Fuel |  | Natural gas | Natural gas | Natural gas |
| Category |  | $\mathrm{I}_{2 \mathrm{~h}}$ | $\mathrm{I}_{2 \mathrm{~h}}$ | $\mathrm{I}_{2 \mathrm{~h}}$ |
| Gas flow rate min.- max. | ( $\mathrm{Stm}^{3} / \mathrm{h}$ ) | 15.3-55 | 28.6-103 | 28.6-103 |
| Gas pressure min.* | mbar | *** | *** | *** |
| Gas pressure max. | mbar | 200 | 200 | 500 |
| Power supply |  | $\begin{gathered} 230 \mathrm{~V} \text { 3~ / 400V } \\ 3 \mathrm{~N} \sim 50 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 230 \mathrm{~V} 3 \sim / 400 \mathrm{~V} \\ 3 \mathrm{~N} \sim 50 \mathrm{~Hz} \end{gathered}$ | $\begin{gathered} 230 \mathrm{~V} 3 \sim / 400 \mathrm{~V} \\ 3 \mathrm{~N} \sim 50 \mathrm{~Hz} \end{gathered}$ |
| Power consumption | W | 900 | 2000 | 2000 |
| Electric motor (2800 rpm) | W | 620 | 1500 | 1500 |
| Protection |  | IP40 | IP40 | IP40 |
| Weight | Kg | 58 | 150 | 155 |
| Gas train size |  | 2" | $2 "$ | $2^{\prime \prime} 12$ |
| Gas connections |  | Rp 2 | Rp 2 | DN 65 |
| Operation |  | double stage progressive fully modulating | double stage progressive fully modulating | double stage progressive fully modulating |
| Destination country |  | * | * | * |

Note: all gas flow rates ( $\mathrm{Stm}^{3} / \mathrm{h}$ ) are referred to standard gas conditions: 1013 mbar pressure, $15^{\circ} \mathrm{C}$ temperature.
Flow rates are referred to G 20 natural gas (nett calorific value: $34.02 \mathrm{MJ} / \mathrm{Stm}^{3}$ ), if G 25 is used (n.c.v.: $29.25 \mathrm{MJ} / \mathrm{Stm}^{3}$ ), flow rates must be multiplied by 1.16 factor.

* Minimum pressure to get the maximum rate with any value of back pressure in combustion chamber. The burner operates correctly also with lower pressures but these must guarantee the needed rate.

[^1]
## BURNER MODEL IDENTIFICATION

Burners are identified by burner type and model. Burner model identification is described as follow.
Model:
M-
B. S .
A.

40
(1)
(1) BURNER TYPE
(2) FUEL
(3) OPERATION
(4) BLAST TUBE LENGHT
(2)
(3)
(4)
(5)
(6)
(8)

M - Natural gas
Available versions TN - Single stage
AB - Double stage
PR - Progressive
MD - Fully modulating
(see overall dimensions)
Available versions S-Standard
L - Long
(5) DESTINATION COUNTRY
(6) SPECIAL VERSION
(7) BURNER EQUIPMENT
(8) GAS TRAIN SIZE

## * - see data plate

A - Standard
Available versions
0-2 Valves
1-2 Valves + leakage control (optional if burner input < 1200 kW )
(See Technical data)

$$
\begin{array}{ll}
25=\text { Rp1 } & 40=\text { Rp1 } 1 / 2 \\
50=\text { Rp2 } & 65=\text { DN65 }
\end{array}
$$

## OVERALL DIMENSIONS IN mm



Fig. 4 a


|  | U | V | W | Z |
| :---: | :---: | :---: | :---: | :---: |
| P20 | 155 | 155 | 220 | 160 |
| P30 | 155 | 155 | 220 | 160 |
| P45 | 215 | 190 | 287 | 200 |
| P50 | 215 | 190 | 287 | 200 |
| P65 | 233 | 233 | 330 | 250 |

Fig. 4b - Boiler plate drilling template - Make 4 M10 threaded holes

|  | A | $\mathbf{B}$ | BL | $\mathbf{C}$ | $\mathbf{C L}$ | $\mathbf{D}$ | $\mathbf{E}$ | $\mathbf{F}$ | $\mathbf{G}$ | $\mathbf{K}$ | $\mathbf{J}$ | $\mathbf{L}$ | $\mathbf{N}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathbf{P 2 0}$ | 555 | 210 | 295 | 765 | 850 | 510 | 200 | 710 | 126 | 290 | 178 | 360 | 370 |
| P30 | 555 | 230 | 330 | 785 | 885 | 510 | 200 | 710 | 148 | 290 | 178 | 360 | 370 |
| P45 | 660 | 255 | 355 | 915 | 1015 | 640 | 250 | 890 | 148 | 350 | 210 | 460 | 450 |
| P50 | 620 | 345 | 435 | 965 | 1055 | 640 | 250 | 890 | 184 | 350 | 210 | 460 | 450 |
| P65 | 825 | 325 | 415 | 1150 | 1240 | 750 | 350 | 1060 | 184 | 375 | 230 | 460 | 450 |

BL - Long blast tube

## PERFORMANCE CURVES

P20 M-.TN... 25


P30 M-.TN.. 40


Fig. 5

P30 M-.AB... 40 - M-.MD... 40 - M-.PR... 40


Fig. 6
kW
kW


P20 M-.TN... 40


P45 M-.TN...xx


Fig. 7

P20 M-.AB... 40 - M-.PR... 40 - M-.MD... 40


P45 M-.AB...xx - M-.PR...xx - M-.MD...xx


Fig. 8

## ------ Minimum high flame

To get the input in kcal/h, multiply value in kW by 860 .



Fig. 10

## ------ Minimum high flame

## PRESSURE - RATE IN COMBUSTION HEAD CURVES

## Curves are referred to a null pressure in combustion head!

The pressure - gas rate curves are referred to the burner in operation with $3 \%$ of $\mathrm{O}_{2}$, with the combustion head at the maximum opening, servocontrol at the maximum opening and gas butterfly valve fully opened. Refer to Fig. 11, showing the correct way to take the gas pressure, considering values of backpressure in combustion chamber.


Fig. 11

## Key

1 Boiler
2 Gas pressure port on butterfly valve
3 Sightglass cooling port
4 Water column pressure gauge


Fig. 12


Fig. 14


Fig. 16


Fig. 13

Fig. 15

## NETWORK PRESSURE - RATE CURVES

## P20 M-.TN.. 25



Fig. 17
P20 M-.TN.. 40


Fig. 19
P20 M-.AB.. 25


Fig. 21
P20 M-.AB.. 40


Fig. 23

P30 M-.TN


Fig. 18
P30 M-.AB


Fig. 20


NATURAL GAS RATE $\operatorname{Stm}^{3} / \mathrm{h}$
Fig. 22

## P45 M-.AB



Fig. 24

P50 M-.TN.. 40


Fig. 25

P50 M-.TN.. 65


Fig. 26

P65 M-...50-65


Fig. 27

## MOUNTINGS AND CONNECTIONS

## Packing

The burners are dispatched in cardboard pakages with dimensions:
P20-P30
$98 \times 55 \times 46$
(W x H x D)
P45-P50
$118 \times 67 \times 57$
(WxHxD)
P65
$127 \times 84 \times 76$
(W $\times \mathrm{H} \times \mathrm{D}$ )

Packing cases of this kind are affected by humidity and are not suitable for stacking. The following are placed in each packing case.
1 burner with detached gas train (but electrically connected to the burner in DN65 models);
1 gasket to be inserted between the burner and the boiler;
1 envelope containing this manual
Unpacking the burner take care of not to damage the electrical connection between the burner and the gas train (only on DN65 models).
To get rid of the burner's packing and in the event of scrapping of the latter, follow the procedures laid down by current laws on disposal of materials.

## Fitting the burner to the boiler

After fitting the burner to the boiler ensure that the space between the blast tube and the refractory lining is sealed with appropriate insulating material (ceramic fibre cord or refractory cement).

## Key

1 Burner
2 Fixing nut
3 Washer
4 Seal
5 Stud bolt
6 Sightglass cleaning tube
7 Blast tube


Fig. 28

## Matching the burner to the boiler

The burners described in this manual have been tested with combustion chambers that comply with EN676 regulation and whose dimensions are described in the diagram in Fig. 29. In case the burner must be coupled with boilers with a combustion chamber smaller in diameter or shorter than those described in the diagram, please contact the supplier, to verify that a correct matching is possible, with respect of the application involved.
To correctly match the burner to the boiler verify the necessary input and the pressure in combustion chamber are included in the burner performance curve; otherwise the choice of the burner must be revised consulting the burner manufacturer.
To choose the blast tube lenght follow the instructions of the boiler manufacturer. In absence of these consider the following:

- Cast-iron boilers, three pass flue boilers (with the first pass in the rear part): the blast tube must protrude no more than 100 mm into the combustion chamber.
The length of the blast tubes does not always allow this requirement to be met, and thus it may be necessary to use a suitablysized spacer to move the burner backwards.
- Pressurised boilers with flame reversal: in this case the blast tube must penetrate at least 50-100 mm into combustion chamber in respect to the tube bundle plate.


## Key

a) Heat input $Q$ in $k W$
b) Lenght of the flame tube in meters
c) Flame tube firing intensity in $\mathrm{MW} / \mathrm{m}^{3}$
d) Combustion chamber diameter (m)

Fig. 29 - Firing intensity, diameter and lenght of the test flame tube as a function of the heat input Q .


## ELECTRICAL CONNECTIONS

- Remove the front panel of the electrical board on the burner.
- Carry out the connections in the power supply electrical board as shown in the following diagrams, verify the fan motor direction (only in three-phase burners) and refit the electrical board front panel.

WARNING: The burners with high-low flame operation are fitted with an electrical bridge between terminals 6 and 7; in the event of connecting the high/low flame thermostat remove this bridge before connecting the thermostat.

IMPORTANT: In connecting electric supply wires to burner teminal block be sure that ground wire should be longer than phase and neutral ones.

For a complete key, see on Page 32, Page 35 and Page 42.
Diagrams for burners WITH printed circuit
Burners type P20-P30 - P50 - P65 single stage, double stage and progressive
Fig. 30a


Burners type P45 single stage, double stage and progressive
Fig. 30b



## Diagrams for burners WITHOUT printed circuit

Type P20-P30 M-.TN...

Fig. 33a

Fig. 33b

Fig. 34a

Fig. 34b


Type P65 M-.AB...


Type P20-P30 M-.MD...

Fig. 35a


Type P45 M-.MD


Type P65 M-.MD


PROBE CONNECTION ON FULLY MODULATING BURNERS


Fig. 36
${ }^{* *}$ ) Probe connection, see Fig. 36

## Rotation of fan motor

After completing the electrical connection of the burner, remember to check the rotation of the fan motor. The motor should rotate in an anti-clockwise direction looking at cooling fan. In the event of incorrect rotation reverse the three-phase supply and check again the rotation of the motor.
NOTE. the burners are supplied for three-phase 400 V supply, and in the case of three-phase 230 V supply it is necessary to modify the electrical connections into the terminal box of the electric motor and replace the overload tripped relay.

RESPECT THE BASIC SAFETY RULES. MAKE SURE OF THE CONNECTION TO THE EARTHING SYSTEM. DO NOT REVERSE THE PHASE AND NEUTRAL CONNECTIONS. FIT A DIFFERENTIAL THERMAL MAGNET SWITCH ADEQUATE FOR CONNECTION TO THE MAINS.

## GAS TRAIN INSTALLATION DIAGRAMS

The figures shown the diagrams with the gas train components wich are included in the delivery and those wich must be fitted by the customer. The diagrams complies with regulations in force.

Fig. 37a
Gas train with valves group MBDLE (2 valves + gas filter + pressure governor + pressure switch) + leakage control VPS504


Fig. 37b
Gas train with safety valve + gas valve with built in pressure governor + leakage control VPS504


Key
1 Burner
2 Butterfly valve
3 Leakage control device (optional if output < 1200 kW )
4 Maximum gas pressure switch (optional)
5 Minimum gas pressure switch
6 Gas filter
7 Bellow joint
8 Manual cock
9 Gas valve with pressure governor
10 Safety gas valve
11 Valves group VGD
12 Valves group MB-DLE
13 Valves group DMV-DLE
14 Pressure governor with filter
15 Leakage control pressure switch
16 Gas pressure governor

MANUFACTURER INSTALLER

Fig. 37d
Gas train with valves group VGD with built-in gas pressure governor + leakage control LDU11


Fig. 37e
Gas train with valves group DMVDLE + leakage control VPS504


Fig. 37f
Gas train with valves group DMVDLE + leakage control LDU11


## Key

1 Burner
2 Butterfly valve
3 Leakage control device (optional if output < 1200 kW )
4 Maximum gas pressure switch (optional)
5 Minimum gas pressure switch
6 Gas filter
7 Bellow joint
8 Manual cock
9 Gas valve with pressure governor
10 Safety gas valve
11 Valves group VGD
12 Valves group MB-DLE
13 Valves group DMV-DLE
14 Pressure governor with filter
15 Leakage control pressure switch
16 Gas pressure governor

## IN A SUCH CASE THE DEVICE WARRANTY IS IMMEDIATELY INVALIDATE!

Fig. 38 - Multibloc MB-DLE - VPS504
The multibloc unit is a compact unit consisting of two valves, gas pressure switch, pressure stabilizer and gas filter. It can be paired jointly to the Dungs VPS504 sealing controls.
The valve is adjusted by means of the RP regulator after slackening the locking screw VB by a number of turns. By unscrewing the regulator RP the valve opens, screwing the valve closes.
To set the fast opening remove cover T, reverse it upside down and use it as a tool to rotate screw VR. Clockwise rotation reduces start flow rate, anticlockwise rotation increases it.
Do not use a screwdriver on the screw VR!
The pressure stabilizer is adjusted by operating the screw VS located under the cover C . By screwing down the pressure is increased and by unscrewing it is reduced.
Note: the screw VSB must be removed only in case of replacemente of the coil.

## Leakage control device VPS504 (Optional)

The VPS504 check the operation of the seal of the gas shut off valves costituting the MB-DLE. This check, carried out as soon as the boiler thermostat gives a start signal to the burner, creates, by means of the diaphragm pump inside it, a pressure in the test space of 20 mbar higher than the supply pressure. When wishing to monitor the test, install a pressure gauge ranged to that of the pressure supply point PA. If the test cycle is satisfactory, after a few seconds the consent light LC (yellow) comes on. In the opposite case the lockout light LB (red) comes on.
To restart it is necessary to reset the appliance by pressing the illuminated pushbutton LB.

## Gas valve Dungs MV-DLE

- To adjust the gas flow rate loosen the screw VB and rotate the regulator RP as necessary. Unscrew to close the valve, screw to open.
- Tighten the screw VB.
- To set the fast opening remove cover T, reverse it upside down and use it as a tool to rotate the screw VR. Clockwise rotation reduces the ignition flow rate, anticlockwise rotation increase it.
Note: the screw VSB must be removed only in case of replacemente of the coil.
Do not use a screwdriver on the screw VR!


Fig. 38


Fig. 39

## Gas valve Dungs MVD

- To adjust the gas flow rate unscrew the plug T, slacken the locking nut and apply a screwdriver to the adjusting screw VR. Turn clockwise to close the valve or counterclockwise to open.
- When this operation has been completed lock the nut and screw down the plug T .
- To replace the coil remove the plug T, withdraw the coil B and after replacing the coil refit the plug T .


Fig. 40

## Landis gas valves

Version with SKP20 (with incorporated pressure governor).

- To increase or decrease gas pressure, and therefore gas flow rate, remove the cap $T$ and use a screwdriver to adjust the regulator screw VR. Turn clockwise to increase the flow, anti-clockwise to reduce it.
- Connect up the gas tubing to the gas pressure nipple (TP in figure).
Leave the blowhole free (SA in figure).
Should the spring fitted not permit satisfactory regulation, ask one of our service centres for a suitable replacement.
(For further informations see also the appendix)


## WARNING:

## removing the four screws BS drives the device



Fig. 41

## Landis gas valves VGD

Version with SKP20 (with incorporated pressure governor).

- To increase or decrease gas pressure, and therefore gas flow rate, remove the cap $T$ and use a screwdriver to adjust the regulator screw VR. Turn clockwise to increase the flow, anti-clockwise to reduce it.
- Connect up the gas tubing to the gas pressure nipple (TP in figure).

Leave the blowhole free (SA in figure).
Should the spring fitted not permit satisfactory regulation, ask one of our service centres for a suitable replacement. (For further informations see also the appendix)
§ WARNING: removing the four screws BS causes the device to be unserviceable!


Fig. 42a


Fig. 42 b

## Dungs Valves

SV (without regulation)
SV-D Quick opening valve with regulation
SV-DLE Slow opening valve with regulation

## SV-D...

- To adjust the valve slacken the screw VR and turn the knob G.
- Rotate clockwise to open the valve
- Rotate counterclockwise to close the valve
- Tight the screw VR at the end of setting


Fig. 43a


Fig. 43b


Fig. 43c

## SV-DLE...

- To adjust the valve slacken the screw VR and turn the knob G.
- Rotate clockwise to open the valve
- Rotate counterclockwise to close the valve
- Tight the screw VR at the end of setting


## Rapid stroke adjustment

- Unscrew the cap E from the hydraulic brake unit
Turn the adjustment cap E upside down and use it as a tool, tucking it in the regulation spindle
- Turn clockwise to increase the rapid stroke





## ValvesDungs DMV-DLE

Setting is carried out working on the screw V1. Turning clockwise the valve closes, turning counterclockwise the valve opens.

## Fast stroke setting

- Unscrew the setting cap E.
- Turn the cap upside down and use it as a tool tucking it in the regulation spindle.
Rotate counterclockwise to increase rapid stroke.
Warning: the knob F doesn't make any setting!


Fig. 45

## Pressure regulator Dungs FRS

## Adjustment

- Unscrew the protection cap A
- Rotate the regulation screw B clockwise to increase the pressure or counterclockwise to decrease it
- Check the pressure at the end of settings
- Replace the protection cap A


Fig. 46a


Fig. 46b

## GAS FILTER

The gas filters are components that remove the dust particles carried by the gas, and prevent the elements at risk (e.g.: burners, counters and regulators) from becoming rapidly blocked. The filter is normally installed upstream from all the control and on-off devices.

## GAS FILTER MAINTENANCE

## Flanged fittings - Fig. 47a

After having ensured that there is no pressurised gas inside the filter, remove the cover (1) by unscrewing the fastening screws (8). Remove the filter cartridge (3), wash it in soap and water, blow it with compressed air (or replace if necessary) and put it back in its initial position, checking that it fits between the positioning guides (6) on the bottom (5) and that it does not stop the cover (1) from being put back in place. Finally, put the cover (1) back in place, making sure that the O-Ring (2) is in its seat and that the filter cartridge (3) fits neatly between the guides (6) on the cover (1), the same as those on the bottom (5).

## Threaded fittings - Fig. 47b and Fig. 47c

After having ensured that there is no pressurised gas inside the filter, remove the cover (5) by unscrewing the fastening screws (1). Remove the filter cartridge (3), wash it in soap and water, blow it with compressed air (or replace if necessary) and put it back in its initial position, checking that it fits between the positioning guides (7) and that it does not stop the cover (5) from being put back in place. Finally, put the cover (5) back in place, making sure that the O-Ring (4, Fig. 47b) is in its seat.


Fig. 47a


Fig. 47b


Fig. 47c - Top view, without cover

Key (Fig. 47a)
1 Cover
2 O-Ring
3 Filter cartridge
4 Screws M5 x 12
5 Bottom
6 Positioning guides
7 Body
8 Screws M5 x 14

## Key (Fig. 47b - Fig. 47c)

Fastening screws
2 Body
3 Filter cartridge
4 O-Ring
5 Cover
6 Pressure port
7 Positioning guides

## ADJUSTMENT OF GAS AND AIR FLOW RATE

WARNING: During commissioning operations, do not let the burner operate with insufficient air flow (danger of formation of carbon monoxide); if this should happen, shut down the burner, increase the opening of the air damper and start up the burner again to ensure the purging of the carbon monoxide from the combustion chamber.

## Startup input

The start-up heat input shall not exceed 120 kW (single stage burners) or $1 / 3$ of nominal input (2 stages or fully modulating burners). In order to comply with these requirements, single stage burners are dispatched from the factory with appropriate setting of the hydraulic brake of gas valve.
On 2 stages or modulating burners, take care to set the minimum gas flow rate lower than $1 / 3$ of nominal input.
Important. Set the air flow rate referring to the following values: minimum $\mathrm{CO}_{2}$ value for G25: 9.58\% (8.85\% if the burner is set at its minimum output) with single stage models or during low fire operation on hi-lo flame or fully modulating burners.


Fig. 48

## Burners with single stage operation

- Slacken the screw VBS shown in Fig. 48 by means of a screwdriver; set the desired air flow rate by adjusting directly the damper.
- On final adjustment tight the screw VBS.


## Burners with fully modulating or progressive operation

During the test in the factory, the gas throttle valve, air damper in low flame operation and the servocontrol are set to average values.
To recalibrate the burner on site, proceed as follows.
1 Switch on the burner and drive it to high-flame (servocontrol position $=90^{\circ}$ ).
Adjust the gas flow rate to the required figure by adjusting the pressure governor or the valve regulator. To adjust the air flow rate (Fig. 53) slacken the screw RA and rotate the screw VRA (clockwise rotation increases air flow, anticlockwise rotation decreases it) until the desired flow rate is obtained.
N.B.: at the end of settings remember to tight the screw RA.

2 Drive the burner to low flame. If it should be necessary to adjust burner capacity at low flame move the servocontrol cam accordingly (Page 25).
3 Adjust the gas flow rate in the low-flame position (same position as the ingition) by means of the adjustable screws V (Fig. 53), to change the opening angle of the throttle valve (Fig. 52); rotate clockwise to increase the flow rate or anticlockwise to decrease it.
4 Turn off the burner and turn it on again. If the gas flow rate needs further regulations, repeat operations at step 3.

## Fully modulating burners

To set the gas flow rate in low flame and in the intermediate points, proceed as follows.
5 Push the button EXIT on the modulator device (Fig. 57) for a time of 5 seconds; when the led with the hand simbol lights, use the arrow keys to drive the servocontrol to the maximum opening position and, stopping the movement at each screw V , use the one corresponding to the bearing to set the gas flow rate.
6 Push the EXIT button to exit the manual operation mode.


Fig. 52


Fig. 53

## Double-stage burners

9 drive the burner to the low flame stage by means of the TAB thermostat;
10 In order to change the gas flow rate slacken the nuts DB (Fig. 24) and adjust the opening angle of the gas butterfly valve by rotating the rod TG (clockwise rotation increases gas flow, anticlockwise rotation decreases it). The slot on the butterfly valve shaft shows the opening degree of the valve regardingthe horizontal axis (Fig. 24).
NOTE: At the end of settings, make sure the locking screws RA and DB are fully tightened.


Fig. 24

11 Now adjust the pressure switches (see page 27).
12 If it is necessary to change the burner output in the low flame stage, move the low flame cam: the low flame position matches the ignition position. As far as burners fitted with Dungs MBC gas valves, the low flame cam does not match the ignition cam position, that is why it must be set at about $30^{\circ}$ more than the ignition cam.
13 Turn the burner off and then start it up again. If the adjustment is not correct, repeat the previous steps.

Berger STA6 B 3.41 (high-low flame burners)


Siemens SQN72.2A4Axx (high-low flame burners)


| For DUNGS MB-DLE / Siemens VGD gas valves | Actuator camsBerger <br> STA | Siemens SQN72 |
| :--- | :---: | :---: |
| High flame position (set to $90^{\circ}$ ) | ST2 | I (red) |
| Low flame and ignition position | ST1 | III (orange) |
| Stand-by position (set to $0^{\circ}$ ) | ST0 | II (blue) |
| Not used | MV | IV (black) |


| For DUNGS MBCgas valves | Actuator camsBerger <br> STA | Siemens SQN72 |
| :--- | :---: | :---: |
| High flame position (set to $90^{\circ}$ ) | ST2 | I (red) |
| Stand-by position (set to $0^{\circ}$ ) | ST0 | III (orange) |
| Ignition | ST1 | II (blue) |
| Low flame position | MV | IV (black) |

Berger STA12: a key is provided to move the cams.
Siemens SQN72: a key is provided to move cams I and IV, the other cams can be moved by means of screws.
On the BERGER STA12B3.41 actuator, the manual air damper control is not provided. On the Siemens actuator the AUTO/MAN mode is provided (see picture).

## Progressive burners

Once the procedure till step 8 described on paragraph "Adjusting procedure" on page 22, is accomplished, go on as follows:
9 set the low flame cam matching the high flame cam;
10 set the TAB thermostat to the minimum in order that the actuator moves progressively towards the low flame position;
The manual air damper control is not provided on these actuators. The adjustments must be carried out acting manually on the cams.

Berger STA12B3.41 (progressive and fully modulating burners)


Siemens SQN72.4A4Axx (progressive and fully modulating burners)

IBerger STA12: a key is provided to move the cams.
Siemens SQN72: a key is provided to move cams I and IV, the other cams can be moved by means of screws.
On the BERGER STA12B3.41 actuator, the manual air damper control is not provided. On the Siemens actuator the AUTO/MAN mode is provided (see picture).

11 move the low flame cam to the minimum to move the actuator towards the low flame until the two bearings find the adjusting screw that refers to the lower position: screw $\mathbf{V}$ to increase the rate, unscrew to decrease.
12 Move again the low flame cam towards the minimum to meet the next screw on the adjusting cam and repeat the previous step; go on this way as to reach the desired low flame point.
13 Now adjust the pressure switches (see page 27).


14 If it is necessary to change the burner output in the low flame stage, move the low flame cam: the low flame position matches the ignition position. As far as burners fitted with Dungs MBC gas valves, the low flame cam does not match the ignition cam position, that is why it must be set at about $30^{\circ}$ more than the ignition cam.
15 Turn the burner off and then start it up again. If the adjustment is not correct, repeat the previous steps.

## Calibration of air pressure switch (single stage burners)

Calibration is carried out as follows:

- Remove the transparent plastic cap.
- After air and gas setting have been completed, start the burner.
- The pre-purge phase starts; wait 10 sec . then slowly turn the adjusting ring nut VR in the clockwise direction until the burner lockout, read the value on the pressure switch scale and reduce it by 0.5 mbar.
- Repeat the start up cycle of the burner and check it runs properly.
- Refit the transparent plastic cover on the pressure switch.


## Calibration of air pressure switch (double stage and fully modulating burners)

Calibration is carried out as follows:

- Remove the transparent plastic cap.
- After air and gas setting have been completed, start the burner.
- The pre-purge phase starts; wait 10 sec . then slowly turn the adjusting ring nut VR in the clockwise direction until the burner lockout, read the value on the pressure switch scale and reduce it by $15 \%$.


Fig. 55

- Repeat the ignition cycle of the burner and check it runs properly.
- Refit the transparent plastic cover on the pressure switch.


## Calibration of minimum gas pressure switch

Calibration is carried out as follows:

- Remove the transparent plastic cap.
- With the burner in operation test the pressure on the pressure port at the input of the gas filter; slowly close the manual shut-off valve (see gas train installation diagram) until the detected pressure is reduced by $50 \%$.
- Verify CO emissions of the burner; if the measured value is less than 80 ppm screw down the adjusting ring nut until the burner lockout. If CO emissions are greater than 80 ppm open the shut off valve until the CO value is reduced to 80 ppm , then screw down the adjusting ring nut until the burner lockout.
- Fully open the manual shut-off valve $\triangle$ WARNING: carry out this operation ONLY with the burner turned off!
- Refit the transparent plastic cover on the pressure switch.


## Calibrating the maximum gas pressure switch

The high gas pressure switch is mounted on the burner near to the throttle valve and is connected to it by a copper tube. Calibration is carried out as follows:

- Remove the transparent plastic cap.
- Drive the burner to maximum output.
- Rotate slowly the adjustment ring nut VR clockwise, until the burner stops.
- Rotate the adjustment ring nut slightly back (increase the value indicated on the scale nut after rotation, by $30 \%$ ).
- Turn on the burner and verify it operates correctly; if it shuts-off, turn back the setting knob again.
- Refit the transparent plastic cover on the pressure switch.


## Adjusting the combustion head

The burner is adjusted in the factory with the combustion head in the "MAX" position, corresponding to the maximum power. To operate the burner at a lowest strenght, progressively shift back the combustion head, toward the "MIN" position, rotating the screw VRT clockwise.


Fig. 56

## PART II: OPERATION MANUAL

## LIMITATIONS OF USE

THE BURNER IS AN APPLIANCE DESIGNED AND CONSTRUCTED TO OPERATE ONLY AFTER BEING CORRECTLY CONNECTED TO A HEAT GENERATOR (E.G. BOILER, HOT AIR GENERATOR, FURNACE, ETC.), ANY OTHER USE IS TO BE CONSIDERED IMPROPER AND THEREFORE DANGEROUS.

THE USER MUST GUARANTEE THE CORRECT FITTING OF THE APPLIANCE, ENTRUSTING THE INSTALLATION OF IT TO QUALIFIED PERSONNEL AND HAVING THE FIRST COMMISSIONING OF IT CARRIED OUT BY A SERVICE CENTRE AUTHORISED BY THE COMPANY MANUFACTURING THE BURNER.

A FUNDAMENTAL FACTOR IN THIS RESPECT IS THE ELECTRICAL CONNECTION TO THE GENERATOR'S CONTROL AND SAFETY UNITS (CONTROL THERMOSTAT, SAFETY, ETC.) WHICH GUARANTEES CORRECT AND SAFE FUNCTIONING OF THE BURNER.

THEREFORE, ANY OPERATION OF THE APPLIANCE MUST BE PREVENTED WHICH DEPARTS FROM THE INSTALLATION OPERATIONS OR WHICH HAPPENS AFTER TOTAL OR PARTIAL TAMPERING WITH THESE (E.G. DISCONNECTION, EVEN PARTIAL, OF THE ELECTRICAL LEADS, OPENING THE GENERATOR DOOR, DISMANTLING OF PART OF THE BURNER).

NEVER OPEN OR DISMANTLE ANY COMPONENT OF THE MACHINE.

OPERATE ONLY THE MAIN SWITCH, WHICH THROUGH ITS EASY ACCESSIBILITY AND RAPIDITY OF OPERATION ALSO FUNCTIONS AS AN EMERGENCY SWITCH, AND ON THE RESET BUTTON.

IN THE EVENT OF REPEATED LOCKOUTS, DO NOT PERSIST WITH THE RESET BUTTON AND CONTACT QUALIFIED PERSONNEL WHO WILL PROCEED TO ELIMINATE THE MALFUNCTION.

WARNING: DURING NORMAL OPERATION THE PARTS OF THE BURNER NEAREST TO THE GENERATOR (COUPLING FLANGE) CAN BECOME VERY HOT, AVOID TOUCHING THEM SO AS NOT TO GET BURNT

## OPERATION

- Bring to the ON position the mains switch A on the burner electrical board front panel.
- Check the flame control device is not in the lockout position (light B on), if necessary reset it by means of the pushbutton C (reset);
- Verify that the control thermostats or pressure switches give the consent to the burner to operate.
- Check the gas supply pressure is sufficient (light D on).

Only burners equipped with leakage control device: the check cycle of the leakage control device starts; the completion of this check is signalled by the light of the lamp on the device. When the valves check is finished, the start up cycle of the burner begins. In the case of a leak in a valve, the leakage control device locks and the lamp E lights.
To reset the device operate on the device pushbutton.

- When the startup cycle begins, the servocontrol drives the air damper to the maximum opening position, the fan motor starts and the pre-purgue phase begins.
During the pre-purgue phase, the complete opening of the air damper is signalled by the lamp F on the frontal panel of the electrical board.
- At the end of the pre-purgue phase, the air damper goes to the ignition position, the ignition transformer comes on (signalled by the lamp H) and 3 seconds later the solenoid valves EV1 and EV2 are energized (lights L and I on the front panel).
- 3 seconds after the opening of the valves, the ignition transformer comes off and the lamp H turns off; subsequently:

Single stage burners: the burner is on at the maximum power; the lights $F$ and $G$ are on;
High-low flame burners: the burner is on in low flame (light $G$ is on); 8 seconds later the high flame operation begins and the burner switches automatically to high flame (light $F$ is on) or remains in low flame operation, depending on the plant needs.
Fully modulating burners: after the posted time the modulating operation begins and the burner is driven by the modulator (P), depending on the needs of the plant; the light $F$ is on until the modulator drives the burner to a rise of power.


Fig. 57 - Electrical board front panel

## Key

A main switch on-off
B lockout indicator light
C reset pushbutton for flame control device
D gas pressure switch consent indicator light
E leakage control device lockout indicator light (only on burners with leakage control device)
F high flame operation indicator light (or air damper open during pre-purgue phase)
G low flame operation indicator light
H ignition transformer operation indicator light
I valve in operation indicator light for EV2
L valve in operation indicator light for EV1
M indicator light for fan motor overload tripped (only three-phase burners); to reset the overload tripped, open the electrical board.
P modulator (fitted only on fully modulating burners)
Q operation manual selector: 0 ) stop -1) high flame - 2) low flame - 3) automatic

## PART III: MAINTENANCE MANUAL

At least once a year carry out the maintenance operations listed below. In the case of seasonal servicing, it is recommended to carry out the maintenance at the end of each heating season; in the case of continuous operation the maintenance is carried out every 6 months.

## WARNING: All operations on the burner must be carried out with the mains disconnected!

PERIODICAL OPERATIONS

- Cleaning and examining the gas filter cartridge, if necessary replace it; (see on Page 22);
- Removal, examination and cleaning of the combustion head (see Fig. 58 - Fig. 59);
- Check of ignition electrode, cleaning, adjustment and, if necessary, replacement (see Fig. 60 - Fig. 61);
- Check of detection electrode, cleaning, adjustment and, if necessary, replacement (see Fig. 60 - Fig. 61); if in doubt check the detection circuit as shown in Fig. 62 - Fig. 63, with the burner in operation;
- Cleaning and greasing sliding and rotating parts.

NOTE: The check on the ignition and detection electrodes is carried out after removing the combustion head.

## Removal of the combustion head

Fig. 58 - Burners P20 - P30 - P45 - P50

- Remove the lid C.
- Unscrew the 2 screws $S$ which hold in position the washer, unscrew then the screw VRT, to free the threaded rod AR.
- Unscrew the screws V which lock the gas manifold $G$ and extract the complete unit as shown in the figure.
Note: for subsequent assembly carry out the above described operations in the reverse order, having care to keep the OR ring in the correct position.


Fig. 58


Fig. 59

Fig. 60 - Electrodes position setting P20-P30-P45


Fig. 61 - Electrodes position setting P50-P65


## Check of ionisation current

To measure the detection signals refer to the diagrams in Fig. 62 - Fig. 63. If the signal is less than the value shown, check the position of the detection electrode, the electrical contacts and if necessary replace the detection electrode.

Fig. 62
TERMINAL BLOCK MA


Minimum detection signal
$3 \mu \mathrm{~A}$

SIEMENS LME2x
If the power supply to the burner is 230 V three-phase or 230 V phase-phase (without a neutral), with the Landis LGB2... o LMG2... flame control device, between the terminal 2 on the board and the earth terminal, an RC Landis RC466890660 filter must be inserted

## Key

C - Capacitor (22nF/250V)
LGB - LMG - Landis flame control device
R - Resistor (1Mohm)
RC466890660-RC Landis filter


Fig. 64

## TROUBLESHOOTING

| CAUSE / FAULT |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| MAINS SWITCH OPEN |  |  |  |  |  |  |  |  |  |  |
| ABSENCE OF GAS |  |  |  |  |  |  |  |  |  |  |
| MINIMUM GAS PRESSURE SWITCH FAULT OR BAD SETTING |  |  |  |  | $0$ |  |  |  |  |  |
| BOILER THERMOSTATS OPEN |  |  |  |  |  |  |  |  |  |  |
| OVERLOAD TRIPPED INTERVENTION |  |  |  |  |  |  |  |  |  |  |
| FUSES INTERVENTION |  |  |  |  |  |  |  |  |  |  |
| AIR PRESSURE SWITCH FAULT OR BAD SETTING |  |  |  |  |  |  |  |  |  |  |
| DEFECTIVE FLAME CONTROL DEVICE |  |  |  |  |  |  |  |  |  |  |
| DEFECTIVE AIR DAMPER SERVOCONTROL |  |  |  |  |  |  |  |  |  |  |
| DEFECTIVE IGNITION TRANSFORMER |  |  |  |  |  |  |  |  |  |  |
| IGNITION ELECTRODE WRONG POSITION |  |  |  |  |  |  |  |  |  |  |
| BUTTERFLY VALVE BAD SETTING |  |  |  |  |  |  |  |  |  |  |
| DEFECTIVE GAS GOVERNOR |  |  |  |  |  |  |  |  |  |  |
| DEFECTIVE HI-LO FLAME THERMOSTAT |  |  |  |  |  |  |  |  |  |  |
| SERVOCONTROL CAM BAD SETTING |  |  |  |  |  |  |  |  |  |  |
| DETECTION ELECTRODE BAD POSITION OR DEFECTIVE DETECTION CIRCUIT |  |  |  |  |  |  |  |  |  |  |
| REVERSED PHASE AND NEUTRAL CONNECTION |  |  |  |  |  |  |  |  |  |  |
| PHASE-PHASE SUPPLY OR PRESENCE OF VOLTAGE ON NEUTRAL* |  |  |  |  |  |  |  |  |  |  |

[^2]



| ｜l｜l｜l｜ |
| :--- |
| F |
| Function |
| AIR DAMPER ACTUATOR（ALTERNATIVE） |
| AIR DAMPER ACTUATOR（ALTERNATIVE） |
| CAPACITOR |
| PILOT FLAME THERMOSTAT OR PRESSURE SWITCHES |
| FLAME DETECTION ELECTRODE |
| GAS ELECTRO－VALVE UPSTREAM（OR VALVES GROUP） |
| GAS ELECTRO－VALVE DOWNSTREAM（OR VALVES GROUP） |
| PILOT GAS ELECTRO－VALVE UPSTREAM（OR VALVES GROUP） |
| PILOT GAS ELECTRO－VALVE DOWNSTREAM（OR VALVES GROUP） |
| AUXILIARY LINE FUSE |
| FUSE |
| MAIN DISCONNECTOR |
| AUXILIARY LINE SWITCH |
| AUXIIIARY RELAY |
| AUXILIARY RELAY |
| DELAYED RELAY |
| BURNER IN HIGH FLAME INDICATOR LIGHT |
| INDICATOR LIGHT FOR BURNER LOCK－OUT |
| BURNER IN LOW FLAME INDICATOR LIGHT |
| INDICATOR LIGHT FOR OPENING OF ELECTRO－VALVE［EV1］ |
| INDICATOR LIGHT FOR OPENING OFELECTRO－VALVE［EV2］ |
| INDICATOR LIGHT FOR PRESENCE OF GAS IN THE NETWORK |
| INDICATOR LIGHT FOR LEAKAGE OF VALVES |
| IGNITION TRANSFORMER INDICATOR LIGHT |
| FAN MOTOR |
| COMBUSTION AIR PRESSURE SWITCH |
| MAXIMUM PRESSURE GAS SWITCH（OPTIONAL） |
| MINIMUM GAS PRESSURE SWITCH |
| LOCK－OUT RESET BUTTON |
| RESISTANCE |
| RC CIRCUIT |
| FLAME MONITOR DEVICE |
| AIR DAMPER ACTUATOR（ALTERNATIVE） |
| AIR DAMPER ACTUATOR |
| SERIES OF THERMOSTATS OR PRESSURE SWITCHES |
| IGNITION TRANSFORMER |
| HIGH－LOW THERMOSTAT／PRESSURE SWITCHES |
| GAS LEAKAGE MONITOR DEVICE（OPTIONAL） |
| EARTH TERMINAL |


| $\left\lvert\, \begin{aligned} & \mathrm{O} \\ & \hline \mathrm{~S} \\ & \mathrm{O} \\ & \hline \end{aligned}\right.$ | $\checkmark$ |  |
| :---: | :---: | :---: |
| $\left\lvert\, \begin{gathered} \dot{u} \\ \underset{\alpha}{\underline{\alpha}} \end{gathered}\right.$ | $m$ | $\begin{aligned} & \text { 炭 } \\ & 0 \\ & 山 \\ & 山 \end{aligned}$ |
| £OOZ/てL/GO Dłoo | $\mathfrak{O}$ |  |



| POS. | DESCRIPTION | $\xrightarrow[M-. X X . S . * . A . A .0 .25]{\text { P20 }}$ | M-.XX.L..*.A.0.25 | $\text { M-.XX.S. }{ }^{\text {P20 }} \text {.A. } 0.40$ | M-.XX.L.*.A.A.0.40 | $\text { M-.XX.S. }{ }^{\text {P30 }} \text {.A. } 0.40$ | $M_{M-. X X . L . *}^{\text {P30 }} \text {.A.0.40 }$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | SOCKET FOR FLAME CONTROL DEVICE | 2030415 | 2030415 | 2030415 | 2030415 | 2030415 | 2030415 |
| 2 | FLAME CONTROL DEVICE LGB21 (SINGLE STAGE) | 2020443 | 2020443 | 2020443 | 2020443 | 2020443 | 2020443 |
| 2 | FLAME CONTROL DEVICE LGB22 (HI-LO FLAME) | 2020430 | 2020430 | 2020430 | 2020430 | 2020430 | 2020430 |
| 2 | FLAME CONTROL DEVICE LMG21 (SINGLE STAGE) | 2020449 | 2020449 | 2020449 | 2020449 | 2020449 | 2020449 |
| 2 | FLAME CONTROL DEVICE LMG22 (HI-LO FLAME) | 2020450 | 2020450 | 2020450 | 2020450 | 2020450 | 2020450 |
| 3 | TANSFORMER | 2170128 | 2170128 | 2170128 | 2170128 | 2170128 | 2170128 |
| 5 | MANIFOLD | 2740002 | 2740002 | 2740002 | 2740002 | 2740002 | 2740002 |
| 6 | DETECTION CABLE | 6050205 | 6050205 | 6050205 | 6050205 | 6050205 | 6050205 |
| 7 | DETECTION ELECTRODE | 2080106 | 2080106 | 2080106 | 2080106 | 2080102 | 2080102 |
| 8 | COMPLETE BLAST TUBE | 3090096 | 3090086 | 3090096 | 3090086 | 3090019 | 3091005 |
| 9 | BLAST TUBE EXTENSION | --- | --- | --- | --- | --- | 2200046 |
| 10 | COMBUSTION HEAD | 3060073 | 3060072 | 3060073 | 3060072 | 3060005 | 3060005 |
| 11 | IGNITION ELECTRODE | 2080209 | 2080209 | 2080209 | 2080209 | 2080202 | 2080202 |
| 12 | IGNITION CABLE | 6050108 | 6050108 | 6050108 | 6050108 | 6050108 | 6050108 |
| 13 | GASKET | 2110004 | 2110004 | 2110004 | 2110004 | 2110004 | 2110004 |
| 14 | "O" RING | 2250001 | 2250001 | 2250001 | 2250001 | 2250001 | 2250001 |
| 15 | THROTTLE VALVE (HI-LO FLAME) | 2460221 | 2460221 | 2460221 | 2460221 | 2460221 | 2460221 |
| 15A | THROTTLE VALVE (SINGLE STAGE) | 2460201 | 2460201 | 2460201 | 2460201 | 2460201 | 2460201 |
| 17 | AIR DAMPER | 2140005 | 2140005 | 2140005 | 2140005 | 2140005 | 2140005 |
| 18 | SERVOC. SUPPORT BRACKET (HI-LO FLAME) | 3050009 | 3050009 | 3050009 | 3050009 | 3050009 | 3050009 |
| 19 | SERVOCONTROL (BERGER, VERS. HI-LO FLAME) | 2480057 | 2480057 | 2480057 | 2480057 | 2480057 | 2480057 |
| 20 | INLET CONE | 2040016 | 2040016 | 2040016 | 2040016 | 2040016 | 2040016 |
| 21 | FAN | 2150006 | 2150006 | 2150006 | 2150006 | 2150006 | 2150006 |
| 22 | AIR PRESSURE SWITCH | 2140065 | 2140065 | 2140065 | 2140065 | 2140065 | 2140065 |
| 24 | HEAD ADJUSTING SCREW | 2320501 | 2320501 | 2320501 | 2320501 | 2320501 | 2320501 |
| 25 | MOTOR | 2180704 | 2180704 | 2180704 | 2180704 | 2180704 | 2180704 |
| 26 | LEAKAGE CONTROL (OPTIONAL) | 2191604 | 2191604 | 2191604 | 2191604 | 2191604 | 2191604 |
| 35 | MINIMUM GAS PRESSURE SWITCH | 2160052 | 2160052 | 2160052 | 2160052 | 2160052 | 2160052 |
| 37 | MULTIBLOC VALVES GROUP | 2190341 | 2190341 | 2190342 | 2190342 | 2190342 | 2190342 |
|  | PRINTED CIRCUIT | 6100535 | 6100535 | 6100535 | 6100535 | 6100535 | 6100535 |
| 38 | MULTIBLOC COIL | 2580017 | 2580017 | 2580017 | 2580017 | 2580017 | 2580017 |





| POS. | DESCRIPTION | $\begin{gathered} \text { P20 } \\ \text { M-.M.S. }{ }^{\text {.A.A.0.25 }} \end{gathered}$ | $\begin{gathered} \mathrm{P}^{20} \\ \text { M-.M.L...A.0.25 } \end{gathered}$ | $\begin{gathered} \text { P20 } \\ \text { M-.MD.S. }{ }^{*} \text {.A. } 0.40 \end{gathered}$ | $\begin{gathered} \text { P20 } \\ \text { M-.MD.L...A.0.40 } \end{gathered}$ | $\begin{gathered} \text { P30 } \\ \text { M-MD.S. }{ }^{\text {M.A.O.40 }} \end{gathered}$ | $\begin{gathered} \text { P30 } \\ \text { M-.MD.L. }{ }^{*} \text {.A.0.40 } \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | SOCKET FOR FLAME CONTROL DEVICE | 203.04.15 | 203.04.15 | 203.04.15 | 203.04.15 | 203.04.15 | 203.04.15 |
| 2 | FLAME CONTROL DEVICE LANDIS LGB22 | 202.04.30 | 202.04.30 | 202.04.30 | 202.04.30 | 202.04 .30 | 202.04.30 |
| 2 | FLAME CONTROL DEVICE LANDIS LMG22 | 202.04.50 | 202.04 .50 | 202.04 .50 | 202.04.50 | 202.04.50 | 202.04.50 |
| 3 | TRANSFORMER | 217.01.02 | 217.01.02 | 217.01 .02 | 217.01.02 | 217.01.02 | 217.01 .02 |
| 5 | MANIFOLD | 274.00.02 | 274.00.02 | 274.00.02 | 274.00.02 | 274.00.02 | 274.00.02 |
| 6 | DETECTION CABLE | 605.02 .05 | 605.02 .05 | 605.02 .05 | 605.02 .05 | 605.02 .05 | 605.02 .05 |
| 7 | DETECTION ELECTRODE | 208.01.06 | 208.01.06 | 208.01.06 | 208.01 .06 | 208.01.02 | 208.01.02 |
| 8 | COMPLETE BLAST TUBE | 309.00.96 | 309.00.86 | 309.00.96 | 309.00.86 | 309.00.19 | 309.10 .05 |
| 9 | BLAST TUBE EXTENSION | --- | --- | --- | --- | --- | 220.00.46 |
| 10 | COMBUSTION HEAD | 306.00.73 | 306.00.72 | 306.00.73 | 306.00.72 | 306.00.05 | 306.00.05 |
| 11 | IGNITION ELECTRODE | 208.02.09 | 208.02.09 | 208.02 .09 | 208.02 .09 | 208.02.02 | 208.02.02 |
| 12 | IGNITION CABLE | 60.01 .08 | 605.01 .08 | 605.01 .08 | 605.01 .08 | 605.01 .08 | 605.01 .08 |
| 13 | GASKET | 211.00.04 | 211.00 .04 | 211.00 .04 | 211.00 .04 | 211.00 .04 | 211.00 .04 |
| 14 | "O" RING | 225.00.01 | 225.00.01 | 225.00.01 | 225.00.01 | 225.00.01 | 225.00.01 |
| 15 | THROTTLE VALVE | 246.02.21 | 246.02.21 | 246.02.21 | 246.02.21 | 246.02.21 | 246.02.21 |
| 17 | AIR DAMPER | 214.00.05 | 214.00 .05 | 214.00.05 | 214.00 .05 | 214.00.05 | 214.00 .05 |
| 18 | SERVOCONTROL SUPPORT BRACKET | 305.00.11 | 305.00.11 | 305.00.11 | 305.00.11 | 305.00.11 | 305.00.11 |
| 19 | SERVOCONTROL (BERGER) | 248.00 .53 | 248.00 .53 | 248.00.53 | 248.00 .53 | 248.00.53 | 248.00 .53 |
| 20 | ADJUSTABLE CAM | 244.00.29 | 244.00.29 | 244.00.29 | 244.00.29 | 244.00.29 | 244.00.29 |
| 21 | LEVER | 244.00.15 | 244.00.15 | 244.00.15 | 244.00.15 | 244.00.15 | 244.00.15 |
| 22 | INLET CONE | 204.00.16 | 204.00.16 | 204.00.16 | 204.00.16 | 204.00.16 | 204.00.16 |
| 23 | FAN | 215.00.06 | 215.00 .06 | 215.00 .06 | 215.00 .06 | 215.00 .06 | 215.00 .06 |
| 24 | AIR PRESSURE SWITCH | 216.00.65 | 216.00.65 | 216.00.65 | 216.00.65 | 216.00.65 | 216.00.65 |
| 26 | HEAD ADJUSTING SCREW | 232.05.01 | 232.05.01 | 232.05.01 | 232.05.01 | 232.05.01 | 232.05.01 |
| 27 | MOTOR | 218.07.04 | 218.07.04 | 218.07.04 | 218.07.04 | 218.07.04 | 218.07.04 |
| 28 | MULTIBLOC COIL | 258.00.17 | 258.00.17 | 258.00.17 | 258.00.17 | 258.00.17 | 258.00.17 |
| 29 | MULTIBLOC VALVES GROUP | 219.03 .41 | 219.03.41 | 219.03.42 | 219.03.42 | 219.03.42 | 219.03.42 |
| 37 | LEAKAGE CONTROL VPS504 (OPTIONAL) | 219.16.04 | 219.16.04 | 219.16.04 | 219.16.04 | 219.16.04 | 219.16.04 |
| 39 | MINIMUM GAS PRESSURE SWITCH | 216.00.52 | 216.00.52 | 216.00.52 | 216.00.52 | 216.00.52 | 216.00.52 |
| 41 | MODULATOR | 257.00.34 | 257.00.34 | 257.00.34 | 257.00.34 | 257.00.34 | 257.00 .34 |
| 42 | FIELD ADAPTER | 256.01.. | 256.01.. | 256.01.. | 256.01.. | 256.01.. | 256.01.. |
| 43 | MODULATION PROBE | 256.01.. | 256.01.. | 256.01.. | 256.01.. | 256.01.. | 256.01.. |



| POS. | DESCRIPTION | $\begin{gathered} \text { P45 } \\ \text { M-.MD..S... } 40 \\ \text { M-.MD..L.. } 40 \end{gathered}$ | $\begin{gathered} \text { P45 } \\ \text { M-.MD..S... } 50 \\ \text { M-.MD..L.. } 50 \end{gathered}$ | $\begin{gathered} \text { P65 } \\ \text { M-.MD..S... } 50 \\ \text { M-.MD..L... } 50 \end{gathered}$ | $\begin{gathered} \text { P65 } \\ \text { M-.MD..S... } 65 \\ \text { M-.MD..L... } 65 \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | FLAME CONTROL DEVICE SOCKET | 203.04.15 | 203.04.15 | 203.04.15 | 203.04.15 |
| 2 | FLAME CONTROL DEVICE LANDIS LGB22 | 202.04.30 | 202.04.30 | 202.04 .30 | 202.04.30 |
| 2 | FLAME CONTROL DEVICE LANDIS LMG22 | 202.04.50 | 202.04.50 | 202.04.50 | 202.04.50 |
| 3 | LEAKAGE CONTROL | 219.16.04 | 219.16.04 | 219.16.04 | 219.16.04 |
| 5 | OVERLOAD RELAY | --- | --- | 614.00 .32 | 614.00.32 |
| 6 | CONTACTOR | --- | --- | 613.00 .16 | 613.00 .16 |
| 7 | IGNITION TRANSFORMER | 217.01.02 | 217.01.02 | 217.01.02 | 217.01.02 |
| 8 | RELAY | --- | --- | --- | --- |
| 9 | RELAY SOCKET | --- | --- | --- | --- |
| 11 | MANIFOLD | 274.00.02 | 274.00.02 | 274.00.03 | 274.00.03 |
| 12 | DETECTION CABLE | 605.02.05 | 605.02.05 | 605.02.05 | 605.02 .05 |
| 13 | DETECTION ELECTRODE | 208.01.02 | 208.01.02 | 208.01.02 | 208.01.02 |
| 14 | STANDARD BLAST TUBE EXTENSION | --- | --- | 220.00.55 | 220.00.55 |
| 14 | LONG BLAST TUBE EXTENSION | 220.00 .46 | 220.00 .46 | 220.00.56 | 220.00.56 |
| 15 | BLAST TUBE RING | --- | --- | 247.00.37 | 247.00.37 |
| 16 | BLAST TUBE BODY | --- | --- | 230.00.55 | 230.00.55 |
| 17 | COMPLETE BLAST TUBE - STANDARD | 309.00.39 | 309.00.39 | 309.10.E9 | 309.10.E9 |
| 17 | COMPLETE BLAST TUBE - LONG | 309.10.F1 | 309.10.F1 | 309.10.E0 | 309.10.E0 |
| 18 | COMBUSTION HEAD | 306.00.C1 | 306.00.C1 | 306.00.C2 | 306.00.C2 |
| 19 | IGNITION ELECTRODE | 208.02.02 | 208.02.02 | 208.02.02 | 208.02.02 |
| 20 | IGNITION CABLE | 605.01 .08 | 605.01 .08 | 605.01 .08 | 605.01 .08 |
| 21 | GASKET | 211.00.13 | 211.00.13 | 211.00.33 | 211.00.33 |
| 22 | OR RING FOR THROTTLE VALVE | 225.00.03 | 225.00.03 | 225.00.03 | 225.00.03 |
| 23 | THROTTLE VALVE | 246.02.22 | 246.02.22 | 246.02.22 | 246.02.24 |
| 24 | GAS PRESSURE SWITCH | 216.00.10 | 216.00.10 | 216.00.10 | 216.00.10 |
| 26 | INTERNAL AIR DAMPER | 214.00.07 | 214.00.07 | 214.00.22 | 214.00.22 |
| 26A | EXTERNAL AIR DAMPER | --- | --- | 214.00.23 | 214.00.23 |
| 27 | SERVOCONTROL SUPPORT BRACKET | 305.00.11 | 305.00.11 | 305.00.12 | 305.00.12 |
| 28 | SERVOCONTROL | 248.00.53 | 248.00.53 | 248.00.53 | 248.00.53 |
| 29 | ADJUSTABLE CAM | 244.00.29 | 244.00.29 | 244.00.29 | 244.00.29 |
| 30 | COMPLETE LEVER | 244.00.15 | 244.00.15 | 244.00.15 | 244.00 .15 |
| 31 | INLET CONE | 204.00.17 | 204.00.17 | 204.00.11 | 204.00.11 |
| 32 | FAN | 215.00.21 | 215.00.21 | 215.00 .18 | 215.00 .18 |
| 33 | AIR PRESSURE SWITCH | 216.00.65 | 216.00.65 | 216.00.65 | 216.00.65 |
| 35 | HEAD ADJUSTING KNOB | 232.05.02 | 232.05.02 | 232.05.03 | 232.05.03 |
| 36 | ELECTRIC MOTOR | 218.02.03.01 | 218.02.03.01 | 218.02.03.01 | 218.02.03.01 |
| 37 | GAS SOLENOID VALVE EV2 | --- | --- | --- | 219.01.51 |
| 38 | GAS SOLENOID VALVE EV1 | --- | --- | --- | 219.03.21 |
| 39 | GAS FILTER | --- | --- | --- | 209.01.17 |
| 40 | COIL FOR EV1 | --- | --- | --- | 258.00.05 |
| 41 | PRINTED CIRCUIT FOR EV1 | --- | --- | --- | 253.01.05 |
| 42 | ACTIVATOR WITH STABILIZER | --- | --- | --- | 219.01.20 |
| 43 | MULTIBLOC VALVES GROUP | 219.03.E9 | 219.03.E0 | 219.03.E0 | --- |
| 44 | GAS PRESSURE SWITCH | 216.00.76 | 216.00.76 | 216.00.76 | --- |
| 45 | MODULATOR PROBE | 256.01.. | 256.01.. | 256.01.. | 256.01.. |
| 46 | MODULATOR RWF40 | 257.00.34 | 257.00.34 | 257.00.34 | 257.00.34 |
| 46 | FIELD ADAPTER | 257.01.12 | 257.01.12 | 257.01.12 | 257.01.12 |
| 46A | FLAME CONTROL DEVICE SOCKET | 256.01.. | 256.01.. | 256.01.. | 256.01.. |

## SIEMENS LME11／21／22 CONTROL BOX

The series of equipment LME．．is used for the starup and supervisione of 1 －or 2 －stage gas burners．The series LME．．is interchangeable with the series LGB．．and LMG．．，all diagrams and accessories are interchangea－ ble．

## Comparative table

| LGB Series | LMG Series | LME Series |
| :---: | :---: | :---: |
| --- | LMG 25．33 | LME 11．33 |
| LGB 21．33 | LMG 21．33 | LME 21．33 |
| LGB 22．33 | LMG 22．33 | LME 22．33 |

## Preconditions for burner startup

－Burner control must be reset
－All contacts in the line are closed，request for heat
－No undervoltage
－Air pressure switch LP must be in its＂no－load＂position
－Fan motor or AGK25 is closed
－Flame detector is darkened and there is no extraneous light

## Undervoltage

Safety shutdown from the operating position takes place should mains voltage drop below about AC 175 V （at UN＝AC 230 V ）
Restart is initiated when mains voltage exceeds about AC 185 V （at UN $=$ AC 230 V）．

## Controlled intermittent operation

After no more than 24 hours of continuous operation，the burner control will initiate automatic controlled shutdown followed by a restart．

## Reversed polarity protection with ionization

If the connections of live conductor（terminal 12）and neutral conductor （terminal 2）aremixed up，the burner control will initiate lockout at the end of the safety time＂TSA＂．

## Control sequence in the event of fault

If lockout occurs，the outputs for the fuel valves，the burner motor and the ignition equipment will immediately be deactivated（＜1 second）．

## Operational status indication

In normal operation，the different operating states are showed by means of the multicolor LED，inside the lockout reset button：


During startup，status indication takes place according to the table：

| Status | Color code | Color |
| :---: | :---: | :---: |
| Waiting time tw，other waiting states | O．．．．．．．．．．．．．．．．．．．．．．．．．．．．．．． | Off |
| Ignition phase，ignition controlled | $\bullet \bigcirc \bullet \bigcirc \bullet \bigcirc \bullet \bigcirc \bullet \bigcirc \bullet$ | Flashing yellow |
| Operation，flame ok | 口．．．．．．．．．．．．．．．．．．．．．．．．．．．．．．．．． | Green |
| Operation，flame not ok | ロOロOロOロOロO | Flashing green |
| Extraneous light on burner startup |  | Green－red |
| Undervoltage |  | Yellow－red |
| Fault，alarm | ©．．．．．．．．．．．．．．．．．．．．．．．．．．．．．．．．． | Red |
| Error code output （refer to＂Error code table＂） | $\boldsymbol{\Delta}$ | Flashing red |

## START－UP PROGRAM

As far as the startup program，see its time diagram：

## A Start command（switching on）

This command is triggered by control thermostat／pressure controller «R＂．Terminal 12 receives voltage and the programming mechanism starts running．On completion of waiting time «tw» with the LME21．．．，or after air damper＂SA» has reached the nominal load position（on comple－ tion of «t11»）with the LME22．．．，fan motor «M» will be started．

## tw Waiting time

During the waiting time，air pressure monitor «LP» and flame relay «FR» are tested for correct contact positions．

## t11 Programmed opening time for actuator «SA»

（Only with LME22．．．）The air damper opens until the nominal load position is reached．Only then will fan motor « $M$ » be switched on．

## t10 Specified time for air pressure signal

On completion of this period of time，the set air pressure must have built up，or else lockout will occur．

## t1 Prepurge time

Purging the combustion chamber and the secondary heating surfaces： required with low－fire air volumes when using the LME21．．．and with nomi－ nal load air volumes when using the LME22．．．．The diagrams show the so－ called prepurge time «t1» during which air pressure monitor «LP» must indicate that the required air pressure is available．The effective prepurge time «t1» comprises interval end «tw» through «t3»．

## t12 Programmed closing time for actuator «SA»

（Only with LME22．．．）During «t12»，the air damper travels to the low－fire position．

## t3 Preignition time

During «t3» and up to the end of «TSA»，flame relay «FR» is forced to close．On completion of «t3»，the release of fuel is triggered at terminal 4.

## TSA Ignition safety time

On completion of «TSA»，a flame signal must be present at terminal 1. That flame signal must be continuously available until shutdown occurs， or else flame relay «FR» will be deenergized，resulting in lockout．

## t4 Interval BV1 and BV2－LR

Time between the end of TSA and the signal to the second fuel valve BV2 or to the load controller LR

## B－B＇Interval for flame establishment

C Burner operation position
C－D Burner operation（heat production）
D Controlled by＂R＂shutdown

The burner stops and the control device is ready for a new startup．


LME22 control sequence



## Control sequence

tw Waiting time
t1 Purge time
TSA Ignition safety time
t3 Preignition time
t 3 n Postignition time
t4 Interval between BV1 and BV2/LR
t10 Specified time for air pressure signal
t11 Programmed opening time for actuator SA
t12 Programmed closing time for actuator SA

LME11 connection diagram


LME21 connection diagram


LME22 connection diagram


## Connection diagram

AL Error message (alarm)
BV Fuel valve
EK2 Remote lockout reset button
FS Flame signal
GP Gas pressure switch
LP Air pressure switch
LR Load controller
M Fan motor
R Control thermostat/pressurestat
SB Safety limit thermostat
W Limit thermostat/pressure switch
Z Ignition transformer

## CONTROL PROGRAM IN THE EVENT OF FAULT

- If a fault occurs, all outputs will immediately be deactivated (in less than 1s).
- After an interruption of power, a restart will be made with the full program sequence.
- If the operating voltage drops below the undervoltage thresold, a safety shutdown is performed.
- If the operating voltage exceeds the undervoltage thresold, a restart will be performed.
- In case of extraneous light during "t1", a lockout occurs.
- In case of extraneous light during "tw", there is a prevention of startup and a lockout after 30 seconds.
- In case of no flame at the end of TSA, there will be max. 3 repetitions of the startup cycle, followed by a lockout at the end of TSA, for mod. LME11..; directly a lockout at the end of TSA for LME21-22 models.
- For LME11 model: if a loss of flame occurs during operation, in case of an establishment of flame at the end of TSA, there will be max. 3 repetitions, otherwise a lockout will occur.
- For LME21-22 models: if a loss of flame occurs during operation, there will be a lockout.
- If the contact of air pressure monitor LP is in working position, a prevention of startup and lockout after 65 seconds will occur.
- Ilf the contact of air pressure monitor LP is in normal position, a lockout occurs at the end of t 10 .
- If no air pressure signal is present after completion of t 1 , a lockout will occur.


## CONTROL BOX LOCKED

In the event of lockout, the LME.. remains locked and the red signal lamp (LED) will light up.The burner control can immediately be reset. This state is also mantained in the case fo mains failure.

## DIAGNOSITICS OF THE CASUE OF FAULT

- Press the lockout reset button for more than 3 seconds to activate the visual diagnostics.
- Count the number of blinks of the red signsl lamp and check the fault condition on the "Error code table" (the device repeats the blinks for regular intervals).
During diagnostics, the control outputs are deactivated:
- the burner remains shut down;
- external fault indication is deactivated;
- fault status is showed by the red LED, inside the LME's lockout reset buttonaccording to the "Error code table":

ERROR CODE TABLE

| ERROR CODE TABLE |  |
| :---: | :---: |
| 2 blinks ** | No establishment of flame at the end of TSA <br> - Faulty or soiled fuel valves <br> - Faulty or soiled flame detector <br> - Inadequate adjustement of burner, no fuel <br> - Faulty ignition equipment |
| 3 blinks *** | The air pressure switch does not switch or remains in idle position: <br> - LP is faulty <br> - Loss of air pressure signal after t10 <br> - LPis welded in normal position. |
| 4 blinks **** | - Extraneous light when burner starts up. |
| 5 blinks ***** | - LP is working position. |
| 6 blinks ***** | Free. |
| 7 blinks ******* | Loss of flame during operation <br> - Faulty or soiled fuel valves <br> - Faulty or soiled flame detector <br> - Inadequate adjustement of burner |
| 8 $\div 9$ blinks | Free |
| 10 blinks ********** | Faulty output contacts <br> Attention: "lockout" remote signal (terminal no. 10) not enabled <br> - Wiring error <br> - Anomalous voltage on ouput terminals <br> - Other faults |
| 14 blinks ************** (only for LME4x) | - CPI contact (gas valve microswitch) not closed. |

## RESETTING THE BURNER CONTROL

When lockout occurs, the burner control can immediately be reset, by pressing the lockout reset button for about $1 . .3$ seconds. The LME.. can only be reset when all contacts in the line are closed and when there is no undervoltage.

## LIMITATION OF REPETITIONS (only for LME11.. model)

If no flame is established at the end of TSA, or if the flame is lost during operation, a maximum of 3 repetitions per controller startup can be performed via "R", otherwise lockout will be initiated. Counting of repetitions is restarted each time a controlled startup via "R" takes place.

Condensation, formation of ice and ingress of water are not permitted!

## TECHNICAL CHARACTERISTICS

Mains voltage
Frequency
Power consumption
External primary fuse input current at terminal 12
Detection cable length
Detection cable length
Reset cable length
Term. 8 \& 10 cable length
Thermostat cable length
and other terminals
Safety class
Index of protection
Operating conditions
Storage conditions
Weight

120V AC +10\% / -15\%
230V AC $+10 \% /-15 \%$
50 ... 60 Hz +/- 6\%
12VA
max. 10 A (slow)
max. 5 A
max. 3m (for electrode)
max. 20 m (laid separately, for QRA probe)
max. 20 m (posato separatamente)
max. 20 m
max. 3 m

I
IP40 (to be ensured during mounting)
$-20 \ldots+60^{\circ} \mathrm{C},<95 \%$ UR
$-20 \ldots+60^{\circ} \mathrm{C},<95 \%$ UR
approx. 160 g

## UNIGAS CIB EHIEASS

C.I.B. UNIGAS S.p.A.

Via L.Galvani, 9-35011 Campodarsego (PD) - ITALY
Tel. +390499200944 - Fax + 39049 9200945/9201269 web site: www.cibunigas.it - e-mail: cibunigas@cibunigas.it


EMC conformity has been tested with the following connections

| FUNCTION | CABLE TYPE | LENGTH |
| :--- | :--- | :--- |
| Power supply cable | $1 \mathrm{~mm}^{2}$ | 1 m |
| Relay output cable | $1 \mathrm{~mm}^{2}$ | $3,5 \mathrm{~m}$ |
| TC input | $0,8 \mathrm{~mm}^{2}$ compensated | 5 m |
| Pt100 input | $1 \mathrm{~mm}^{2}$ | 3 m |



## USER'S MANUAL

COD. M12925CA Rel 1.2 08/2014

SOFTWARE VERSION 1.0x T73 code 80379 / Edition 01-06/2012

## 3•DESCRIPTION OF FACEPLATE


"Inc" and "Dec" key
Press to increment (decrement) any numerical parameter •• Increment (decrement) speed is proportional to time key stays pressed •• The operation is not cyclic: once the maximum (minimum) value of a field is reached, the value will not change even if the key remains pressed.

Indication of output states
OUT 1 (AL1): OUT 2 (OPEN). OUT 3 OUT 1 (AL1); OUT 2 (OPEN); OUT 3 (CLOSED)

PV Display: Indication of process variable Error Indication: LO, HI, Sbr, Err
$L O=$ the value of process variable is $<$ di LO_S
Ho the value of process variable is $>$ di
Ebr=faulty sensor or input values higher than max. limits Err= PT100 thir values lower than min. limits (i.e.: TC wrong connection)

SV display: Indication of setpoint
Function key
Gives access to the various configuration phases • Confirms change of set parameters and browses next or previous parameter (if Auto/Man key is pressed)

## $4 \cdot$ CONNECTIONS




| Prot | Display | Modification |
| :--- | :--- | :--- |
| 0 | SP, Hy.P, Hy.n | SP, Hy.P, Hy.n |
| 1 | SP, Hy.P, Hy.n | SP |
| 2 | SP |  |

+4 to disable InP, Out
+8 to disable CFG

## 6•PROGRAMMING and CONFIGURATION


N.B.: Once a particular configuration is entered, all unnecessary parameters are no longer displayed


## - CFG



(*) LBA alarm may be reset by simultaneously pressing $\Delta+\nabla$ keys when OutP is displayed or by switching to Manual.



| Pro Protection code |
| :--- | | Prot | Display | Modification |
| :--- | :--- | :--- |
| 0 | SP, Hy.P, Hy.n, AL.2, AL.3, PoS, OuP, INF | SP, Hy.P, Hy.n, AL.2, AL.3, PoS |
| 1 | SP, Hy.P, Hy.n, AL.2, AL.3, PoS, OuP, INF | SP |
| 2 | SP, OuP, INF |  |

+4 to disable InP , Out
+8 to disable CFG

+ 16 to disable SW "power-up - power down"
+ 32 disable manual power latching
+64 to disable manual power modification
+128 enables full configuration
Note: OuP and INF only display configuration extended


## - Hrd




## - Lin



- U.CAL

| U.CA |  |
| :---: | :---: | :--- |
| User <br> calibration | Val Function <br> 1 - <br> 2 Input 1 - custom $10 \mathrm{~V} / 20 \mathrm{~mA}$ <br> 3 Input 1 - custom 60mV <br> 4 Custom PT100 / J PT100 <br> 5 Custom PTC <br> 6 Custom NTC <br> 7 - |



Obtain burner consent by configuring alarm 1 as inverse deviation with positive hysteresis Hy.P and negative hysteresis Hy.n

## $8 \cdot$ PRE-HEATING FUNCTION

Enable the pre-heating function by setting parameters GS.0, Ht.0, GS. 1 other than zero.
It consists of three phases that are activated sequentially at firing:

## - Ramp 0 phase

Enabled by setting GS. $0>0$. Starting from setpoint $=P V$ (initial state), it reaches pre-heating set SP. 0 with gradient GS. 0

## - Maintenance phase

Enabled by setting Ht. $0>0$. Maintains pre-heating setpoint SP. 0 for time Ht .0

## - Ramp 1 phase

Enabled by setting GS. $1>0$. Starting from pre-heating setpoint SP.0, it reaches active _SP set with gradient GS. 1
In case of selftuning, the pre-heating function is not activated


## 9 • ADJUSTMENT WITH MOTORIZED VALVE

In an adjustment process the adjustment valve has the function of varying fuel delivery (frequently corresponding to the thermal energy introduced into the process) in relation to the signal coming from the controller.
For this purpose it is provided with an actuator able to modify its opening value, overcoming the resistances produced by the fluid passing inside it.
The adjustment valves vary the delivery in a modulated manner, producing finite variations in the fluid passage inner area corresponding to finite variations of the actuator input signal, coming from the controller. The servomechanism, for example, comprises an electric motor, a reducer and a mechanical transmission system which actions the valve.
Various auxiliary components can be present such as the mechanical and electrical safety end travels, manual actioning systems.


The controller determines, on the basis of the dynamics of the process, the control output for the valve corresponding to the opening of the same in such a way so as to maintain the desired value of the process variable.

## Characteristic parameters for valves control

- Actuator time (Ac.t) is the time employed by the valve to pass from entirely open to entirely closed (or vice-versa), and can be set with a resolution of one second. It is a mechanical feature of the valve+actuator unit.
NOTE: if the actuator's travel is mechanically limited it is necessary to proportionally reduce the Ac.t value.
- Minimum impulse (t.Lo) expressed as a \% of the actuator time (resolution 0.1\%).

Represents the minimum change in position corresponding to a minimum change in power supplied by the instrument below which the actuator will not physically respond to the command.
This represents the minimum variation in position due to which the actuator does not physically respond to the command.
The minimum duration of the movement can be set in t.Lo, expressed as a \% of actuator time.

- Impulsive intervention threshold (t.Hi) expressed as a \% of the actuator time (resolution $0.1 \%$ ) represents the position displacement (requested position real position) due to which the manoeuvre request becomes impulsive.
You can choose between 2 types of control:

1) ON time of movement $=\mathrm{t}$.on and OFF time proportional to shift and greater than or equal to t .Lo (we recommend setting t.on $=\mathrm{t} . \mathrm{Lo}$ ) (set t.oF = 0 ).
2) ON time of movement $=$ t.on and OFF time $=$ t.oF. A value set for t.oF <t.on is forced to t.on. To activate this type, set t.oF $<>0$.

The type of movement approach allows fine control of the reverse drive valve (from potentiometer or not), especially useful in cases of high mechanical inertia. Set $\mathrm{t} . \mathrm{Hi}=0$ to exclude modulation in positioning.
This type of modulated approach allows precise control of the feedback actioned valve, by a potentiometer or not, and is especially useful in cases of high mechanical inertia. Setting $\mathrm{t} . \mathrm{Hi}=0$ excludes modulation in positioning.

- Dead zone(dE.b) is a displacement band between the adjustment setpoint and the process variable within which the controller does not supply any command to the valve (Open = OFF; Close = OFF). It is expressed as a percentage of the bottom scale and is positioned below the setpoint.
The dead zone is useful in an operative process to avoid straining the actuator with repeated commands and an insignificant effect on the adjustment. Setting $\mathrm{dE} . \mathrm{b}=0$ the dead zone is excluded.


Graph of behavior inside the band with integral time $\neq 0$.
With integral time $=0$, movement ON time is always equal to OFF time.

$$
\mathrm{t} 0=\mathrm{t} . \mathrm{Lo}
$$

## Valve control modes

With the controller in manual, the setting of parameter At.y $\geq 8$ allows direct control of the valve open and close commands through the keyboard Increments and Decrements on the front seats.
V0 - for floating valve without potentiometer
Model Vo have similar behaviour: every manoeuvre request greater than the minimum impulse t.Lo is sent to the actuator by means of the OPEN/CLOSE relays; every action updates the presumed position of the virtual potentiometer calculated on the basis of the actuator travel declared time.
In this way there is always a presumed position of the valve which is compared with the position request of the controller.
Having reached a presumed extreme position (entirely open or entirely closed determined by the "virtual potentiometer") the controller provides a command in the same direction, in this way ensuring the real extreme position is reached (minimum command time $=\mathrm{t} . \mathrm{on}$ ).
The actuators are usually protected against the OPEN command in the entirely open position or CLOSE command in the entirely closed position.
V3 - for floating valve, PI control
When the difference between the position calculated by the controller and the only proportional component exceeds the value corresponding to the minimum impulse t.Lo the controller provides an OPEN or CLOSE command of the duration of the minimum impulse itself t .Lo.
At each delivery the integral component of the command is set to zero (discharge of the integral).
The frequency and duration of the impulses is correlated to the integral time (h.it or c.it).
Non-movement behavior
$\mathrm{t} . \mathrm{Hi}=0$ : with power $=100 \%$ or $0.0 \%$, the corresponding open or close outputs always remain enabled (safety status).
Movement behavior
t.Hi <>0: with position attained corresponding to $100 \%$ or $0.0 \%$, the corresponding open or close outputs are switched off.


If t.oF $=0$, current function is maintained.

If t.oF $\neq 0$ movement mode will be as shown on the graph

## 10•CONTROL ACTIONS

## Proportional Action:

action in which contribution to output is proportional to deviation at input (deviation = difference between controlled variable and setpoint).
Derivative Action:
action in which contribution to output is proportional to rate of variation input deviation.
Integral Action:
action in which contribution to output is proportional to integral of time of input deviation.
Influence of Proportional, Derivative and Integral actions on response of process under control

* An increase in P.B. reduces oscillations but increases deviation.
* A reduction in P.B. reduces the deviation but provokes oscillations of the controlled variable (the system tends to be unstable if P.B. value is too low).
* An increase in Derivative Action corresponds to an increase in Derivative Time, reduces deviation and prevents oscillation up to a critical value of Derivative Time, beyond which deviation increases and prolonged oscillations occur.
* An increase in Integral Action corresponds to a reduction in Integral Time, and tends to eliminate deviation between the controlled variable and the setpoint when the system is running at rated speed.
If the Integral Time value is too long (Weak integral action), deviation between the controlled variable and the setpoint may persist.
Contact GEFRAN for more information on control actions.


## 11•MANUAL TUNING

A) Enter the setpoint at its working value.
B) Set the proportional band at $0.1 \%$ (with on-off type setting).
C) Switch to automatic and observe the behavior of the variable. It will be similar to that in the figure:

D) The PID parameters are calculated s follows: Proportional band

( V max $-\mathrm{V} \min$ ) is the scale range.
Integral time: $\mathrm{It}=1.5 \times \mathrm{T}$
Derivative time: $\mathrm{dt}=\mathrm{It} / 4$
E) Switch the unit to manual, set the calculated parameters. Return to PID action by setting the appropriate relay output cycle time, and switch back to Automatic.
F) If possible, to optimize parameters, change the setpoint and check temporary response. If an oscillation persists, increase the proportional band. If the response is too slow, reduce it.

## 12•SET GRADIENT

SET GRADIENT: if set to $\neq 0$, the setpoint is assumed equal to $P V$ at power-on and auto/man switchover. With gradient set, it reaches the local setpoint. Every variation in setpoint is subject to a gradient.
The set gradient is inhibited at power-on when self-tuning is engaged.
If the set gradient is set to $\neq 0$, it is active even with variations of the local setpoint.
The control setpoint reaches the set value at the speed defined by the gradient.

## 13•SOFTWARE ON / OFF SWITCHING FUNCTION

How to switch the unit OFF: hold down the "F" and "Raise" keys simultaneously for 5 seconds to deactivate the unit, which will go to the OFF state while keeping the line supply connected and keeping the process value displayed. The SV display is OFF.
All outputs (alarms and controls) are OFF (logic level 0, relays de-energized) and all unit functions are disabled except the switch-on function and digital communication.
How to switch the unit ON: hold down the " F " key for 5 seconds and the unit will switch OFF to ON. If there is a power failure during the OFF state, the unit will remain in OFF state at the next power-up (ON/OFF state is memorized).
The function is normally enabled, but can be disabled by setting the parameter Prot $=$ Prot +16 .

## 14•SELF-TUNING

The function works for single output systems (heating or cooling). The self-tuning action calculates optimum control parameter values during process startup. The variable (for example, temperature) must be that assumed at zero power (room temperature).
The controller supplies maximum power until an intermediate value between starting value and setpoint is reached, after which it zeros power.
PID parameters are calculated by measuring overshoot and the time needed to reach peak. When calculations are finished, the system disables automatically and the control proceeds until the setpoint is reached.

## How to activate self-tuning:

A. Activation at power-on

1. Set the setpoint to the required value
2. Enable selftuning by setting the Stun parameter to 2 (CFG menu)
3. Turn off the instrument
4. Make sure the temperature is near room temperature
5. Turn on the instrument again

## B. Activation from keyboard

1. Make sure that key M/A is enabled for Start/Stop selftuning (code but = 6 Hrd menu)
2. Bring the temperature near room temperature

3. Set the setpoint to the required value
4. Press key $M / A$ to activate selftuning (Attention: selftuning interrupts if the key is pressed again)

The procedure runs automatically until finished, when the new PID parameters are stored: proportional band, integral and derivative times calculated for the active action (heating or cooling). In case of double action (heating or cooling), parameters for the opposite action are calculated by maintaining the initial ratio between parameters (ex.: $\mathrm{CPb}=\mathrm{HPb}{ }^{*} \mathrm{~K}$; where $\mathrm{K}=\mathrm{CPb} / \mathrm{HPb}$ when self-tuning starts). When finished, the Stun code is automatically cancelled.

## Notes:

-The procedure does not start if the temperature is higher than the setpoint (heating control mode) or if the temperature is lower than the setpoint (cooling control mode). In this case, the Stu code is not cancelled.
-It is advisable to eneable one of the configurable LEDs to signal selftuning status.By setting one of parameters
LED1, LED2, LED3=4 or 20 on the Hrd menu, the respective LED will be on or flashing when selftuning is active.

## 15•ACCESSORIES

- Interface for instrument configuration

KIT PC USB / RS485 o TTL


Kit for PC via the USB port (Windows environment) for GEFRAN instruments configuration: Lets you read or write all of the parameters

- A single software for all models
- Easy and rapid configuration
- Saving and management of parameter recipes
- On-line trend and saving of historical data

Component Kit:

- Connection cable PC USB ... port TTL
- Connection cable PC USB ... RS485 port
- Serial line converter
- CD SW GF Express installation


## - ORDERING CODE

## GF_eXK-2-0-0

## cod F049095

## 16•ORDER CODE



| UTPUT 2 |  |  |  |
| :--- | :---: | :---: | :---: |
| Relay | R |  |  |
| UTPUT 3 |  |  |  |
| Relay | R |  |  |

## - WARNINGS

WARNING: this symbol indicates danger. It is placed near the power supply circuit and near high-voltage relay contacts.

## Read the following warnings before installing, connecting or using the device:

- follow instructions precisely when connecting the device.
- always use cables that are suitable for the voltage and current levels indicated in the technical specifications.
- the device has no ON/OFF switch: it switches on immediately when power is turned on. For safety reasons, devices permanently connected to the power supply require a twophase disconnecting switch with proper marking. Such switch must be located near the device and must be easily reachable by the user. A single switch can control several units. - if the device is connected to electrically NON-ISOLATED equipment (e.g. thermocouples), a grounding wire must be applied to assure that this connection is not made directly through the machine structure.
- if the device is used in applications where there is risk of injury to persons and/or damage to machines or materials, it MUST be used with auxiliary alarm units. You should be able to check the correct operation of such units during normal operation of the device.
- before using the device, the user must check that all device parameters are correctly set in order to avoid injury to persons and/or damage to property.
- the device must NOT be used in infiammable or explosive environments. It may be connected to units operating in such environments only by means of suitable interfaces in conformity to local safety regulations.
- the device contains components that are sensitive to static electrical discharges. Therefore, take appropriate precautions when handling electronic circuit boards in order to prevent permanent damage to these components.
Installation: installation category II, pollution level 2, double isolation
The equipment is intended for permanent indoor installations within their own enclosure or panel mounted enclosing the rear housing and exposed terminals on the back.
- only for low power supply: supply from Class 2 or low voltage limited energy source
- power supply lines must be separated from device input and output lines; always check that the supply voltage matches the voltage indicated on the device label.
- install the instrumentation separately from the relays and power switching devices
- do not install high-power remote switches, contactors, relays, thyristor power units (particularly if "phase angle" type), motors, etc... in the same cabinet.
- avoid dust, humidity, corrosive gases and heat sources.
- do not close the ventilation holes; working temperature must be in the range of $0 \ldots 50^{\circ} \mathrm{C}$.
- surrounding air: $50^{\circ} \mathrm{C}$
- use $60 / 75^{\circ} \mathrm{C}$ copper (Cu) conductor only, wire size range $2 x$ No 22-14AWG, Solid/Stranded
- use terminal tightening torque 0.5 N m

If the device has faston terminals, they must be protected and isolated; if the device has screw terminals, wires should be attached at least in pairs.

- Power: supplied from a disconnecting switch with fuse for the device section; path of wires from switch to devices should be as straight as possible; the same supply should not be used to power relays, contactors, solenoid valves, etc.; if the voltage waveform is strongly distorted by thyristor switching units or by electric motors, it is recommended that an isolation transformer be used only for the devices, connecting the screen to ground; it is important for the electrical system to have a good ground connection; voltage between neutral and ground must not exceed 1 V and resistance must be less than 6Ohm; if the supply voltage is highly variable, use a voltage stabilizer for the device; use line filters in the vicinity of high frequency generators or arc welders; power supply lines must be separated from device input and output lines; always check that the supply voltage matches the voltage indicated on the device label.
- Input and output connections: external connected circuits must have double insulation; to connect analog inputs (TC, RTD) you have to: physically separate input wiring from power supply wiring, from output wiring, and from power connections; use twisted and screened cables, with screen connected to ground at only one point; to connect adjustment and alarm outputs (contactors, solenoid valves, motors, fans, etc.), install RC groups (resistor and capacitor in series) in parallel with inductive loads that work in AC (Note: all capacitors must conform to VDE standards (class x2) and support at least 220 VAC. Resistors must be at least $2 W$ ); fit a 1 N 4007 diode in parallel with the coil of inductive loads that operate in DC.

GEFRAN spa will not be held liable for any injury to persons and/or damage to property deriving from tampering, from any incorrect or erroneous use, or from any use not conforming to the device specifications.

## Set-up for 600V RRR0-1-T73 regulator

## Set up for temperature probe Pt100 (ex Siemens QAE2120 $130^{\circ} \mathrm{C}$ max.)

The regulator comes out of the factory preset with the corresponding values of the Siemens RWF40.000 and RWF50.2x

Verify wiring of the sensor


Regulation of the set-point $=\mathbf{8 0}$
It can be modified by using arrows "up" and "down".
By pushing F you go to parameters:

| Hy.P | 5 (hysteresis positive for output 1, terminals 21-22 (ex Q13-Q14) |
| :--- | :--- |
| Hy.n | -5 hysteresis negative for output ,1 terminals 21-22 (ex Q13-Q14) |

Keep pushing $\mathbf{F}$ until you see PASS, release $\mathbf{F}$ and through the arrows set 99 , push $\mathbf{F}$ and visualize Pro (protection code) default is 12, through the arrows set 128 and push $\mathbf{F}$, keep it pushed until all parameters InF, CFG, InP, Out, PASS are visualized.

| CFG |  |
| :--- | :--- |
| S.tun | 0 |
| hPb | 1,2 |
| hlt | 5,83 |
| hdt | 1,33 |
| $\ldots$ |  |


| InP |  |
| :--- | :--- |
| $\ldots \ldots$ | $30($ Pt100) |
| tyP | 1 (decimals num.) |
| $\ldots$ | 0 (min. sensor scale) |
| dP_S | 850,0 (max sensor scale) |
| Lo.S | 0 (offset of input correction) |
| Hi.S | 30,0 (lower set-point range limit) |
| oFS | 130,0 (upper set-point range limit) |
| Lo.L |  |
| Hi.L |  |


| Out | 0 |
| :--- | :--- |
| A1.r |  |
| $\ldots$ | 3 (operating mode AL1 =inverse-relative-normal) |
| A1.t |  |
| $\ldots$ | 2 (AL1) |
| rL. 1 | 18 (open) |
| rL.2 | 19 (close) |
| rL.3 | 0 |
| rEL | 9 (type of servocontrol command) |
| A.ty | 12 (servocontrol running time: SQN72.4.../STA12.. $=12 ;$ |
| Ac.t | SQM40.265=30) |
| t_Lo | 2 |
| t_Hi | 0.0 |
| t.on | 2 |
| t.oF | 0.0 |
| dE.b | 0,1 (dead zone in \% of end scale) |
|  |  |


| PAS | 99 then push and keep pushed F until visualization of Hrd |
| :--- | :--- |
|  |  |
| Hrd |  |
| $\ldots$ | 6 (PID warm) |
| CtrL | 1 |
| AL.nr | 1 |
| but | 0 |
| diSP | 1 |
| Ld. 1 | 28 |
| Ld. 2 | 20 |
| Ld.3 |  |

Keep pushed $\mathbf{F}$ until you visualize PASS, release $\mathbf{F}$ and through the arrows set 99, push $F$ and visualize Pro (protection code) from 128, through the arrows, bring it back to 12, and keep F pushed until you come back to set-point value.

## Manual operation :

Keep pushed the lower left key for at least 5 sec .
The instrument will enter the "MAN" mode (see also "Ld1" switching on).
Through the arrows, "Open" and "Close" outputs are activated.
To come back to normal working keep the lower left key pushed for at least 5 sec.

## Software switch off :

By keeping pushed keys Arrow up + F for more than 5 sec . the instrument switches off the software, does not command the outputs and visualize only the variable of process measured by the probe.
To restore keep pushed $\mathbf{F}$ for more than 5 sec.

## Set up for temperature probe Pt100 for high temperature ( $350^{\circ} \mathrm{C}$ max.)

Verify wiring of the sensor


Regulation of the set-point $=\mathbf{8 0}$
It can be modified by using arrows "up" and "down".
By pushing F you go to parameters:

| Hy.P | 10 (hysteresis positive for output 1 terminals 21-22 (ex Q13-Q14) |
| :--- | :--- |
| Hy.n | -5 (hysteresis negative for output 1 terminals 21-22 (ex Q13-Q14) |

Keep pushing F until you see PASS, release F and through the arrows set 99, push F and visualize Pro (protection code) default is 12, through the arrows set 128 and push $F$, keep it pushed until all parameters InF, CFG, InP, Out, PASS are visualized.

| CFG | 0 |
| :--- | :--- |
| S.tun | 1,2 |
| hPb | 5,83 |
| hlt | 1,33 |
| hdt |  |
| $\ldots$ |  |


| InP |  |
| :--- | :--- |
| $\ldots \ldots$ | $30($ Pt100 $)$ |
| tyP | 1 (decimals num.) |
| $\ldots$ | 0 (min. sensor scale) |
| dP_S | 850,0 (max sensor scale) |
| Lo.S | 0 (offset of input correction) |
| Hi.S | 0,0 (lower set-point range limit) |
| oFS | 350,0 (upper set-point range limit) |
| Lo.L |  |
| Hi.L |  |


| Out |  |
| :--- | :--- |
| A1.r | 0 |
| $\ldots$ | 3 (mode AL1 =inverse-relative-normal) |
| A1.t |  |
| $\ldots$ | 2 (AL1) |
| r.. 1 | 18 (open) |
| rL.2 | 19 (close) |
| rL.3 | 0 |
| rEL | 9 (type of servocontrol command) |
| A.ty | 12 (servocontrol running time: SQN72.4.../STA12.. $=12 ;$ |
| Ac.t | SQM40.265=30) |
| t_Lo | 2 |
| t_Hi | 0.0 |
| t.on | 2 |
| t.oF | 0.0 |
| dE.b | 0,1 (dead zone in $\%$ of end scale) |


| PAS | 99 then push and keep pushed F until visualization of Hrd |
| :--- | :--- |
|  |  |
| Hrd |  |
| $\ldots$ | 6 (PID warm) |
| CtrL | 1 |
| AL.nr | 1 |
| but | 0 |
| diSP | 1 |
| Ld. 1 | 28 |
| Ld. 2 | 20 |
| Ld. 3 |  |

Keep pushed $\mathbf{F}$ until you visualize PASS, release $\mathbf{F}$ and through the arrows set 99 , push $F$ and visualize Pro (protection code) from 128, through the arrows, bring it back to 12, and keep F pushed until you come back to set-point value.

## Manual operation:

Keep pushed the lower left key for at least 5 sec .
The instrument will enter the "MAN" mode (see also "Ld1" switching on).
Through the arrows, "Open" and "Close" outputs are activated.
To come back to normal working keep the lower left key pushed for at least 5 sec .

## Software switch off :

By keeping pushed keys Arrow up + F for more than 5 sec. the instrument switches off the software, does not command the outputs and visualize only the variable of process measured by the probe.
To restore keep pushed $\mathbf{F}$ for more than 5 sec.

## Set up for pressure transmitter 2 wires signal $4 \div 20 \mathrm{~mA}$



With pressure transmitters first we need to enable their power supply: remove the part as shown below, then, on the CPU unit, move the bridge from Pt100 to +Vt


Verify wiring of the sensor
Impostazione set-point

| Transmitter | 1,6bar | 3bar | 10bar | 16bar | 25bar | 40bar |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Set-point | 1 bar | $1,5 \mathrm{bar}$ | 6 bar | 6 bar | 6 bar | 6bar |

To modify it directly use "up" and "down" arrows.
By pushing F you go to parameter:

| Transmitter | 1,6bar | 3bar | 10bar | 16bar | 25bar | 40bar |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Hy.P | 0,2bar | $0,5 \mathrm{bar}$ | $0,5 \mathrm{bar}$ | $0,8 \mathrm{bar}$ | $1,25 \mathrm{bar}$ | 2bar |
| Hy.n | Obar | Obar | Obar | Obar | Obar | Obar |

Keep pushing F until you see PASS, release F and through the arrows set 99, push F and visualize Pro (protection code) default is 12, through the arrows set 128 and push $F$, keep it pushed until all parameters InF, CFG, InP, Out, PASS are visualized.

| CFG | 0 |
| :--- | :--- |
| S.tun | 5 |
| hPb | 1,33 |
| hlt | 0,33 |
| hdt |  |
| $\ldots$ |  |


| InP |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\ldots$ |  |  |  |  |  |  |  |
| tyP |  |  | $44(4 \div 20 \mathrm{~mA})$ |  |  |  |  |
| $\ldots$ |  |  | ( |  |  |  |  |
| dP_S |  |  | 2 (decimals num.) |  |  |  |  |
|  |  |  |  |  |  |  |  |
| Transmitter | 1,6bar | 3bar | 10bar | 16bar | 25bar | 40bar |  |
| Lo.S | 0,00 | 0,00 | 0,00 | 0,00 | 0,00 | 0,00 | min. sensor scale |
| Hi.S | 1,60 | 3,00 | 10,00 | 16,00 | 25,00 | 40,00 | max sensor scale |
| oFS | 0 | 0 | 0 | 0 | 0 | 0 | offset of input correction |
| Lo.L | 0,00 | 0,00 | 0,00 | 0,00 | 0,00 | 0,00 | lower set-point setting |
| Hi.L | 1,60 | 3,00 | 10,00 | 16,00 | 25,00 | 40,00 | upper set-point setting |


| Out |  |
| :--- | :--- |
| A1.r | 0 |
| $\ldots$ | 3 (mode AL1 =inverse-relative-normal) |
| A1.t |  |
| $\ldots$ | 2 (AL1) |
| rL.1 | 18 (open) |
| rL.2 | 19 (close) |
| rL.3 | 0 |
| rEL | 9 (type of servocontrol command) |
| A.ty | 12 (servocontrol running time: SQN72.4.../STA12.. $=12 ;$ |
| Ac.t | SQM40.265=30) |
| t_Lo | 2 |
| t_Hi | 0.0 |
| t.on | 2 |
| t.oF | 0.0 |
| dE.b | 0,1 (dead zone in \% of end scale) |


| PAS | 99 then push and keep pushed F until visualization of Hrd |
| :--- | :--- |
|  |  |
| Hrd |  |
| $\ldots$ | 6 (PID warm) |
| CtrL | 1 |
| AL.nr | 1 |
| but | 0 |
| diSP | 1 |
| Ld. 1 | 28 |
| Ld.2 | 20 |
| Ld.3 |  |

Keep pushed F until you visualize PASS, release F and through the arrows set 99, push F and visualize Pro (protection code) from 128, through the arrows, bring it back to 12, and keep F pushed until you come back to set-point value.

## Manual operation:

Keep pushed the lower left key for at least 5 sec.
The instrument will enter the "MAN" mode (see also "Ld1" switching on).
Through the arrows, "Open" and "Close" outputs are activated.
To come back to normal working keep the lower left key pushed for at least 5 sec.

## Software switch off :

By keeping pushed keys Arrow up + F for more than 5 sec. the instrument switches off the software, does not command the outputs and visualize only the variable of process measured by the probe.
To restore keep pushed $\mathbf{F}$ for more than 5 sec.

## Set -up for thermocouples type $K_{\text {or }} \mathbf{J}$

Verify wiring of the sensor

| Function indicators Indicates modes of operation | CINICHS CIE enfigas 600 V | Indication of output states OUT 1 (AL1); OUT 2 (OPEN); OUT 3 (CLOSED) |
| :---: | :---: | :---: |
| L1 MAN/AUTO $=$ OFF (automatic control) |  |  |
| ON (manual control) |  | PV Display. Indication of process variable Error Indication: LO, HI, Sbr, Err <br> $L O=$ the value of process variable is $<$ di LO_S <br> $H I=$ the value of process variable is $>$ di HI_S <br> Sbr= faulty sensor or input values higher than max. limits <br> Err= PT100 third wire opened for PT100, PTC or input <br> values lower than min. limits (i.e.: TC wrong connection) |
| L2 PRE-HEATING $=$ ON (running) |  |  |
| L3 $\quad$ SELFTUNING $=\mathrm{ON}$ (enabled Self) OFF (disabled Self) |  |  |
| Automatic/Manual adjustment selection Active only when PV display visualises the process variable (button pressed for at least 5 sec .) |  |  |
|  |  | SV display: Indication of setpoint |
|  |  | Function key <br> Gives access to the various configuration phases .. Confirms change of set parameters and browses next or previous parameter (if Auto/Man key is pressed) |
| "Inc" and "Dec" key <br> Press to increment (decrement) any numerical parameter $\boldsymbol{\bullet}$ Increment (decrement) speed is proportional to time key stays pressed •• The operation is not cyclic: once the maximum (minimum) value of a field is reached, the value will not change even if the key remains pressed. |  |  |

Regulation of the set-point $=\mathbf{8 0}$
It can be modified by using arrows "up" and "down".
By pushing F you go to parameters:

| Hy.P | 10 (hysteresis positive for output 1 terminals 21-22 (ex Q13-Q14) |
| :--- | :--- |
| Hy.n | -5 (hysteresis negative for output 1 terminals 21-22 (ex Q13-Q14) |

Keep pushing F until you see PASS, release $\mathbf{F}$ and through the arrows set 99 , push $\mathbf{F}$ and visualize Pro (protection code) default is 12, through the arrows set 128 and push $\mathbf{F}$, keep it pushed until all parameters InF, CFG, InP, Out, PASS are visualized.

| CFG | 0 |
| :--- | :--- |
| S.tun | 1,2 |
| hPb | 5,83 |
| hlt | 1,33 |
| hdt |  |
| $\ldots$ |  |


| InP |  |
| :--- | :--- |
| $\ldots$ | 2 (thermocouple $\left.\mathbf{K} 0 \div 1300^{\circ} \mathrm{C}\right) / 0$ (thermocouple $\mathbf{J} 0 \div 1000^{\circ} \mathrm{C}$ ) |
| tyP |  |
| $\ldots$ | 0 (no decimal) $/ 1(1$ decimal) |
| dP_S | 0 (min. sensor scale) |
| Lo.S | 1300 (max sensor scale for tc $\mathbf{K}) / 1000$ (max sensor scale for tc $\mathbf{J}$ ) |
| Hi.S | 0 (offset of input correction) |
| oFS | 0 (lower set-point range limit) |
| Lo.L | 1300 (upper set-point range limit) per tc $\mathbf{K} / 1000$ for tc $\mathbf{J}$ |
| Hi.L |  |


| Out |  |
| :--- | :--- |
| A1.r | 0 |
| $\ldots$ | 3 (mode AL1 =inverse-relative-normal) |
| A1.t |  |
| $\ldots$ | 2 (AL1) |
| rL. 1 | 18 (open) |
| rL.2 | 19 (close) |
| rL.3 | 0 |
| rEL | 9 (type of servocontrol command) |
| A.ty | 12 (servocontrol running time: SQN72.4.../STA12.. $=12 ;$ |
| Ac.t | SQM40.265=30) |
| t_Lo | 2 |
| t_Hi | 0.0 |
| t.on | 2 |
| t.oF | 0.0 |
| dE.b | 0,1 (dead zone in $\%$ of end scale) |


| PAS | 99 then push and keep pushed F until visualization of Hrd |
| :--- | :--- |
|  |  |
| Hrd |  |
| $\ldots$ | 6 (PID warm) |
| CtrL | 1 |
| AL.nr | 1 |
| but | 0 |
| diSP | 1 |
| Ld. | 28 |
| Ld. 2 | 20 |
| Ld.3 |  |

Keep pushed F until you visualize PASS, release F and through the arrows set 99, push F and visualize Pro (protection code) from 128, through the arrows, bring it back to 12, and keep F pushed until you come back to set-point value.

## Manual operation:

Keep pushed the lower left key for at least 5 sec.
The instrument will enter the "MAN" mode (see also "Ld1" switching on).
Through the arrows, "Open" and "Close" outputs are activated.
To come back to normal working keep the lower left key pushed for at least 5 sec .

## Software switch off :

By keeping pushed keys Arrow up + F for more than 5 sec. the instrument switches off the software, does not command the outputs and visualize only the variable of process measured by the probe.
To restore keep pushed $\mathbf{F}$ for more than 5 sec .

# MANUAL FOR <br> OPERATION AND <br> CALIBRATION 

## MODULATOR

SIEMENS RWF 40....

## INSTRUMENT MOUNTING

Mount the instrument using the relevant mounts as illustrated in the figure.
To wire the instrument and sensors, follow the instructions given on the burner's wiring diagrams.


## INSTRUMENT FRONTAL PANEL



## INSTRUMENT SETTINGS

The instrument comes with a number of factory settings that are good for $90 \%$ of cases. However, you can set or edit parameters proceeding as follows

## 1. Setting or editing of setpoint value

With the burner switched off (thermostat/pressure switch series contacts open, i.e. terminals 3-4 open), press the PGM key, holding it down for less than 2 sec.. The display at the bottom (green) reads SP1: use the up and down arrows to set the setpoint value on the display at the top (red).

To confirm the value, press the PGM key, then press EXIT to return to normal operation.

## 2. Checking or editing the instrument's PID parameters (table 1 attached)

- Press the PGM key, holding it down for longer than 2 sec.. The code AL appears on the green display whilst the red display reads 0
- reads 0 .
- To change, use the up and down arrows to change the value on the red display.
- To confirm, press PGM and the green display moves on to the next parameter.
- Repeat the previous operations for all parameters.
- To stop, press the EXIT key.
- For a list of PID parameters, see table (1) attached.


## 3. Setting the kind of sensor to be connected to the instrument (table 2 attached)

- With the instrument in normal operating mode, press the PGM key, holding it down for 2 sec.. The instrument enters PID parameter configuration mode, hence press the PGM key for another 2 sec.
- The green display features the code C111 whilst the red display gives the code $\mathbf{9 0 3 0}$.
- Each digit of the code corresponds to a settable parameter
- When the down arrow is pressed, the first digit on the left ( $n^{\circ} 9$ ) on the red display starts flashing. Pressing the up arrow while the digit is flashing, you can change the value according to table (2) attached .
- Once you have edited the value, press the down arrow again and the second digit from the left ( $n^{\circ} 0$ ) starts flashing and so on for all four digits. Press PGM to confirm and EXIT to exit.
Example: temperature sensor, set 9030; pressure sensor, set G030.


## 4. C112 and C113 configurations (tables 3 \& 4 attached) :

Configurations C112 and C113 enable use of an auxiliary contact (terminals Q63-Q64 and LED K6 on the front panel), which is fully configurable.
It also allows you to choose between degrees Celsius ${ }^{\circ} \mathrm{C}$ or Fahrenheit ${ }^{\circ} \mathrm{F}$ and to lock the instrument's keys.
With the instrument in normal operating mode, press the PGM key, holding it down for 2 sec.. The instrument enters PID parameter configuration mode, hence press the PGM key for another 2 sec..
The code C111 appears on the green display whilst the red display reads 9030 . If you press PGM again, the green display reads C112 and the red display reads 0110.
For the instrument to work as standard, the $\mathbf{C 1 1 2}$ configuration should never be altered, whilst the $\mathbf{C 1 1 3}$ configuration should be changed when using pressure sensors or $0-10 \mathrm{~V} / 0.4-20 \mathrm{~mA}$ signals (see table (5) attached).

## 5. Configuring process values:

With the instrument in normal operating mode, press the PGM key for 2 sec.. The instrument enters PID parameter configuration mode. The code C111 appears on the green display, whilst the code 9030 (or different code depending on settings made previously) appears on the red display. If you press PGM again, the code becomes C112 and the red display reads 0010. When you next press PGM, the code becomes C113 and the red display reads 0110 . When you next press PGM, the green display reads SCL (=lower limit [instrument range start] for analogue input 1, valid for signals 0-10V, 0-20mA, 4-20mA, 0-100ohms etc.). Use the up arrow or down arrow to set the chosen value (see table (5) attached).
If you press the PGM key again, the green display reads SCH (=upper limit [instrument range end] for analogue input 1, valid for input signals $0-10 \mathrm{~V}, 0-20 \mathrm{~mA}, 4-20 \mathrm{~mA}, 0-100 \mathrm{ohms}$ etc.). Use the up and down arrow to set the chosen value (see table (5) attached).
Example: for SIEMENS pressure sensor QBE2.. P25 (25bar), the input signal used is 0-10V: set SCL to 0 and SCH to 2500. That way the instrument's scale ranges from 0 to 2500 kPa ( 25 bar ).
Pressing the PGM key repeatedly calls up the following parameters in sequence. These parameters can be edited with the up and down arrows:

SCL2:lower limit for analogue input 2 (same as SCL but for input 2 - factory setting 0);
SCH2:upper limit for analogue input 2 (same as SCH but for input 2 - factory setting 100);
SPL: lower setpoint limit (same as SCL but for setpoint - factory setting 0);
SPH: upper setpoint limit (same as SCH but for setpoint - factory setting 100);
Example: for SIEMENS pressure sensor QBE2.. P25 (25bar), the input signal used is 0-10V: if you want to work between 5 and 19 bar, set SPL to 500 and SPH to 1900 (kPa). That way the setpoint scale can be set between 500 and 1900 kPa (5 and 19 bar).
OFF1:correction for analogue input 1 (factory setting 0 )
OFF2:correction for analogue input 2 (factory setting 0)
OFF3:correction for analogue input 3 (factory setting 0)
HYST:"K6" auxiliary contact differential (factory setting 1)
dF1: delay applied to sensor signal to prevent transients (range 0-100sec.; factory setting 1 sec .)

## 6. Manual control

- To control burner output manually, press the EXIT key for 5 sec . with the burner operating - the LED with the hand symbol lights.
- At this point, use the up arrow and down arrow to increase or decrease burner output.
- To exit manual mode, press the EXIT key.
- NB: Every time the controller switches the burner off (start enabled LED off - Q13-Q14 contact open), manual mode is disabled when the burner is switched back on.


## 7. Instrument self-setting (auto-tuning)

- If the burner in the steady state does not respond properly to heat generator requests, you can activate the instrument's self-setting function, which recalculates PID values for its operation, deciding which are most suitable for the specific kind of request
- To activate this function, proceed as follows:
- Press the PGM key and down arrow at the same time.
- The green display reads tunE and the instrument forces the burner to increase and decrease output.
- During these output oscillations, the instrument calculates the PID parameters (proportional band, integral time, derivative time).
- At the end of calculations, the tunE function switches off automatically and the instrument has stored the new parameters.
- If you want to disable the self-setting function, press the up arrow once it has started.
- PID parameters calculated by the instrument can be edited at any time following the procedure illustrated earlier in point 2.


## Note:

If no key is pressed for $\sim 10$ sec. during the instrument's setting, the instrument automatically exits setting mode and returns to normal operating mode.

## TABLE 1 - "PID" PARAMETERS AND RELEVANT FACTORY SETTINGS

| Parameter | Display | Values range | Factory setting | Remarks |
| :---: | :---: | :---: | :---: | :---: |
| Limit value for auxiliary contact (*) | AL | $\begin{gathered} \text { from -1999 to } 9999 \\ \text { digit } \end{gathered}$ | 0 | Do not alter |
| Auxiliary contact switching differential (*) | HYST | from 0 to 999.9 digit | 1 | Do not alter |
| Proportional band (*) | PB. 1 | from 0.1 to 9999 digit | 10 | Typical value for temperature |
| Derivative action | dt | from 0 to 9999 sec . | 80 | Typical value for temperature |
| Integral action | rt | from 0 to 9999 sec . | 350 | Typical value for temperature |
| Dead band (*) | db | from 0 to 999.9 digit | 1 | Typical value |
| Servocontrol running time | tt | from 10 to 3000 sec . | 15 | Set servocontrol running time |
| Switch-on differential (*) | HYS1 | from 0.0 to -199.9 digit | -5 | Value under setpoint below which the burner switches back on (Q13Q14 closes) |
| Lower switch-off differential (*) | HYS2 | from 0.0 to HYS3 | 3 | Do not alter |
| Upper switch-off differential (*) | HYS3 | from 0.0 to 999.9 digit | 5 | Value over setpoint above which the burner switches off (Q13-Q14 opens) |
| Modulating response threshold | q | from 0.0 to 999.9 | 0 | Do not alter |
| Weather compensation gradient | H | from 0.0 to 4 | 1 | Do not alter |
| Ambient temperature parallel displacement (*) | P | from -90 to +90 | 0 | Do not alter |

(*) Parameters affected by setting of decimal place (C113 configuration 01X0)

TABLE 2 - INPUTS CONFIGURATION C111

| Red display |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Analog input 1 | $1^{\wedge}$ digit | $2^{\wedge}$ digit | $3^{\wedge}$ digit | $4^{\wedge}$ digit |
| Pt100 3 wires | 0 |  |  |  |
| Pt100 22 wires | 1 |  |  |  |
| Ni100 3 wires | 2 |  |  |  |
| Ni100 22 wires | 3 |  |  |  |
| Pt1000 3 wires | 4 |  |  |  |
| Pt 100022 wires | 5 |  |  |  |
| Ni1000 3 wires DIN 43760 | 6 |  |  |  |
| Ni1000 22 wires DIN 43760 | 7 |  |  |  |
| Ni1000 3 wires Siemens | 8 |  |  |  |
| Ni1000 22 wires Siemens | 9 |  |  |  |
| Thermocoupling K NiCr-Ni | A |  |  |  |
| Thermocoupling T Cu-Con | b |  |  |  |
| Thermocoupling N NiCrSil-NiSil | C |  |  |  |
| Thermocoupling J Fe-Con | d |  |  |  |
| Signal $0 \div 20 \mathrm{~mA}$ | E |  |  |  |
| Signal 4 $\div 20 \mathrm{~mA}$ | F |  |  |  |
| Signal $0 \div 10 \mathrm{~V}$ | G |  |  |  |
| Signal $0 \div 1 \mathrm{~V}$ | H |  |  |  |
| Analog input 2 |  |  |  |  |
| none |  | 0 |  |  |
| external set point WFG |  | 1 |  |  |
| external set point $0 \div 20 \mathrm{~mA}$ |  | 2 |  |  |
| external set point $4 \div 20 \mathrm{~mA}$ |  | 3 |  |  |
| external set point $0 \div 10 \mathrm{~V}$ |  | 4 |  |  |
| external set point $0 \div 1 \mathrm{~V}$ |  | 5 |  |  |
| analog shift set-point WFG |  | 6 |  |  |
| analog shift set-point $0 \div 20 \mathrm{~mA}$ |  | 7 |  |  |
| analog shift set-point $4 \div 20 \mathrm{~mA}$ |  | 8 |  |  |
| analog shift set-point $0 \div 10 \mathrm{~V}$ |  | 9 |  |  |
| analog shift set-point $0 \div 1 \mathrm{~V}$ |  | A |  |  |
| Analog input 3 |  |  |  |  |
| none |  |  | 0 |  |
| external themperature sensor Pt 100022 wires |  |  | 1 |  |
| xternal themperature sensor Ni1000 22 wires DIN |  |  | 2 |  |
| xternal themperature sensor Ni1000 22 wires Siemens |  |  | 3 |  |
| Input D2-Logic functions |  |  |  |  |
| none |  |  |  | 0 |
| changeover set-point |  |  |  | 1 |
| V shift set-point |  |  |  | 2 |
| Typical settings |  |  |  |  |
| Siemens sensors QAE2../QAC2../QAM2.. | 9 | 0 | 3 | 0 |
| Factory sensors Pt1000 30 $130{ }^{\circ} \mathrm{C}$ | 5 | 0 | 3 | 0 |
| Factory sensors Pt1000 $0 \div 350{ }^{\circ} \mathrm{C}$ | 5 | 0 | 3 | 0 |
| Pressure probes QBE... 3 wires (signal $0 \div 10 \mathrm{~V}$ ) | G | 0 | 3 | 0 |
| Pressure probes MBS... 2 wires (signal 4 $\mathbf{2} \mathbf{2 0} \mathbf{m A}$ ) | F | 0 | 3 | 0 |
| Probes Pt100 3 wires | 0 | 0 | 3 | 0 |
| Thermocouplings K type | A | 0 | 3 | 0 |
| Signal 4 - 20 mA | F | 0 | 3 | 0 |

TABLE 3 - CONFIGURATION C112

| Red display | $1^{\wedge}$ digit | $2^{\wedge}$ digit | $3^{\wedge}$ digit | $4^{\wedge}$ digit |
| :---: | :---: | :---: | :---: | :---: |
| Auxiliary limit switch K6 |  |  |  |  |
| none | 0 |  |  |  |
| Ik1 function for input 1 | 1 |  |  |  |
| IK2 function for input 1 | 2 |  |  |  |
| Ik3 function for input 1 | 3 |  |  |  |
| Ik4 function for input 1 | 4 |  |  |  |
| Ik5 function for input 1 | 5 |  |  |  |
| Ik6 function for input1 | 6 |  |  |  |
| Ik7 function for input 1 | 7 |  |  |  |
| Ik8 function for input 2 | 8 |  |  |  |
| Ik7 function for input 2 | 9 |  |  |  |
| Ik8 function for input 2 | A |  |  |  |
| Ik7 function for input 3 | b |  |  |  |
| Ik8 function for input 3 | C |  |  |  |
| Type of instrumentoutput control |  |  |  |  |
| 3 points (relay type) |  | 0 |  |  |
| DC $0 \div 20 \mathrm{~mA}$ (*) |  | 1 |  |  |
| DC $4 \div 20 \mathrm{~mA}$ (*) |  | 2 |  |  |
| DC $0 \div 10 \mathrm{~V}{ }^{*}$ ) |  | 3 |  |  |
| Set-point SP1 |  |  |  |  |
| SP1set with keys |  |  | 0 |  |
| SP1 dependent on outside sensor (analogue input 3 must be configured) |  |  | 1 |  |
| Parameter lock |  |  |  |  |
| no keyboard lock |  |  |  | 0 |
| configuration level block |  |  |  | 1 |
| parameters level block PID |  |  |  | 2 |
| total block |  |  |  | 3 |
| Factory settings | 0 | 0 | 1 | 0 |

## Note: (*) for RWF 40.002 only

TABLE 4 - CONFIGURATION C113

| Red display | $1^{\wedge}$ digit | $2^{\wedge}$ digit | $3^{\wedge}$ digit | $4^{\wedge}$ digit |
| :---: | :---: | :---: | :---: | :---: |
| Instrument addresses (for RWF 40.003 only |  |  |  |  |
| address 0 | 0 |  |  |  |
| address 1 | 0 | 1 |  |  |
| address... | ... | $\ldots$ |  |  |
| address 99 | 9 | 9 |  |  |
| Unit of measurement and decimal place |  |  |  |  |
| ${ }^{\circ} \mathrm{C}$ without decimal |  |  | 0 |  |
| ${ }^{\circ} \mathrm{C}$ and 1 decimal |  |  | 1 |  |
| ${ }^{\circ} \mathrm{F}$ without decimal |  |  | 2 |  |
| ${ }^{\circ} \mathrm{F}$ and 1 decimal |  |  | 3 |  |
| Activation of "K6" |  |  |  |  |
| limit contact OFF |  |  |  | 0 |
| limit contact ON |  |  |  | 1 |
| Factory settings | 0 | 1 | 1 | 0 |

TABLE 5 - SUMMARY OF STANDARD PARAMETER SETTINGS

|  | PARAMETERS TO BE EDITED |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SENSORS/PROBES | C111 | C113 | SCL | SCH | SPL | SPH | HYS1 (*) | HYS3 (*) | Pb. 1 | dt | rt | SP1 (*) |
| Siemens QAE2120.010 | 9030 | 0110 | - | - | 30 | 95 | -5 | 5 | 10 | 80 | 350 | $80^{\circ} \mathrm{C}$ |
| Siemens QAM2120.040 | 9030 | 0110 | - | - | 0 | 80 | -2,5 | 2,5 | 10 | 80 | 350 | $40^{\circ} \mathrm{C}$ |
| Pt1000 (130 ${ }^{\circ} \mathrm{C}$ max.) | 5030 | 0110 | - | - | 30 | 95 | -5 | 5 | 10 | 80 | 350 | $80^{\circ} \mathrm{C}$ |
| Pt1000 (350 ${ }^{\circ} \mathrm{C}$ max.) | 5030 | 0110 | - | - | 0 | 350 | -5 | 10 | 10 | 80 | 350 | $80^{\circ} \mathrm{C}$ |
| Pt100 (130 ${ }^{\circ} \mathrm{C}$ max.) | 0030 | 0110 | - | - | 0 | 95 | -5 | 5 | 10 | 80 | 350 | $80^{\circ} \mathrm{C}$ |
| Pt100 (350 ${ }^{\circ} \mathrm{C}$ max) | 0030 | 0110 | - | - | 0 | 350 | -5 | 10 | 10 | 80 | 350 | $80^{\circ} \mathrm{C}$ |
| Termocouple K | A030 | 0110 | - | - | 0 | 1200 | -5 | 20 | 10 | 80 | 350 | $80^{\circ} \mathrm{C}$ |
| Danfoss/Siemens $4 \div 20 \mathrm{~mA} \mathrm{p} \mathrm{1,6}$ bar | F030 | 0100 | 0 | 160 | 0 | 160 | 0 | 20 | 5 | 20 | 80 | 100 kPa |
| Danfoss/Siemens $4 \div 20 \mathrm{~mA} \mathrm{p} 10$ bar | F030 | 0100 | 0 | 1000 | 0 | 1000 | 0 | 50 | 5 | 20 | 80 | 600kPa |
| Danfoss/Siemens $4 \div 20 \mathrm{~mA} \mathrm{p} 16$ bar | F030 | 0100 | 0 | 1600 | 0 | 1600 | 0 | 80 | 5 | 20 | 80 | 600kPa |
| Danfoss/Siemens $4 \div 20 \mathrm{~mA}$ p 25 bar | F030 | 0100 | 0 | 2500 | 0 | 2500 | 0 | 125 | 5 | 20 | 80 | 600kPa |
| Danfoss/Siemens $4 \div 20 \mathrm{~mA} \mathrm{p} 40$ bar | F030 | 0100 | 0 | 4000 | 0 | 4000 | 0 | 200 | 5 | 20 | 80 | 600kPa |
| Siemens QBE2.. P4 | G030 | 0100 | 0 | 400 | 0 | 400 | 0 | 20 | 5 | 20 | 80 | 200 kPa |
| Siemens QBE2.. P10 | G030 | 0100 | 0 | 1000 | 0 | 1000 | 0 | 50 | 5 | 20 | 80 | 600 kPa |
| Siemens QBE2.. P16 | G030 | 0100 | 0 | 1600 | 0 | 1600 | 0 | 80 | 5 | 20 | 80 | 600 kPa |
| Siemens QBE2.. P25 | G030 | 0100 | 0 | 2500 | 0 | 2500 | 0 | 125 | 5 | 20 | 80 | 600 kPa |
| Siemens QBE2.. P40 | G030 | 0100 | 0 | 4000 | 0 | 4000 | 0 | 200 | 5 | 20 | 80 | 600 kPa |
| Signal 0 $\div 10 \mathrm{~V}$ | G030 | to be fixed | to be fixed | to be fixed | to be fixed | to be fixed | to be fixed | to be fixed | 5 | 20 | 80 | to be fixed |
| Signal 4 $\mathbf{~ 2 0 m A ~}$ | F030 | to be fixed | to be fixed | to be fixed | to be fixed | to be fixed | to be fixed | to be fixed | 5 | 20 | 80 | to be fixed |
| tt - servocontrol run | 12 sec. | Servocontro | ol Berger ST | TA12B.../Si | iemens SQN | N30.251/Sie | mens SQN | 72.4A4A20 |  |  |  |  |
| tt - servocontrol run | 13 sec. | Servocontro | ol Berger STA | TA13B... |  |  |  |  |  |  |  |  |
| tt - servocontrol run | 15 sec. | Servocontro | ol Berger ST | TA15B... |  |  |  |  |  |  |  |  |
| tt - servocontrol run | 30 sec. | Servocontro Siemens | ol Siemens QM40. 265 | SQL33.03/S | Siemens | QM10/Siem | ens SQM50 | /Siemens | SQM54 | Bers | STM |  |

## NOTES

(*) $^{*}$ These values are factory set - values must be set during operation at the plant based on the real working temperature/pressure value.

## WARNING

With pressure sensors, parameters SP1, SCH, SCL, HYS1, HYS3 must be selected and displayed in kPa (kilo Pascal).
$(1$ bar $=100,000 \mathrm{~Pa}=100 \mathrm{kPa})$

## Probe electric connection :

With 7 pins connector version


With terminals version


## With external setpoint



C111 configuration code $=\mathrm{X} 1 \mathrm{X} 1$

With setpoint modified by independent management system


C111 configuration code $=\mathrm{X9XX}$
SCH2 $=0.5 x$ (SPH -SPL )
SCL2 $=-0.5 \times(\mathrm{SPH}-\mathrm{SPL})$

Example:
SPH= max. $130^{\circ} \mathrm{C}$
$\mathrm{SPL}=\mathrm{min} .30^{\circ} \mathrm{C}$
SCH2 $=0.5 \times(130-30)=50$
SCL2 $=-0.5 \times(130-30)=-50$

## APPENDIX: PROBES CONNECTION

To assure the utmost comfort, the control system needs reliable information, which can be obtained provided the sensors have been installed correctly.
Sensors measure and transmit all variations encountered at their location.
Measurement is taken based on design features (time constant) and according to specific operating conditions.
With wiring run in raceways, the sheath (or pipe) containing the wires must be plugged at the sensor's terminal board so that currents of air cannot affect the sensor's measurements

## Ambient probes (or ambient thermostats)

## Installation

The sensors (or room thermostats) must be located in reference rooms in a position where they can take real temperature measurements without being affected by foreign factors.


It's good to be admired ...even better to be effective
Heating systems: the room sensor must not be installed in rooms with heating units complete with thermostatic valves. Avoid all sources of heat foreign to the system.


## Location

On an inner wall on the other side of the room to heating units height above floor 1.5 m , at least 1.5 m away from external sources of heat (or cold)


Installation position to be avoided
near shelving or alcoves and recesses, near doors or windows, inside outer walls exposed to solar radiation or currents of cold air, on inner walls with heating system pipes, domestic hot water pipes, or cooling system pipes running through them.


## Outside probes (weather)

## Installation

In heating or air-conditioning systems featuring adjustment in response to outside temperature, the sensor's positioning is of paramount importance.


General rule: on the outer wall of the building where the living rooms are, never on the south-facing wall or in a position where they will be affected by morning sun. If in any doubt, place them on the north or north-east façade

Positions to be avoided


Avoid installing near windows, vents, outside the boiler room, on chimney breasts or where they are protected by balconies, cantilever roofs.
The sensor must not be painted (measurement error).

## Duct or pipe sensors

## Installing temperature sensors

For measuring outlet air:

- after delivery fan or
- after coil to be controlled, at a distance of at least $0,5 \mathrm{~m}$

For measuring room temperature:

- before return air intake fan and near room's return air intake. For measuring saturation temperature: after mist eliminator.


Bend 0.4 m sensor by hand (never use tools) as illustrated.


Use whole cross-section of duct, min. distance from walls 50 mm , radius of curvature 10 mm for 2 m or 6 m sensors.

## Installing pressure sensors

A - installation on ducts carrying fluids at max. temperature $80^{\circ} \mathrm{C}$
B - installation on ducts at temperature over $80^{\circ} \mathrm{C}$ and for refrigerants
C - installation on ducts at high temperatures:

- increase length of siphon
- place sensor at side to prevent it being hit by hot air coming from the pipe.


Installing differential pressure sensors for water

- Installation with casing facing down not allowed.-With temperature over $80^{\circ} \mathrm{C}$, siphons are needed
- To avoid damaging the sensor, you must comply with the following instructions


## when installing:

- make sure pressure difference is not greater than the value permitted by the sensor
- when there are high static pressures, make sure you insert shutoff valves A-B-C.


## Putting into operation

start disable
1=open C1=open C
$2=$ open A2=close $B$
3=open B3=close A
4= close C

## Installing combined humidity sensors

As max. humidity limit sensor on outlet (steam humidifiers).




Placing the probes (QAD22.../QAE21.../QAP21.../RCA...)

## With pumps on outlet

with 3 ways valves / with 4 ways valves


## With pumps on return

with 3 ways valves / with 4 ways valves


## Immersion probes mounting

Sensors must be installed on the stretch of pipe in which fluid circulates all the time.
The rigid stem (sensing element doing the measuring) must be inserted by at least 75 mm and must face the direction of flow.
Recommended locations: on a bend or on a straight stretch of pipe but tilted by $45^{\circ}$ and against the flow of fluid.
Protect them to prevent water from infiltrating (dripping gates, condensation from pipes etc.)

## Installing QAD2.. strap-on sensors

Make sure fluid is circulating in the chosen location.
Eliminate insulation and paintwork (including rust inhibitor) on a min. 100 mm length of pipe.
Sensors come with straps for pipes up to 100 mm in diameter

## Strap-on or immersion sensors?

## QAD2.. strap-on sensors

Advantages

- 10 sec . time constant
- Installed with system running (no plumbing work)
- Installation can be changed easily if it proves incorrect.

Limits:
Suitable for pipe diameters max. 100 mm

- Can be affected by currents of air etc.

QAE2... immersion sensors
Advantages

- Measure "mean" fluid temperature
- No external influence on measurement such as: currents of air, nearby pipes etc.


## Limits

- Time constant with sheath: 20 sec .
- Hard to change installation position if it proves incorrect.

Duct pressure switches and sensors
Installing differential pressure probes for air


A - Control a tilter (Clogging)


B - Control a tan (upstream/downstream)


C - Measurement of difterence in pressure between two ducts

$-(+)$
D - Measurement of difference in pressure between two rooms or of inside of duct and outside

Pressure probes connection Siemens QBE 2...P... to burner's terminal block

## SONDA DI PRESSIONE PRESSURE SENSOR SONDE DE PRESSION

MORSETTIERA BRUCIATORE BURNER TERMINAL BLOCK BORNIER DU BRÛLEUR


## Spare parts

| Description | Code |
| :---: | :---: |
| Modulator RWF40.000 | 2570112 |
| Adapting frame Siemens ARG40 from RWF32.. to RWF40.. | 2570113 |
| Temperature probe Siemens QAE2120.010A ( $30 \div 130^{\circ} \mathrm{C}$ ) | 2560101 |
| Temperature probe Siemens QAM2120.040 (-15 $\left.\div+50^{\circ} \mathrm{C}\right)$ | 2560135 |
| Thermoresistor Pt1000 $\varnothing=6 \mathrm{~mm} \mathrm{~L}=100 \mathrm{~mm}\left(30 \div 130^{\circ} \mathrm{C}\right)$ | 2560188 |
| Thermoresistor Pt1000 $\varnothing=10 \mathrm{~mm} \mathrm{~L}=200 \mathrm{~mm}\left(0 \div 350^{\circ} \mathrm{C}\right)$ | 2560103 |
| Pressure probe Siemens QBE2.. P4 (0ㄴ4bar) | 2560159 |
| Pressure probe Siemens QBE2.. P10 (0 $\div 10 \mathrm{bar} /$ signal $0 \div 10 \mathrm{~V}$ ) | 2560160 |
| Pressure probe Siemens QBE2.. P16 (0 $\div 16 \mathrm{bar} /$ signal $0 \div 10 \mathrm{~V})$ | 2560167 |
| Pressure probe Siemens QBE2.. P25 (0%25bar/ signal 0 $\div 10 \mathrm{~V}$ ) | 2560161 |
| Pressure probe Siemens QBE2.. P40 (0 $\div 40 \mathrm{bar} /$ signal $0 \div 10 \mathrm{~V}$ ) | 2560162 |
| Pressure probe Danfoss MBS3200 p 1,6 (0 $\div 1,6 \mathrm{bar} /$ segnale 4 $\div 20 \mathrm{~mA}$ ) | 2560189 |
| Pressure probe Danfoss MBS3200 p 10 (0 $\div 10 \mathrm{bar} /$ segnale $4 \div 20 \mathrm{~mA}$ ) | 2560190 |
| Pressure probe Danfoss MBS3200 p 16 (0 $\div 16 \mathrm{bar} /$ segnale $4 \div 20 \mathrm{~mA}$ ) | 2560191 |
| Pressure probe Danfoss MBS3200 p 25 (0 $\div 25$ bar / segnale 4 $\div 20 \mathrm{~mA}$ ) | 2560192 |
| Pressure probe Danfoss MBS3200 p 40 (0 $\div 40$ bar / segnale $4 \div 20 \mathrm{~mA}$ ) | 2560193 |
| Pressure probe Siemens 7MF1564-3BB00-1AA1 ( $0 \div 1,6 \mathrm{bar} /$ segnale $4 \div 20 \mathrm{~mA}$ ) | 25601A3 |
| Pressure probe Siemens 7MF1564-3CA00-1AA1 ( $0 \div 10 \mathrm{bar}$ / segnale $4 \div 20 \mathrm{~mA}$ ) | 25601A4 |
| Pressure probe Siemens 7MF1564-3CB00-1AA1 ( $0 \div 16 \mathrm{bar}$ / segnale 4 $\div 20 \mathrm{~mA}$ ) | 25601A5 |
| Pressure probe Siemens 7MF1564-3CD00-1AA1 ( $0 \div 25 \mathrm{bar}$ / segnale 4 $\div 20 \mathrm{~mA}$ ) | 25601A6 |
| Pressure probe Siemens 7MF1564-3CE00-1AA1 ( $0 \div 40 \mathrm{bar}$ / segnale 4 $\div 20 \mathrm{~mA}$ ) | 25601A7 |
| Thermocoupling type $\mathrm{K} \varnothing=10 \mathrm{~mm} \mathrm{~L}=200 \mathrm{~mm}\left(0 \div 1200^{\circ} \mathrm{C}\right)$ | 2560142 |
| Thermoresistor Pt100 $\varnothing=10 \mathrm{~mm} \mathrm{~L}=200 \mathrm{~mm}\left(0 \div 350^{\circ} \mathrm{C}\right)$ | 2560145 |

## RWF50.2x \& RWF50.3x



## DEVICE INSTALLATION

Install the device using the relevant tools as shown in the figure.
To wire the device and sensors, follow the instructions on the burner wiring diagram.


## FRONT PANEL



## NAVIGATION MENU



RWF5 is preset good for $90 \%$ of applications. However, you can set or edit parameters as follow:

## Set-point: set or modification:

When the burner is in stand-by, (safety loop open, that is terminals $3-4 / \mathrm{T} 1-\mathrm{T} 2$ on the 7 pole plug open) push the Enter button: on the lower display (green) Opr appears; push Enter again and in the same display SP1 appears. Push Enter again and the lower display (green SP1) flashes. Using the up and down arrows change the set-point on the upper display (red).Push Enter to confirm and push ESC more times to get the home position.

PID parameters set and modifications (see table below):

- Push Enter button, on the green display Opr appears; using the down arrow, scroll until group PArA is reached and push Enter.
- on the green display Pb1 e appears and on the red one the set parameter
- Push is sequence the down or up arrow the menu is scrolled.
- Push Enter to select and the arrows to choose the desired value. Enter to confirm.

| Parameter | Display | Range | Factory <br> setting | Remarks |
| :---: | :---: | :---: | :---: | :---: |
| Proportional band | PB.1 | $1 \ldots 9999$ digit | 10 | Typical value for temperature |
| Derivative action | dt | $0 \ldots 9999$ sec. | 80 | Typical value for temperature |
| Integral action | rt | $0 \ldots 9999$ sec. | 350 | Typical value for temperature |

(*)Parameters affected by setting of decimal place (ConF > dISP parameter dECP)

Setting the kind of sensor to be connected to the device:

- push the Enter button: on the lower display (green) Opr appears. Using the up and down arrows find ConF. Push Enter to confirm.
- Now on the green display the group InP appears. Push Enter and InP1 is displaied. Enter to confirm.
- You are inside InP1; the green display shows Sen1 (sensor type), while the red display shows the chosen sensor code
- Push Enter to enter the Sen1 parameter, then choose the desired sensor using the arrows. Push Enter to confirm and ESC to escape.
- Once selected the sensor, you can modify all the other parameters using up and down arrows according to the tables here below.


## ConF > InP > $\operatorname{lnP1}$

| Parameter | Value | Description |
| :---: | :---: | :---: |
| SEn1 type of sensor for analog input 1 | 1 | Pt100 3 fili |
|  | 2 | Pt100 2 fili |
|  | 3 | Pt1000 3 fili |
|  | 4 | Pt1000 2 fili |
|  | 5 | Ni1000 3 fili |
|  | 6 | Ni1000 2 fili |
|  | 7 | $0 \div 135$ ohm |
|  | 15 | $0 \div 20 \mathrm{~mA}$ |
|  | 16 | $4 \div 20 \mathrm{~mA}$ |
|  | 17 | $0 \div 10 \mathrm{~V}$ |
|  | 18 | $0 \div 5 \mathrm{~V}$ |
|  | 19 | $1 \div 5 \mathrm{~V}$ |
| OFF1 <br> sensor offset | -1999..0.. +9999 | Using the measured value correction (offset), a measured value can be corrected to a certain degree, either up or down |
| $\begin{aligned} & \text { SCL1 } \\ & \text { scale low level } \end{aligned}$ | -1999..0.. +9999 | In the case of a measuring transducer with standard signal, the physical signal is assigned a display value here (for input ohm, mA, V) |
| $\mathrm{SCH} 1$ <br> scale high level | -1999..100.. +9999 | In the case of a measuring transducer with standard signal, the physical signal is assigned a display value here (for input ohm, mA, V) |
| dF1 digital filter | 0...0,6... 100 | Is used to adapt the digital 2nd order input filter (time in s; $0 \mathrm{~s}=$ filter off) |
| Unit temperature unit | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ | $1=$ degrees Celsius $2=$ degrees Fahrenheit |

(bold = factory settings)

## Remark:

RWF50.2 e RWF50.3 cannot be connected to thermocouples.
If thermocouples have to be connected, convert the signal to a 4-20 mA one and set the RWF accordingly.

ConF > Cntr

| Parameter | Value | Description |
| :---: | :---: | :---: |
| CtYP <br> controller type | $\begin{aligned} & 1 \\ & 2 \\ & \hline \end{aligned}$ | 1 = 3-position controller (open-stop-close only RWF50.2) <br> 2 = continuative action controller (only RWF50.3) |
| CACt control action | $\begin{aligned} & \hline 1 \\ & 0 \\ & \hline \end{aligned}$ | 1 = heating controller <br> $0=$ cooling controller |
| SPL <br> least value of the set-point range | -1999..0..+9999 | set-point limitation prevents entry of values outside the defined range |
| SPH maximum value of the set-point range | -1999..100..+9999 | set-point limitation prevents entry of values outside the defined range |
| olLo <br> set-point limitation start, operation limit low | -1999.... +9999 | lower working range limit |
| oLHi <br> set-point limitation end, operation limit high | -1999.... +9999 | upper working range limit |

(bold = factory settings)

## ConF > rAFC

Activation boiler shock termic protetion:
RWF50.. can activate the thermal shock protection only on sites where the set-point is lower than $250^{\circ} \mathrm{C}$ and according to rAL parameter.

| Parameter | Value | Description |
| :---: | :---: | :---: |
| FnCT function | $\begin{aligned} & 0 \\ & 1 \\ & 2 \\ & \hline \end{aligned}$ | Choose type of range degrees/time $0=$ deactivated <br> 1 = Kelvin degrees/minute <br> 2 = Kelvin degrees/hour |
| rASL ramp rate | 0,0 ... 999,9 | Slope of thermal shock protection (only with functions 1 and 2) |
| toLP tolerance band ramp | 0...9999 | width of tolerance band (in K) about the set-point 0 = tolerance band inactive |
| rAL ramp limit | 0... 250 | Ramp limit. When this value is lower than the temperature setpoint, the RWF controls the output increasing the temp set point step by step according to rASL. If this is over the temp set point, the control is performed in cooling. |

(bold = factory settings)

ConF > OutP (parameter under group only for RWF50.3)

| Parameter | Value | Description |
| :---: | :---: | :---: |
| FnCt tipo di controllo | $\begin{array}{r} 1 \\ 4 \\ \hline \end{array}$ | 1 = analog input 1 doubling with possibility to convert (depending on par SiGn) <br> $4=$ modulation controller |
| SiGn type of output signal | $\begin{aligned} & 0 \\ & 1 \\ & 2 \end{aligned}$ | $\begin{aligned} & \text { physical output signal (terminals A+, A-) } \\ & 0=0 \div 20 \mathrm{~mA} \\ & 1=4 \div 20 \mathrm{~mA} \\ & 2=0 \div 10 \mathrm{~V} \end{aligned}$ |
| rOut <br> Value when out of input range | 0... 101 | signal (in percent) when measurement range is crossed |
| oPnt zero point | -1999...0..+9999 | value range of the output variable is assigned to a physical output signal Per default, the setting corresponds to $0 . . .100 \%$ angular positioning for the controller outputs (terminals A+, A-) (effective only with $\mathrm{FnCt}=1$ ) |
| End End value | -1999...100..+9999 | value range of the output variable is assigned to a physical output signal Per default, the setting corresponds to $0 . . .100 \%$ angular positioning for the controller outputs (terminals A+, A-) (effective only with $\mathrm{FnCt}=1$ ) |

(bold = factory settings)

## ConF > binF

| Parameter | Value | Description |
| :--- | :--- | :--- |
| bin1 |  | 0 = without function |
| digital inputs |  | 1 = set-point changeover (SP1 / SP2) |
| (terminals DG - D1) | 0 | 2 = set-point shift (Opr > dSP parameter = value of set-point |
|  | 1 | modify) |
|  | 2 | $4=$ changeover of operating mode |
|  | 4 | open - modulating operation; |
|  | close -2 stage operation. |  |

(bold = factory settings)
ConF > dISP

| Parameter | Value | Description |
| :---: | :---: | :---: |
| diSU upper display (red) | $\begin{aligned} & 0 \\ & 1 \\ & 4 \\ & 6 \\ & 7 \end{aligned}$ | display value for upper display: <br> 0 = display power-off <br> 1 = analog input value <br> 4 = Controller's angular positioning <br> $6=$ set-point value <br> 7 = end value with thermal shock protection |
| diSL lower display (green) | $\begin{aligned} & 0 \\ & 1 \\ & 4 \\ & 6 \\ & 7 \end{aligned}$ | display value for lower display: <br> 0 = display power-off <br> 1 = analog input value <br> 4 = Controller's angular positioning <br> 6 = set-point value <br> 7 = end value with thermal shock protection |
| tout timeout | 0..180.. 250 | time (s) on completion of which the controller returns automatically to the basic display, if no button is pressed |
| dECP decimal point | $\begin{aligned} & 0 \\ & 1 \\ & 2 \\ & \hline \end{aligned}$ | $0=$ no decimal place <br> 1 = one decimal place <br> 2 = two decimal places |
| CodE level lockout | $\begin{aligned} & 0 \\ & 1 \\ & 2 \\ & 3 \end{aligned}$ | 0 = no lockout <br> 1 = configuration level lockout (ConF) <br> 2 = Parameter and configuration level lockout (PArA \& ConF) <br> 3 = keyboard lockout |

(bold = factory settings)

## Manual control :

- in order to manual change the burner load, while firing keep pushing the ESC button for more than 5 s ; on the lower green display Hand appears.
- using the UP and DOWN arrows, the load varies.
- Keep pushing the ESC button for getting the normal operation again.
- NB: every ime the device shuts the burner down (start led switched off - contact $1 \mathrm{~N}-1 \mathrm{P}$ open), the manual control is not active.


## Device self-setting (auto-tuning):

If the burner in the steady state does not respond properly to heat generator requests, you can activate the Device's self-setting function, which recalculates PID values for its operation, deciding which are most suitable for the specific kind of request


Follow the below instructions:
push the UP and DOWN arrows for more than 5 s ; on the green lower display TUNE appears. Now the device pushes the burner to increase and decrease its output. During this time, the device calculates PID parameters ( $\mathbf{P b 1}$, $\mathbf{d t}$ and $\mathbf{r t}$ ). After the calculations, the TUNE is automatically deactivated and the device has already stored them. In order to stop the Auto-tuning function while it works, push again the UP and DOWN arrows for more than 5 s . The calculated PID parameters can be manually modified following the previously described instructions.

## Display of software version :

## SIEMENS



The software version is shown by pushing Enter + UP arrow on the upper display

## Electric connection :



Matches terminals between RWF50.2 and RWF40.0x0

| SIEMENS RWF50.2 |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | $\begin{aligned} & K Q \\ & \varnothing \end{aligned}$ | $\begin{aligned} & \text { K2 } \\ & \varnothing \end{aligned}$ | $\begin{aligned} & \text { K3 } \\ & \varnothing \end{aligned}$ | $\begin{aligned} & 1 \mathrm{~N} \\ & \varnothing \end{aligned}$ | $\begin{aligned} & 1 P \\ & \varnothing \end{aligned}$ | $\varnothing$ | $\stackrel{N}{\varnothing}$ | G- | $\stackrel{G+}{\varnothing}$ | $\begin{aligned} & 13 \\ & \varnothing \end{aligned}$ | $\begin{aligned} & 12 \\ & \varnothing \end{aligned}$ | $\begin{aligned} & 11 \\ & \varnothing \end{aligned}$ |


| SIEMENS RWF40.0x0 |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\begin{aligned} & Y 1 \\ & \varnothing \end{aligned}$ | $\begin{aligned} & Y 2 \\ & \varnothing \end{aligned}$ | $\begin{aligned} & \text { Q13 } \\ & \varnothing \end{aligned}$ | $\begin{aligned} & \text { Q14 } \\ & \varnothing \end{aligned}$ | $\begin{aligned} & \mathrm{L} 1 \\ & \varnothing \end{aligned}$ | $\stackrel{N}{\varnothing}$ | $\begin{aligned} & \mathrm{TE} \\ & \varnothing \end{aligned}$ | $\begin{aligned} & \mathrm{U1} \\ & \varnothing \end{aligned}$ | $\varnothing$ | $\varnothing$ | $\begin{aligned} & \text { M1 } \\ & \varnothing \end{aligned}$ | $\begin{aligned} & 11 \\ & \varnothing \end{aligned}$ | $\begin{aligned} & \mathrm{G} 1+ \\ & \varnothing \end{aligned}$ |

Parameters summarising for RWF50.2x:

| Navigation menù | Conf |  |  |  |  | Conf |  |  | PArA |  |  |  |  |  | Opr |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Inp |  |  |  |  | Cntr |  | diSP |  |  |  |  |  |  |  |
|  | Inp1 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Types of probe | SEn1 | OFF1 | SCL1 | SCH1 | Unit | SPL | SPH | dECP | Pb. 1 | dt | rt | tt | HYS1 (*) | HYS3 (*) | SP1 (*) |
| Siemens QAE2120... | 6 | 0 | needless | needless | 1 | 30 | 95 | 1 | 10 | 80 | 350 | (\#) | -5 | 5 | $80^{\circ} \mathrm{C}$ |
| Siemens QAM2120.. | 6 | 0 | needless | needless | 1 | 0 | 80 | 1 | 10 | 80 | 350 | (\#) | -2,5 | 2,5 | $40^{\circ} \mathrm{C}$ |
| Pt1000 ( $130^{\circ} \mathrm{C}$ max.) | 4 | 0 | needless | needless | 1 | 30 | 95 | 1 | 10 | 80 | 350 | (\#) | -5 | 5 | $80^{\circ} \mathrm{C}$ |
| Pt1000 (350 ${ }^{\circ} \mathrm{C}$ max.) | 4 | 0 | needless | needless | 1 | 0 | 350 | 1 | 10 | 80 | 350 | (\#) | -5 | 10 | $80^{\circ} \mathrm{C}$ |
| Pt100 ( $130^{\circ} \mathrm{C}$ max.) | 1 | 0 | needless | needless | 1 | 0 | 95 | 1 | 10 | 80 | 350 | (\#) | -5 | 5 | $80^{\circ} \mathrm{C}$ |
| Pt100 $\left(350^{\circ} \mathrm{C}\right.$ max) | 1 | 0 | needless | needless | 1 | 0 | 350 | 1 | 10 | 80 | 350 | (\#) | -5 | 10 | $80^{\circ} \mathrm{C}$ |
| Probe $4 \div 20 \mathrm{~mA} \mathrm{/} \mathrm{0} ~ 1 ~ 1,6 \mathrm{bar}$ | 16 | 0 | 0 | 160 | needless | 0 | 160 | 0 | 5 | 20 | 80 | (\#) | 0 | 20 | 100 kPa |
| Probe $4 \div 20 \mathrm{~mA} / 0 \div 3 \mathrm{bar}$ | 16 | 0 | 0 | 300 | needless | 0 | 300 | 0 | 5 | 20 | 80 | (\#) | 0 | 20 | 200 kPa |
| Probe $4 \div 20 \mathrm{~mA} / 0 \div 10 \mathrm{bar}$ | 16 | 0 | 0 | 1000 | needless | 0 | 1000 | 0 | 5 | 20 | 80 | (\#) | 0 | 50 | 600 kPa |
| Probe $4 \div 20 \mathrm{~mA} / 0 \div 16 \mathrm{bar}$ | 16 | 0 | 0 | 1600 | needless | 0 | 1600 | 0 | 5 | 20 | 80 | (\#) | 0 | 80 | 600 kPa |
| Probe $4 \div 20 \mathrm{~mA} / 0 \div 25$ bar | 16 | 0 | 0 | 2500 | needless | 0 | 2500 | 0 | 5 | 20 | 80 | (\#) | 0 | 125 | 600 kPa |
| Probe 4 $\div 20 \mathrm{~mA} \mathrm{/} \mathrm{0} ~+40$ bar | 16 | 0 | 0 | 4000 | needless | 0 | 4000 | 0 | 5 | 20 | 80 | (\#) | 0 | 200 | 600 kPa |
| Siemens QBE2002 P4 | 17 | 0 | 0 | 400 | needless | 0 | 400 | 0 | 5 | 20 | 80 | (\#) | 0 | 20 | 200 kPa |
| Siemens QBE2002 P10 | 17 | 0 | 0 | 1000 | needless | 0 | 1000 | 0 | 5 | 20 | 80 | (\#) | 0 | 50 | 600 kPa |
| Siemens QBE2002 P16 | 17 | 0 | 0 | 1600 | needless | 0 | 1600 | 0 | 5 | 20 | 80 | (\#) | 0 | 80 | 600 kPa |
| Siemens QBE2002 P25 | 17 | 0 | 0 | 2500 | needless | 0 | 2500 | 0 | 5 | 20 | 80 | (\#) | 0 | 125 | 600 kPa |
| Siemens QBE2002 P40 | 17 | 0 | 0 | 4000 | needless | 0 | 4000 | 0 | 5 | 20 | 80 | (\#) | 0 | 200 | 600 kPa |
| Segnale 0 $\div 10 \mathrm{~V}$ | 17 | 0 | to be fixed | to be fixed | needless | to be fixed | to be fixed | to be fixed | 5 | 20 | 80 | (\#) | to be fixed | to be fixed | to be fixed |
| Segnale 4 $\div 20 \mathrm{~mA}$ | 16 | 0 | to be fixed | to be fixed | needless | to be fixed | to be fixed | to be fixed | 5 | 20 | 80 | (\#) | to be fixed | to be fixed | to be fixed |

## NOTE

(\#) tt - servo control run time
SQL33 ; STM30; SQM10; SQM40; SQM50; SQM54 = 30 (secondi) - STA12B3.41; SQN30.251; SQN72.4A4A20 = 12 (secondi)
(*) $^{*}$ These values are factory set - values must be set during operation at the plant based on the real working temperature/pressure value.
WARNING: With pressure probes the parameters SP1, SCH, SCL, HYS1, HYS3 must be selected, and visualized in kPa (kilo Pascal). ( $1 \mathbf{1 \mathrm { bar }} \equiv \underline{100.000 \mathrm{~Pa}} \equiv \underline{100 \mathrm{kPa}})$

## APPENDIX: PROBES CONNECTION

To assure the utmost comfort, the control system needs reliable information, which can be obtained provided the sensors have been installed correctly. Sensors measure and transmit all variations encountered at their location.
Measurement is taken based on design features (time constant) and according to specific operating conditions.With wiring run in raceways, the sheath (or pipe) containing the wires must be plugged at the sensor's terminal board so that currents of air cannot affect the sensor's measurements.

## Ambient probes (or ambient thermostats)

## Installation

The sensors (or room thermostats) must be located in reference rooms in a position where they can take real temperature measurements without being affected by
foreign factors.


It's good to be admired ...even better to be effective
Heating systems: the room sensor must not be installed in rooms with heating units complete with thermostatic valves. Avoid all sources of heat foreign to the system.


## Location

On an inner wall on the other side of the room to heating unitsheight above floor 1.5 m , at least 1.5 m away from external sources of heat (or cold).


## Installation position to be avoided

near shelving or alcoves and recesses, near doors or win-dows, inside outer walls exposed to solar radiation or currents of cold air, on inner walls with heating system pipes, domestic hot water pipes, or cooling system pipes running through them.


Outside probes (weather)

## Installation

In heating or air-conditioning systems featuring adjustment in response to outside temperature, the sensor's positioning is of paramount importance.


General rule: on the outer wall of the building where the living rooms are, never on the south-facing wall or in a position where they will be affected by morning sun. If in any doubt, place them on the north or north-east façade.

## Positions to be avoided



Avoid installing near windows, vents, outside the boiler room, on chimney breasts or where they are protected by balconies, cantilever roofs.
The sensor must not be painted (measurement error).

## Duct or pipe sensors

## Installing temperature sensors

For measuring outlet air:

- after delivery fan or
- after coil to be controlled, at a distance of at least 0,5 m

For measuring room temperature:

- before return air intake fan and near room's return airintake. For measuring saturation temperature: after mist eliminator.


Bend 0.4 m sensor by hand (never use tools) as illustrated.


Use whole cross-section of duct, min. distance from walls 50 mm , radius of curvature 10 mm for 2 m or 6 m sensors.

## Installing combined humidity sensors

As max. humidity limit sensor on outlet (steam humidifiers).


## Installing pressure sensors

A - installation on ducts carrying fluids at max. temperature $80^{\circ} \mathrm{C}$
B - installation on ducts at temperature over $80^{\circ} \mathrm{C}$ and for refrigerants
C - installation on ducts at high temperatures:

- increase length of siphon
- place sensor at side to prevent it being hit by hot air coming from the pipe.



## Installing differential pressure sensors for water

- Installation with casing facing down not allowed.-With temperature over $80^{\circ} \mathrm{C}$, siphons are needed.
- To avoid damaging the sensor, you must comply with the following instructions
when installing:
- make sure pressure difference is not greater than thevalue permitted by the sensor
- when there are high static pressures, make sure you insert shutoff valves A-B-C.


## Putting into operation

Start disable
1=open C1=open C
$2=$ open $A 2=$ close $B$
$3=$ open B3=close $A$
4= close C


Immersion or strap-on sensors


Placing the probes (QAD22.../QAE21.../QAP21.../RCA...)

## With pumps on outlet

with 3 ways valves / with 4 ways valves


Panel system / burner control


## With pumps on return

with 3 ways valves / with 4 ways valves


## Immersion probes installation

Sensors must be installed on the stretch of pipe in which fluid circulates all the time.
The rigid stem (sensing element doing the measuring) must be inserted by at least 75 mm and must face the direction of flow.
Recommended locations: on a bend or on a straight stretch of pipe but tilted by $45^{\circ}$ and against the flow of fluid.
Protect them to prevent water from infiltrating (dripping gates, condensation from pipes etc.)

## Installing QAD2.. strap-on sensors

Make sure fluid is circulating in the chosen location.
Eliminate insulation and paintwork (including rust inhibitor) on a min. 100 mm length of pipe.
Sensors come with straps for pipes up to 100 mm in diameter

## Strap-on or immersion sensors?

QAD2.. strap-on sensors
Advantages :

- 10 sec. time constant
- Installed with system running (no plumbing work)
- Installation can be changed easily if it proves incorrect.


## Limits:

- Suitable for pipe diameters max. 100 mm
- Can be affected by currents of air etc.

QAE2... immersion sensors
Advantages:

- Measure "mean" fluid temperature
- No external influence on measurement such as: currents of air, nearby pipes etc.
Limits:
- Time constant with sheath: 20 sec .
- Hard to change installation position if it proves incorrect.

Installing differential pressure probes for air


A - Control a filter (clogging)


B - Control a fan (upstream/downstream)


C - Measurement of difference in pressure between two ducts

$-(+)$
D - Measurement of difference in pressure between two rooms or of inside of duct and outside

Basic principles


Measuring dinamic pressure


$$
P d=\frac{y \vartheta^{2}}{2 g}
$$

y $\quad \mathrm{Kg} / \mathrm{m}^{3}$, specific weight of air $\mathrm{m} / \mathrm{s}$, air speed
g $\quad 9.81 \mathrm{~m} / \mathrm{s}^{2}$ gravity acceleration Pd mm C.A., dynamic pressure

Measuring total pressure


Spare parts

| Description | Code |
| :---: | :---: |
| Modulator RWF50.2 (uscita a 3 punti - apri, fermo, chiudi) | 2570148 |
| Modulator RWF50.3 (uscita continua $0 \div 20 \mathrm{~mA}, 4 \div 20 \mathrm{~mA}, 0 \div 10 \mathrm{~V}$ ) | 2570149 |
| Temperature probe Siemens QAE2120.010A ( $30 \div 130^{\circ} \mathrm{C}$ ) | 2560101 |
| Temperature probe Siemens QAM2120.040 ( $-15 \div+50^{\circ} \mathrm{C}$ ) | 2560135 |
| Thermoresistor Pt1000 ø6mm L100mm ( $30 \div 130^{\circ} \mathrm{C}$ ) | 2560188 |
| Thermoresistor Pt1000 ø10mm L200mm ( $0 \div 350^{\circ} \mathrm{C}$ ) | 2560103 |
| Thermoresistor Pt100 ø10mm L200mm ( $0 \div 350^{\circ} \mathrm{C}$ ) | 2560145 |
| Thermoresistor Pt100 ø8mm L85mm ( $0 \div 120^{\circ} \mathrm{C}$ ) | 25601C3 |
| Pressure probe Siemens QBE2.. P4 (0 $\div$ 4bar) | 2560159 |
| Pressure probe Siemens QBE2.. P10 ( $0 \div 10 \mathrm{bar} /$ signal $0 \div 10 \mathrm{~V}$ ) | 2560160 |
| Pressure probe Siemens QBE2.. P16 ( $0 \div 16 \mathrm{bar} /$ signal $0 \div 10 \mathrm{~V}$ ) | 2560167 |
| Pressure probe Siemens QBE2.. P25 ( $0 \div 25 \mathrm{bar} /$ signal $0 \div 10 \mathrm{~V}$ ) | 2560161 |
| Pressure probe Siemens QBE2.. P40 ( $0 \div 40 \mathrm{bar}$ / signal 0 $\div 10 \mathrm{~V}$ ) | 2560162 |
| Pressure probe Danfoss MBS 3200 P 1,6 ( $0 \div 1,6 \mathrm{bar} /$ signal $4 \div 20 \mathrm{~mA}$ ) | 2560189 |
| Pressure probe Danfoss MBS 3200 P 10 ( $0 \div 10 \mathrm{bar} /$ signal $4 \div 20 \mathrm{~mA}$ ) | 2560190 |
| Pressure probe Danfoss MBS 3200 P 16 ( $0 \div 16 \mathrm{bar} /$ signal $4 \div 20 \mathrm{~mA}$ ) | 2560191 |
| Pressure probe Danfoss MBS 3200 P 25 ( $0 \div 25$ bar / signal $4 \div 20 \mathrm{~mA}$ ) | 2560192 |
| Pressure probe Danfoss MBS 3200 P 40 ( $0 \div 40 \mathrm{bar} /$ signal $4 \div 20 \mathrm{~mA}$ ) | 2560193 |
| Pressure probe Siemens 7MF1565-3BB00-1AA1 ( $0 \div 1,6 \mathrm{bar} /$ signal $4 \div 20 \mathrm{~mA}$ ) | 25601A3 |
| Pressure probe Siemens 7MF1565-3CA00-1AA1 ( $0 \div 10 \mathrm{bar} /$ signal $4 \div 20 \mathrm{~mA}$ ) | 25601A4 |
| Sonda di pressione Siemens 7MF1565-3CB00-1AA1 (0%16bar / signal | 25601A5 |
| Pressure probe Siemens 7MF1565-3CD00-1AA1 (0 $\div 25$ bar / signal 4 $\div 20 \mathrm{~mA}$ ) | 25601A6 |
| Pressure probe Siemens 7MF1565-3CE00-1AA1 ( $0 \div 40 \mathrm{bar} /$ signal $4 \div 20 \mathrm{~mA}$ ) | 25601A7 |
| Pressure probe Gefran E3E B1V6 MV ( $0 \div 1,6 \mathrm{bar}$ / segnale 4 $\div 20 \mathrm{~mA}$ ) | 25601C4 |
| Pressure probe Danfoss E3E B01D MV ( $0 \div 10 \mathrm{bar}$ / segnale 4 $\div 20 \mathrm{~mA}$ ) | 25601C5 |
| Pressure probe Danfoss E3E B16U MV ( $0 \div 16 \mathrm{bar}$ / segnale 4 $4 \div 20 \mathrm{~mA}$ ) | 25601C6 |
| Pressure probe Danfoss E3E B25U MV ( $0 \div 25$ bar / segnale $4 \div 20 \mathrm{~mA}$ ) | 25601C7 |
| Pressure probe Danfoss E3E B04D MV ( $0 \div 40 \mathrm{bar}$ / segnale 4 $\div 20 \mathrm{~mA}$ ) $)$ | 25601C8 |

Note: Specifications and data subject to change. Errors and omissions excepted.

# KM3 Modulator 

USER MANUAL

MOUNTING


## DISPLAY AND KEYS



|  | Operator Mode | Editing Mode |
| :---: | :---: | :---: |
| $\square$ | Access to: <br> - Operator Commands <br> (Timer, Setpoint selection ...) <br> - Parameters <br> - Configuration | Confirm and go to Next parameter |
|  | Access to: <br> - Operator additional information (Output value, running time ...) | Increase the displayed value or select the next element of the parameters list |
|  | Access to: <br> - Set Point | Decrease the displayed value or select the previous element |
|  | Programmable key: Start the programmed function (Autotune, Auto/Man, Timer ...) | Exit from Operator commands/Parameter setting/Configuration |

CONNECTIONS DIAGRAM


Probe connection:

- PT1000/NTC/PTC: between terminal 3 and 2
- PT 100: between terminal 3 and 2 with terminal 1
- Passive pressure probe 0/4-20 mA: between terminal 4 ( + ) e 1 ( - ) Note: out4 must be activated ( IO4F must be setted to ON )
- Powered pressure probe 0/4-20 mA between terminal 4 (power supply), 2 ( negative) e 1 (positive) Note: set IO4F to ON to activate Out4


## Power supply connection:

- Neutral wire: terminal 9
- Phase: terminal 10 ( $100 \ldots 240 \mathrm{Vac}$ )
- Close terminals 15-16 to switch to the set point 2


## Output connection:

- Channel 1: terminal 7 and 8 (burner on - off)
- Channel 2: terminal 11 and 12 (servomotor opens)
- Channel 3: terminal 13 and 14 (servomotor closes)


## SETPOINT AND HYSTERESIS CONFIGURATION (SP, AL1, HAL1 parameters)

Push the $\boldsymbol{\square}$ button to enter into the setpoint configuration:


To return to normal mode, press the key for 3 seconds or wait the 10 s timeout

## Operation example



## LIMITED ACCESS LEVEL

Proceed as follows to change some parameters that are not visible in standard user mode:


Press the $\boldsymbol{\omega}$ key for 3 seconds


Password $=20$


Access to parameter:

| $\boldsymbol{\Delta}$ | Increase the displayed value |
| :--- | :--- |
| $\boldsymbol{\nabla}$ | Decrease the displayed <br> value |
| $\boldsymbol{\omega}$ | Confirm and go to next <br> parameter |


| Param | Description | Values | Default |
| :---: | :---: | :---: | :---: |
| SEnS | Input type | $\begin{array}{\|l\|} \hline \text { Pt1 }=\text { RTD Pt100 } \\ \text { Pt10 }=\text { RTD Pt1000 } \\ 0.20=0 . .20 \mathrm{~mA} \\ 4.20=4 . .20 \mathrm{~mA} \text { Pressure probe } \\ 0.10=0 . .10 \mathrm{~V} \\ 2.10=2 . .10 \mathrm{~V} \\ \text { crAL }=\text { Thermocouple } \mathrm{K} \end{array}$ | Depends on the probe |
| SP | Set point 1 | SPLL ... SPLH | See page 7 |
| AL1 | AL1 threshold | AL1L... AL1H (E.U.) |  |
| HAL1 | AL1 hysteresis | 1... 9999 (E.U.) |  |
| Pb | Proportional band | 1... 9999 (E.U.) |  |
| ti | Integral time | 0 (oFF) ... 9999 (s) |  |
| td | Derivative time | 0 (oFF) ... 9999 (s) |  |
| Str.t | Servomotor stroke time | 5...1000 seconds |  |
| db.S | Servomotor dead band | 0...100\% |  |
| SPLL | Minimum set point value | -1999 ... SPHL |  |
| SPHL | Maximum set point value | SPLL ... 9999 |  |
| dp | Decimal point position | 0... 3 |  |
| SP 2 | Set point 2 | SPLL...SPLH | 60 |
| A.SP | Selection of the active set point | "SP" ... " nSP" | SP |

To exit the parameter setting procedure press the key (for 3 s ) or wait until the timeout expiration (about 30 seconds)
Probe parameters configuration MODULATORE ASCON KM3

| Parameter Group | inP |  |  |  |  |  | AL1 |  | rEG |  |  |  |  | SP |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Parameter | Sens | dp | SSC | FSc | unit | $\begin{gathered} \text { IO4.F } \\ (* *) \\ \hline \end{gathered}$ | AL1 <br> (***) | HAL1 (***) | $\begin{aligned} & \mathrm{Pb} \\ & \text { (***) } \end{aligned}$ | $\begin{gathered} \mathrm{ti} \\ (* * *) \end{gathered}$ | $\begin{aligned} & \text { td } \\ & (* * *) \end{aligned}$ | Str.t | db.S | SPLL | SPHL | $\begin{aligned} & \hline \text { SP } \\ & (* * *) \end{aligned}$ |
| Probes |  | Dec Point | Scale <br> Min | Scale <br> Max |  |  | Off | On | p | - | d | servo time s | Band Mo. | $\begin{aligned} & \mathrm{SP} \\ & \mathrm{Min} \end{aligned}$ | $\begin{aligned} & \hline \text { SP } \\ & \mathrm{Max} \\ & \hline \end{aligned}$ | Set point |
| Pt1000 ( $130^{\circ} \mathrm{C}$ max) | Pt10 | 1 |  |  | ${ }^{\circ} \mathrm{C}$ | on | 5 | 10 | 10 | 350 | 1 | * | 5 | 30 | 95 | 80 |
| Pt1000 ( $350^{\circ} \mathrm{C}$ max) | PT10 | 1 |  |  | ${ }^{\circ} \mathrm{C}$ | on | 10 | 10 | 10 | 350 | 1 | * | 5 | 0 | 350 | 80 |
| Pt100 ( $130^{\circ} \mathrm{C}$ max) | PT1 | 1 |  |  | ${ }^{\circ} \mathrm{C}$ | on | 5 | 10 | 10 | 350 | 1 | * | 5 | 0 | 95 | 80 |
| Pt100 ( $350^{\circ} \mathrm{C}$ max) | Pt1 | 1 |  |  | ${ }^{\circ} \mathrm{C}$ | on | 10 | 10 | 10 | 350 | 1 | * | 5 | 0 | 350 | 80 |
| Pt100 ( $0 \div 100^{\circ} \mathrm{C} 4 \div 20 \mathrm{~mA}$ ) | 4.20 | 1 | 0 | 100 |  | on | 5 | 10 | 10 | 350 | 1 | * | 5 | 0 | 95 | 80 |
| Thermocouple K ( $1200^{\circ} \mathrm{C}$ max) | crAL | 0 |  |  | ${ }^{\circ} \mathrm{C}$ | on | 20 | 25 | 10 | 350 | 1 | * | 5 | 0 | 1200 | 80 |
| Thermocouple $\mathrm{J}\left(1000^{\circ} \mathrm{C} \mathrm{max}\right)$ | J | 0 |  |  | ${ }^{\circ} \mathrm{C}$ | on | 20 | 25 | 10 | 350 | 1 | * | 5 | 0 | 1000 | 80 |
| 4-20mA / 0-1,6barPressure probe | 4.20 | 0 | 0 | 160 |  | on | 20 | 20 | 5 | 120 | 1 | * | 5 | 0 | 160 | 100 |
| 4-20mA/ 0-10bar Pressure probe | 4.20 | 0 | 0 | 1000 |  | on | 50 | 50 | 5 | 120 | 1 | * | 5 | 0 | 1000 | 600 |
| 4-20mA/ 0-16bar Pressure probe | 4.20 | 0 | 0 | 1600 |  | on | 80 | 80 | 5 | 120 | 1 | * | 5 | 0 | 1600 | 600 |
| 4-20mA/ 0-25bar Pressure probe | 4.20 | 0 | 0 | 2500 |  | on | 125 | 125 | 5 | 120 | 1 | * | 5 | 0 | 2500 | 600 |
| 4-20mA / 0-40bar Pressure probe | 4.20 | 0 | 0 | 4000 |  | on | 200 | 200 | 5 | 120 | 1 | * | 5 | 0 | 4000 | 600 |
| QBE2002 / 0-25bar Pressure probe | 0.10 | 0 | 0 | 2500 |  | On | 125 | 125 | 5 | 120 | 1 | * | 5 | 0 | 2500 | 600 |

## CONFIGURATION

## How to access configuration level

The configuration parameters are collected in various groups. Every group defines all parameters related with a specific function (e.g.: control, alarms, output functions).

1. Push the button for more than 5 seconds. The upper display will show PASS while the lower display will show 0.
2. Using $\boldsymbol{\Delta}$ and $\boldsymbol{\nabla}$ buttons set the programmed password.

According to the entered password, it is possible to see a part of the parameters listed in the "configuration parameters" section.
a. Enter " 30 " as password to view all the configuration parameters
b. Enter "20" as password to view the parameters of the "limited access level". At this point, only the parameters with attribute Liv $=\mathbf{A}$ or Liv $=\mathbf{O}$ will be editable.
c. Leave the password blank to edit "user level" parameters, that are identified by attribute Liv=0
3. Push the $\quad$ button. If the password is correct the display will show the acronym of the first parameter group preceded by the symbol: ${ }^{-1}$. In other words the upper display will show: ${ }^{-1} \mathrm{inP}$ (group of the Input parameters).

The instrument is in configuration mode. To press more than 5 seconds, the instrument will return to the "standard display.
Keyboard functions during parameter changing:

|  | Operator Mode <br> Whe the upper display is showing a group and the lower display is blank, this key allows to enter in the <br> selected group. When the upper display is showing a parameter and the lower display is showing its value, <br> this key allows to store the selected value for the current parameter and access the next parameter within <br> the same group. |
| :--- | :--- |
|  | Allows to increase the value of the selected parameter. |
|  | Allows to decrease the value of the selected parameter. | | Short presses allow you to exit the current group of parameters and select a new group. A long press |
| :--- |
| terminates the configuration procedure (the instrument returns to the normal display). |

Configuration Parameters

| inP GROUP - input confiuration |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Liv | $\mathrm{N}^{\circ}$ | Param | Description | Values | Default |
| A | 1 | SEnS | Input type | $\begin{array}{\|l\|} \hline \text { Pt1 }=\text { RTD Pt100 } \\ \text { Pt10 }=\text { RTD Pt1000 } \\ 0.20=0 . .20 \mathrm{~mA} \\ 4.20=4 . .20 \mathrm{~mA} \text { Pressure probe } \\ 0.10=0 . .10 \mathrm{~V} \\ 2.10=2 . .10 \mathrm{~V} \\ \text { crAL }=\text { Thermocouple } \mathrm{K} \\ \hline \end{array}$ | Depends on the probe |
| A | 2 | dp | Decimal point position | 0... 3 | $\begin{aligned} & \hline \text { See page } \\ & 7 \end{aligned}$ |
| A | 3 | SSc | Initial scale read-out for linear inputs (avaiable only if SEnS parameter is not equal to Pt 1 , Pt10, crAL values) | -1999... 9999 | 0 |
| C | 4 | FSc | Full scale read-out for linear input inputs (avaiable only if SEnS parameter is not equal to Pt1, Pt10, crAL values) | -1999... 9999 | Depends on the probe |
| C | 5 | unit | Unit of measure (present only in the case of temperature probe) | ${ }^{\circ} \mathrm{C} /{ }^{\circ} \mathrm{F}$ | ${ }^{\circ} \mathrm{C}$ |
| C | 6 | Fil | Digital filter on the measured value | 0 (= OFF)... 20.0 s | 1.0 |
| C | 7 | inE | Selection of the Sensor Out of Range type that will enable the safety output value | $\begin{array}{\|l\|} \hline \text { or }=\text { Over range } \\ \text { ou = Under range } \\ \text { our = over e under range } \\ \hline \end{array}$ | or |


| C | 8 | oPE | Safety output value | -100... 100 |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| C | 9 | io4.F | I/O4 function selection | on = Out4 will be ever ON (used as a transmitter power supply) ,out4 = Uscita 4 (Used as digital output 4), dG2c = Digital input 2 for contact closure, dG2U = Digital input 2 driven by 12... 24 VDC | on |
| C | 10 | diF1 | Digital input 1 function | ```oFF = Not used, 1 = Alarm reset, 2 = Alarm acknowledge (ACK), 3 = Hold of the measured value, 4 = Stand by mode, 5 = Manual mode, \(6=\) HEAt with SP1 and CooL with SP2, 7 = Timer RUN/Hold/Reset, 8 = Timer Run, 9 = Timer Reset, \(10=\) Timer Run/Hold, 11 = Timer Run/Reset, \(12=\) Timer Run/Reset with lock, 13 = Program Start, 14 = Program Reset, 15 = Program Hold, 16 = Program Run/Hold, 17 = Program Run/Reset, \(18=\) Sequential SP selection, 19 = SP1 - SP2 selection, \(20=\) SP1... SP4 binary selection, \(21=\) Digital inputs in parallel``` | 19 |
| C | 12 | di.A | Digital Inputs Action (DI2 only if configured) | 0 = DI1 direct action, DI2 direct action <br> 1 = DI1 reverse action, DI2 direct action <br> $2=$ DI1 direct action, DI2 reverse action <br> 3 = DI1 reverse action, DI2 reverse action | 0 |

Out GROUP- Output parameters

| Liv | $\mathrm{N}^{\circ}$ | Param | Description | Values | Default |
| :---: | :---: | :---: | :---: | :---: | :---: |
| C | 14 | 01F | Out 1 function | AL = Alarm output | AL |
| C | 15 | 01AL | Initial scale value of the analog retransmission | -1999 ... Ao1H | 1 |
| C | 18 | 01Ac | Out 1 action | ```dir = Direct action rEU = Reverse action dir.r = Direct with reversed LED ReU.r = Reverse with reversed LED``` | rEUr.r |
| C | 19 | 02F | Out 2 function | H.rEG = Heating output | H.rEG |
| C | 21 | o2Ac | Out 2 action | ```dir = Direct action rEU = Reverse action dir.r = Direct with reversed LED ReU.r = Reverse with reversed LED``` | dir |
| C | 22 | 03F | Out 3 function | H.rEG = Heating output | H.rEG |
| C | 24 | o3Ac | Out 3 action | dir = Direct action rEU = Reverse action dir.r = Direct with reversed LED ReU.r = Reverse with reversed LED | dir |


| AL1 GROUP - Alarm 1 parameters |  |  |  |  |  |  |  | Values | Default |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
| Liv | $\mathbf{N}^{\circ}$ | Param | Descrizione | nonE = Alarm not used <br> LoAb = Absolute low alarm <br> HiAb = Absolute high alarm <br> LHAo = Windows alarm in alarm outside the <br> windows <br> LHAI = Windows alarm in alarm inside the |  |  |  |  |  |
| C | 28 | AL1t | Tipo allarme AL1 |  |  |  |  |  |  |


|  |  |  |  | windows <br> SE. $\mathrm{br}=$ Sensor Break <br> LodE = Deviation low alarm (relative) <br> HidE = Deviation high alarm (relative) <br> LHdo = Relative band alarm in alarm out of the band <br> LHdi $=$ Relative band alarm in alarm inside the band |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| C | 29 | Ab1 | Alarm 1 function | ```\[ 0 . .15 \] \[ +1=\text { Not active at power up } \] \[ +2=\text { Latched alarm (manual reset) } \] +4 = Acknowledgeable alarm \[ +8=\text { Relative alarm not active at set point change } \]``` | 0 |
| C | 30 | AL1L | -- For High and low alarms, it is the low limit of the AL1 threshold; <br> -- For band alarm, it is low alarm threshold | -1999... AL1H (E.U.) | -199.9 |
| C | 31 | AL1H | -- For High and low alarms, it is the high limit of the AL1 threshold; <br> -- For band alarm, it is high alarm threshold | AL1L... 9999 (E.U.) | 999.9 |
| 0 | 32 | AL1 | AL1 threshold | AL1L... AL1H (E.U.) | See page 7 |
| 0 | 33 | HAL1 | AL1 hysteresis | 1... 9999 (E.U.) | See page 7 |
| C | 34 | AL1d | AL1 delay | 0 (oFF)... 9999 (s) | oFF |
| C | 35 | AL1o | Alarm 1 enabling during Stand-by mode and out of range conditions | 0 = Alarm 1 disabled during Stand by and out of range <br> 1 = Alarm 1 enabled in stand by mode <br> 2 = Alarm 1 enabled in out of range condition <br> 3 = Alarm 1 enabled in stand by mode and in overrange condition | 1 |


| GRUPPO AL2 - parametri allarme 2 |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Liv | $\mathrm{N}^{\circ}$ | Param | Description | Values | Default |
| C | 36 | AL2t | Alarm 2 type | nonE = Alarm not used <br> LoAb = Absolute low alarm <br> $\mathrm{HiAb}=$ Absolute high alarm <br> LHAo = Windows alarm in alarm outside the windows <br> LHAI = Windows alarm in alarm inside the windows <br> SE.br = Sensor Break <br> LodE = Deviation low alarm (relative) <br> HidE = Deviation high alarm (relative) <br> LHdo $=$ Relative band alarm in alarm out of the band <br> LHdi = Relative band alarm in alarm inside the band | SE.br |
| C | 37 | Ab2 | Alarm 2 function | 0... 15 <br> $+1=$ Not active at power up <br> +2 = Latched alarm (manual reset) <br> +4 = Acknowledgeable alarm <br> $+8=$ Relative alarm not active at set point change | 0 |
| C | 42 | AL2d | AL2 hysteresis | 0 (oFF)... 9999 (s) | oFF |
| C | 43 | AL2o | Alarm 2 enabling during Stand-by mode and out of range conditions | 0 = Alarm 2 disabled during Stand by and out of range <br> 1 = Alarm 2 enabled in stand by mode <br> 2 = Alarm 2 enabled in out of range condition <br> 3 = Alarm 2 enabled in stand by mode and in overrange condition | 0 |

## AL3 Group - alarm 3 parameters

| Liv | $\mathbf{N}^{\circ}$ | Param | Description | Values | Default |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  | 44 | AL3t | Alarm 3 type | nonE = Alarm not used <br> LoAb = Absolute low alarm <br> HiAb = Absolute high alarm <br> LHAo = Windows alarm in alarm outside the <br> windows <br> LHAI = Windows alarm in alarm inside the <br> windows <br> SE.br = Sensor Break <br> LodE = Deviation low alarm (relative) <br> HidE = Deviation high alarm (relative) <br> LHdo = Relative band alarm in alarm out of the <br> band <br> LHdi = Relative band alarm in alarm inside the <br> band |  |


| LbA Group - Loop break alarm |  |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: |
| Liv | $\mathbf{N}^{\circ}$ | Param | Descrizione | Values | Default |  |
| C | 52 | LbAt | LBA time | Da 0 (oFF) a 9999 (s) | oFF |  |


| rEG Group - Control parameters |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Liv | $\mathrm{N}^{\circ}$ | Param | Description | Values | Default |
| C | 56 | cont | Control type | Pid = PID (heat and/or) <br> On.FA = ON/OFF asymmetric hysteresis <br> On.FS = ON/OFF symmetric hysteresis <br> $n r=$ Heat/Cool ON/OFF control with neutral zone <br> $3 \mathrm{Pt}=$ Servomotor control (available only when Output 2 and <br> Output 3 have been ordered as " $M$ ") | 3pt |
| C | 57 | Auto | Autotuning selection | $-4=$ Oscillating auto-tune with automaticrestart at power up and after all point change <br> $-3=$ Oscillating auto-tune with manual start <br> $-2=$ Oscillating -tune with auto-matic start at the first power up only <br> $-1=$ Oscillating auto-tune with auto-matic restart at every power up <br> $0=$ Not used <br> 1 = Fast auto tuning with automatic restart at every power up <br> $2=$ Fast auto-tune with automatic start the first power up only <br> 3 = FAST auto-tune with manual start <br> $4=$ FAST auto-tune with automatic restart at power up and <br> after set point change <br> $5=$ Evo-tune with automatic restart at every power up <br> $6=$ Evo-tune with automatic start the first power up only <br> 7 = Evo-tune with manual start <br> $8=$ Evo-tune with automatic restart at power up and after a set point change | 7 |
| C | 58 | tunE | Manual start of the Autotuning | $\begin{aligned} & \text { oFF = Not active } \\ & \text { on = Active } \end{aligned}$ | oFF |


| C | 59 | SELF | Self tuning enabling | no = The instrument does not perform the self- <br> tuning <br> YES $=$ The instrument is performing the self- <br> tuning | No |
| :--- | :--- | :--- | :--- | :--- | :--- |
| A | 62 | Pb | Proportional band | $1 \ldots 9999$ (E.U.) | See <br> page 7 |
| A | 63 | ti | Integral time | $0($ oFF) ... 9999 (s) | See <br> page 7 |
| A | 64 | td | Derivative time | $0($ oFF) ... 9999 (s) | See <br> page 7 |
| C | 65 | Fuoc | Fuzzy overshoot control | $0.00 \ldots 2.00$ | 1 |
| C | 69 | rS | Manual reset (Integral pre-load) | $-100.0 \ldots+100.0(\%)$ | 0.0 |
| A | 70 | Str.t | Servomotor stroke time | $5 \ldots 1000$ seconds | See <br> page 7 |
| A | 71 | db.S | Servomotor dead band | $0 \ldots 100 \%$ | 5 |
| C | 72 | od | Delay at power up | $0.00(\mathrm{oFF}) \ldots 99.59(\mathrm{hh} . \mathrm{mm})$ | oFF |

SP Group - Set point parameters

| Liv | $\mathrm{N}^{\circ}$ | Param | Description | Values | Default |
| :---: | :---: | :---: | :---: | :---: | :---: |
| C | 76 | nSP | Number of used set points | 1... 4 | 2 |
| A | 77 | SPLL | Minimum set point value | -1999 ... SPHL | $\begin{array}{\|c\|} \hline \text { See } \\ \text { page } 7 \end{array}$ |
| A | 78 | SPHL | Maximum set point value | SPLL ... 9999 | $\begin{array}{\|l\|} \hline \text { See } \\ \text { page } 7 \\ \hline \end{array}$ |
| 0 | 79 | SP | Set point 1 | SPLL ... SPLH | See page 7 |
| C | 80 | SP 2 | Set point 2 | SPLL ... SPLH | 60 |
|  | 83 | A.SP | Selection of the active set point | "SP" ... " nSP" | SP |
| C | 84 | SP.rt | Remote set point type | RSP = The value coming from serial link is used as remote set point <br> trin = The value will be added to the local set point selected by <br> A.SP and the sum becomes the operative set point <br> PErc $=$ The value will be scaled on the input range and this value will be used as remote SP | trin |
| C | 85 | SPLr | Local/remote set point selection | $\begin{aligned} & \text { Loc = Local } \\ & \text { rEn = Remote } \end{aligned}$ | Loc |
| C | 86 | SP.u | Rate of rise for POSITIVE set point change (ramp UP) | 0.01... 99.99 (inF) Eng. units per minute | inF |
| C | 87 | SP.d | Rate of rise for NEGATIVE set point change (ramp DOWN) | 0.01... 99.99 (inF) Eng. units per minute | inF |

## PAn Group - Operator HMI

| Liv | $\mathbf{N}^{\circ}$ | Param | Description | Values | Default |
| :--- | :--- | :--- | :--- | :--- | :--- |
| C | 118 | PAS2 | Level 2 password (limited access level) | oFF (Level 2 not protected by password) <br> $1 \ldots 200$ | 20 |
| C | 119 | PAS3 | Level 3 password (complete <br> configuration level) | $3 \ldots 300$ <br> codice) | $201 \ldots 400$ |
| C | 120 | PAS4 | Password livello (livello configurazione a <br> C | 121 | uSrb |
| button function during RUN TIME | nonE $=$ No function <br> tunE = Auto-tune/self-tune enabling. A single <br> press (longer than 1 second) <br> starts the auto-tune <br> oPLo = Manual mode. The first pressure puts the <br> instrument in manual mode <br> (OPLO) while a second one puts the instrument <br> in Auto mode | tunE |  |  |  |


|  |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |

## SEr Group - Serial link parameter

| Liv | $\mathbf{N}^{\circ}$ | Param | Description | Values | Default |
| :--- | :--- | :--- | :--- | :--- | :--- |
| C | 131 | Add | Instrument address | -- oFF <br> $--1 \ldots 254$ | 1 |
| C | 132 | bAud | baud rate | $1200=1200$ baud <br> $2400=2400$ baud <br> $9600=9600$ baud <br> $19.2=19200$ baud <br> $38.4=38400$ baud |  |
| C | 133 | trSP | Selection of the value to be retransmitted <br> (Master) | nonE $=$ Retransmission not used (the instrument <br> is a slave) <br> rSP $=$ The instrument becomes a Master and <br> retransmits the operative set point <br> PErc $=$ The instrument become a Master and it <br> retransmits the power output | nonE |

## con Group - Consumption parameters

| Liv | $\mathrm{N}^{\circ}$ | Param | Description | Values | Default |
| :---: | :---: | :---: | :---: | :---: | :---: |
| C | 134 | Co.tY | Count type | oFF = Not used <br> 1 = Instantaneous power (kW) <br> $2=$ Power consumption (kW/h) <br> 3 = Energy used during program execution. This measure starts from <br> zero when a program runs end stops at the end of the program. A <br> new program execution will reset the value <br> $4=$ Total worked days: number of hours the instrument is turned ON <br> divided by 24 . <br> 5 = Total worked hours: number of hours the instrument is turned ON. <br> $6=$ Total worked days with threshold: number of hours the instrument is <br> turned ON divided by 24 , the controller is forced in stand-by when <br> Co.ty value reaches the threshold set in [137] <br> h.Job. <br> 7 = Total worked hours with threshold: number of hours the instrument <br> is turned ON , the controller is forced in stand-by when Co.ty value <br> reaches the threshold set in [137] h.Job. <br> $8=$ Totalizer of control relay worked days: <br> number of hours the control <br> relay has been in ON condition, divided by 24. <br> 9 = Totalizer of control relay worked hours: <br> number of hours the control <br> relay has been in ON condition. <br> $10=$ Totalizer of control relay worked days with <br> threshold: number of <br> hours the control relay has been in ON condition divided by 24, <br> the controller is forced in stand-by when Co.ty value reaches the <br> threshold set in [137] h.Job. <br> 11 = Totalizer of control relay worked hours with threshold: number of <br> hours the control relay has been in ON condition, the controller is forced in stand-by when Co.ty value reaches the threshold set in <br> [137] h.Job. | oFF |
| C | 138 | t.Job | Worked time (not resettable) | 0... 9999 days | 0 |

cAL Group - User calibration group

| Liv | $\mathbf{N}^{\circ}$ | Param | Description | Values | Default |
| :--- | :--- | :--- | :--- | :--- | :---: |
| C | 139 | AL.P | Adjust Low Point | From -1999 to (AH.P -10$)$ in engineering units | 0 |
| C | 140 | AL.o | Adjust Low Offset | $-300 \ldots+300($ E.U. $)$ | 0 |
| C | 141 | AH.P | Adjust High Point | From (AL.P +10$)$ to 9999 engineering units | 999.9 |
| C | 142 | AH.o | Adjust High Offset | $-300 \ldots+300$ | 0 |

## OPERATIVE MODES

When the instrument is powered, it starts immediately to work according to the parameters values loaded in its memory. The instrument behaviour and its performance are governed by the value of the stored parameters.

At power ON the instrument can start in one of the following mode depending on its configuration:
Automatic Mode In Automatic mode the instrument drives automatically the control output according to the parameter value set and the set point/measured value.

Manual Mode (OPLO): In Manual mode the the upper display shows the measured value while the lower display shows the power output The lower display shows the power output [preceded by H (for heating) or C (for cooling)], MAN is lit and the instrument allows you to set manually the control output power. No Automatic action will be made.

Stand by Mode (St.bY): In stand-by mode the instrument operates as an indicator. It will show on the upper display the measured value and on the lower display the set point alternately to the "St.bY" messages and forces the control outputs to zero.

We define all the above described conditions as "Standard Display".
As we have seen, it is always possible to modify the value assigned to a parameter independently from the operative modes selected.

## AUTOMATIC MODE

Keyboard function when the instrument is in Auto mode:

|  | Modo Operatore |
| :--- | :--- |
|  | Allows entry into parameter modification procedures |
|  | Allows you to start the "Direct set point modification" function <br> (see below). |
|  | Allows you to display the "additional informations" (see below). |
|  | Performs the action programmed by [121] uSrb (CPbutton <br> function during RUN TIME) parameter |

## Additional information

This instrument is able to show you some additional informations that can help you to manage your system. The additional informations are related to how the instrument is programmed, hence in many cases, only part of this information is available.

1. When the instrument is showing the "standard display" push button. The lower display will show H or c followed by a number. This value is the current power output applied to the process. The H show you that the action is a Heating action while the "c" show you that the action is a Cooling action
2. Push button again. When the programmer is running the lower display will show the segment currently performed and the Event status as shown below:
100 where the first character can be $r$ for a ramp or $S$ for a soak, the next digit show the number of the segment (e.g. S3 means Soak number 3) and the twoless significant digits (LSD) show you the status of the two event (the LSD is the Event 2)..
3. Push button again. When the programmer is running the lower display will show the theoretical remaining time to the end of the program preceded by a "P" letter:

## 日G4.

4. Push button again. When the wattmeter function is running the lower display will show $U$ followed by the measured energy..
5. Push button. When the "Worked time count" is running the lower display will show "d" for days or "h" for hours followed by the measured time.
6. Push button. The instrument returns to the "standard display".

Note: The additional information visualization is subject to a time out. If no button is pressed for more than 10 second the instrument comes automatically back to the Standard display..

## Direct set point modification

This function allows to modify rapidly the set point value selected by [83] A.SP (selection of the active Set point) or to the set point of the segment group (of the programmer) currently in progress.

1. Push button. The upper display shows the acronym of the selected set point (e.g. SP2) and the lower display will show its value.
2. By and buttons, assign to this parameter the desired value
3. Do not push any button for more than 5 second or push the button. In both cases the instrument memorize the new value and come back to the "standard display".

## Manual mode

This operative mode allows you to deactivate automatic control and manually program the percentage power output to the process. When the instrument is in manual mode, the upper display shows the measured value while the lower display shows the power output [preceded by H (for heating action) or C (for cooling action)] The MAN LED is lit. When manual control is selected, the instrument will start to operate with the same power output as the last one supplied by automatic mode and can be modified using the $\boldsymbol{\Delta}$ and $\boldsymbol{\nabla}$ buttons.

In case of ON/OFF control, $0 \%$ corresponds to the deactivated output while any value different from 0 corresponds to the activated output. As in the case of visualization, the programmable values range from H 100 ( $100 \%$ output power with reverse action) to C100 (100\% output power with direct action).

## Notes:

- During manual mode, the alarms are operative.
- If you set manual modes during program execution, the program will be frozen and it will restart when the instrument will come back to Auto mode.
- If you set manual modes during self-tune execution, the self- tune function will be aborted.
- During manual mode, all functions not related with the control (wattmeter, independent timer, "worked time", etc) continue to operate normally..


## STAND-BY MODE

This operative mode also deactivates the automatic control but forces the control output to zero. In this mode the instrument operates as an indicator. When the instrument is in stand by mode the upper display will show the measured value while the lower display will show alternately the set point and the message "St.bY".
Notes:

- During stand by mode, the relative alarms are disabled while the absolute alarms are operative or not according to the ALxo (Alarm x enabling during Stand-by mode) parameter setting.
- If you set stand by mode during program execution, the program will be aborted.
- If you set stand by mode during self-tune execution, the self- tune function will be aborted.
- During stand by mode, all functions not related with the control (wattmeter, independent timer, "worked time", etc) continue to operate normally.
- When the instrument is swapped from stand by to auto modes, the instrument will start automatically the alarm masking, the soft start functions and the auto-tune (if programmed).


## AUTOTUNE (EVOTUNE)

Evotune is a fast and fully automatic procedure that can be started in any condition, regardless the deviation from SP. The controller selects automatically the best tune method and computes the optimum PID parameters. To activate Evotune press button for 3 seconds.

## ERROR MESSAGES

The upper display shows the OVER-RANGE and UNDERRANGE conditions with the following indications:
Over-range: 0000
Under-range ப.ேப.L.

The sensor break will be signalled as an out of range:
Note: When an over-range or an under-range is detected, the alarms operate as in presence of the maximum or the minimum measurable value respectively.

To check the out of span Error condition, proceed as follows:

1. Check the input signal source and the connecting line.
2. Make sure that the input signal is in accordance with the instrument configuration. Otherwise, modify the input configuration.
3. If no error is detected, send the instrument to your supplier to be checked.

## List of possible errors

ErAT Fast Auto-tune cannot start. The measure value is tooclose to the set point. Push the button in order to delete the error message.
ouLd Overload on the out 4. The messages shows that a short circuit is present on the Out 4 when it is used as output or as a transmitter power suply. When the short circuit disappears the output restart to operate.

NoAt Auto-tune not finished within 12 hours.
ErEP Possible problem of the instrument memory. The messages disappears automatically. When the error continues, send the instrument to your supplier.

RonE Possible problem of the firmware memory. When this error is detected, send the instrument to your supplier.
Errt Possible problem of the calibration memory. When this error is detected, send the instrument to your supplier.

## FACTORY RESET

Sometime, e.g. when you re-configure an instrument previously used for other works or from other people or when you have made too many errors during configuration and you decided to re-configure the instrument, it is possible to restore the factory configuration. This action allows to put the instrument in a defined condition (the same it was at the first power ON).

The default data are those typical values loaded in the instrument prior to ship it from factory. To load the factory default parameter set, proceed as follows:

1. Press the $\quad$ button for more than 5 seconds. The upper display will show PASS while the lower display shows 0;
2. Using $\boldsymbol{\Delta}$ and $\boldsymbol{b}$ buttons set the value -481;
3. Push $\boldsymbol{\omega}$ button;
4. The instrument will turn OFF all LEDs for a few seconds, then the upper display will show dFLt (default) and then all LEDs are turned ON for 2 seconds. At this point the instrument restarts as for a new power ON.

The procedure is complete.
Note: The complete list of the default parameters is available in Chapter "Configuration".

## RWF55.5X \& RWF55.6X



Fixing system


Drilling dimensions:



## NAVIGATION MENU



RWF55 is preset good for $90 \%$ of applications. However, you can set or edit parameters as follow:

## Set-point: set or modification:

When the burner is in stand-by, (safety loop open, that is terminals 3-4/T1-T2 on the 7 pole plug open) push the Enter button: on the lower display (green) Opr appears; push Enter again and in the same display SP1 appears. Push Enter again and the lower display (green SP1) flashes. Using the up and down arrows change the set-point on the upper display (red).Push Enter to confirm and push ESC more times to get the home position.

## PID parameters set and modifications (PArA):

Push Enter button, on the green display Opr appears; using the down arrow, scroll until group PArA is reached and push Enter.
On the green display Pb1 e appears and on the red one the set parameter. Push is sequence the down or up arrow the menu is scrolled.
Push Enter to select and the arrows to choose the desired value. Enter to confirm

| Parameter | Display | Range | Factory setting | Remarks |
| :---: | :---: | :---: | :---: | :---: |
| Proportional band | Pb1 | 1... 9999 digit | 10 | Typical value for temperature |
| erivative action | dt | 0... 9999 sec. | 80 | Typical value for temperature |
| Integral action | rt | 0... 9999 sec. | 350 | Typical value for temperatureT |
| Dead band (*) | db | 0... 999,9 digit | 1 | Typical value |
| Servocontrol running time | tt | 10... 3000 sec. | 15 | Set servocontrol running time |
| Switch-on differential (*) | HYS1 | 0,0...-1999 digit | -5 | Value under setpoint below which the burner switches back on (1N-1P closes) |
| Switch-off differential $2^{\circ}$ stage (*) | HYS2 | 0,0 ... HYS3 | 3 | (enable only with parameter bin1 = 4) |
| Upper switch-off differential (*) | HYS3 | 0,0... 9999 digit | 5 | Value over setpoint above which the burner switches off ( $1 \mathrm{~N}-1 \mathrm{P}$ opens) |
| Switch-on differential on cooling controller (*) | HYS4 | 0,0... 9999 digit | 5 | Do not used $($ enable only with parameter $\mathbf{C A C t}=0)$ |
| Switch-off differential $2^{\circ}$ stage on cooling controller (*) | HYS5 | HYS6...0,0 digit | 5 | Do not used (enable only with parameter CACt $=0$ and parame- ter bin1=0) |
| Upper switch-off differential on cooling controller (*) | HYS6 | 0,0...-1999 digit | 5 | Do not used (enable only with parameter $\mathrm{CACt}=0$ ) |
| Delay modulation | q | 0,0... 999,9 digit | 0 | Do not alter |
| T Outside temperature Curve point 1 (*) | At1 | -40 ... 120 digit | -10 | First point of external temperature for climatic curve |
| Boiler temperature Curve point 1 (*) | Ht1 | SPL...SPH | 60 | Set-point temperature for the external temperature 1 |
| TT Outside temperature Curve point 2 (*) | At2 | -40 ... 120 digit | 20 | Second point of external temperature for climatic curve |
| Boiler temperature Curve point 2 (*) | Ht2 | SPL...SPH | 50 | Set-point temperature for the external temperature 2 |

(*) Parameters affected by setting of decimal place (ConF > dISP parameter dECP)

## Setting the kind of sensor to be connected to the device:

Push the Enter button: on the lower display (green) Opr appears. Using the up and down arrows find ConF. Push Enter to confirm. Now on the green display the group $\operatorname{InP}$ appears. Push Enter and $\operatorname{InP1}$ is displaied. Enter to confirm. You are inside InP1; the green display shows Sen1 (sensor type), while the red display shows the chosen sensor code Push Enter to enter the Sen1 parameter, then choose the desired sensor using the arrows. Push Enter to confirm and ESC to escape
Once selected the sensor, you can modify all the other parameters using up and down arrows according to the tables here below :

## ConF > InP >InP1

| Parameter | Value | Description |
| :---: | :---: | :---: |
| SEn1 | 1 | Pt100 3 wire |
| type of sensor for analog | 2 | Pt100 2 wire |
| input 1 | 3 | Pt1000 3 wire |
|  | 4 | Pt1000 2 wire |
|  | 5 | Ni1000 3 wire |
|  | 6 | Ni1000 2 wire |
|  | 7 | 0 $\div 135$ ohm |
|  | 8 | Cu-CuNi T |
|  | 9 | Fe-CuNi J |
|  | 10 | NiCr-Ni K |
|  | 11 | NiCrSi-NiSi N |
|  | 12 | Pt10Rh-Pt S |
|  | 13 | Pt13Rh-Pt R |
|  | 14 | Pt30Rh-Pt6Rh B |
|  | 15 | 0 $\div 20 \mathrm{~mA}$ |
|  | 16 | $4 \div 20 \mathrm{~mA}$ |
|  | 17 | $0 \div 10 \mathrm{~V}$ |
|  | 18 | 0 $\div 5 \mathrm{~V}$ |
|  | 19 | $1 \div 5 \mathrm{~V}$ |
| OFF1 | -1999..0.. +9999 | Correction value measured by the sensor |
| Sensor offset |  |  |
| SCL1 scale low level | -1999..0.. +9999 | minimum scale value(for input ohm, mA, V) |
| $\mathrm{SCH} 1$ <br> scale high level | -1999..100.. +9999 | maximum scale value(for input ohm, mA, V) |
| dF1 <br> digital filter | 0...0,6... 100 | Is used to adapt the digital 2nd order input filter (time in s; $0 \mathrm{~s}=$ filter off) |
| Unit <br> temperature unit | 1 | $\begin{aligned} & 1 \text { = degrees Celsius } \\ & 2 \text { = degrees Fahrenheit } \end{aligned}$ |

(bold = factory settings)

## ConF > InP >InP2

Input 2 : this input can be used to specify an external setpoint or carry out setpoint shifting

| Parameter | Value | Description |
| :---: | :---: | :---: |
| FnC2 | 0 | 0= no function |
|  | 1 | $1=$ external setpoint (display SPE) |
|  | 2 | 2 =setpoint shifting (display dSP) |
|  | 3 | 3 = angular positioning feedback |
| SEn2 tisensor type input 2 | 1 | $0 \div 20 \mathrm{~mA}$ |
|  | 2 | $4 \div 20 \mathrm{~mA}$ |
|  | 3 | $0 \div 10 \mathrm{~V}$ |
|  | 4 | $0 \div 5 \mathrm{~V}$ |
|  | 5 | $1 \div 5 \mathrm{~V}$ |
|  | 1 | $0 \div 20 \mathrm{~mA}$ |
| OFF2 | -1999..0.. +9999 | Correction value measured by the sensor |
| Sensor offset |  |  |
| SCL2 <br> scale low level | -1999..0.. +9999 | minimum scale value(for input ohm, mA, V) |
| SCH2 scale high level | -1999..100.. +9999 | maximum scale value(for input ohm, mA, V) |
| dF2 digital filter | 0...2... 100 | Is used to adapt the digital 2nd order input filter (time in s; $0 \mathrm{~s}=$ filter off) |

(bold = factory settings)

## ConF $>\operatorname{InP}>\operatorname{InP} 3$

Input 3: this input is used to acquire the outside temperature

| Parameter | Value | Description |
| :--- | :--- | :--- |
| SEn3 <br> sensor type input 3sensor <br> type input 2 | 0 | 1 |
|  | 2 | $0=$ |
| OFF3 <br> Sensor offset | $-1999 . .0 . .+9999$ | $2=$ wire |
| dF3 |  |  |
| digital filter |  |  |

[^3]
## ConF > Cntr

Here, the type of controller, operating action, setpoint limits and presettings for self-optimization are selected

| Parameter | Value | Description |
| :---: | :---: | :---: |
| CtYP controller type | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ | $\begin{aligned} & 1=3 \text {-position controller (open-stop-close) } \\ & 2=\text { continuative action controller }(0 \div 10 \mathrm{~V} \text { or } 4 \div 20 \mathrm{~mA}) \end{aligned}$ |
| CACt control action | $\begin{aligned} & 1 \\ & 0 \end{aligned}$ | $\begin{aligned} & 1=\text { heating controller } \\ & 0=\text { cooling controller } \end{aligned}$ |
| SPL <br> least value of the set-point range | -1999..0..+9999 | minimum set-point scale |
| SPH maximum value of the setpoint range | -1999..100..+999 | maximum set-point scale |
| Self-optimization | $\begin{aligned} & 0 \\ & 1 \end{aligned}$ | $\begin{aligned} & 0=\text { Free } \\ & 1=\text { Locked } \end{aligned}$ <br> Self-optimization can only be disabled or enabled via the ACS411 setup program. Self-optimization is also disabled when the parameter level is locked |
| oLLo <br> set-point limitation start, operation limit low | -1999... +9999 | lower working range limit |
| ```olHi set-point limitation end, operation limit high``` | -1999.... 9999 | upper working range limit |

(bold = factory settings)

## ConF > rAFC

Activation boiler shock termic protetion:
RWF55.. can activate the thermal shock protection only on sites where the set-point is lower than $250^{\circ} \mathrm{C}$ and according to rAL parameter

| Parameter | Value | Description |
| :---: | :---: | :---: |
| FnCT <br> type of contol | $\begin{aligned} & 0 \\ & 1 \\ & 2 \end{aligned}$ | ```tchoose type of range degrees/time \(0=\) deactived 1 = Kelvin degrees/minute 2 = Kelvin degrees/hour``` |
| rASL ramp rate | 0,0 ... 999,9 | Slope of thermal shock protection (only with functions 1 and 2) |
| toLP <br> tolerance band ramp | $2 \times(\mathrm{HYS} 1)=10 \ldots 9999$ | width of tolerance band (in K) about the set-point $0=$ tolerance band inactive |
| rAL ramp limit | 0... 250 | Ramp limit. When this value is lower than the temperature set-point, the RWF controls the output increasing the temp set point step by step according to rASL. If this is over the temp set point, the control is performed in cooling |

[^4]
## Alarm functionAF

The alarm function can be used to monitor the analog inputs. If the limit value is exceeded, multifunctional relay K6 (terminals $\mathbf{6 N}$ and $6 P$ ) is activated (depending on the switching characteristic)
The alarm function can have different switching functions (lk1 to lk8) and can be set to a deviation from the active setpoint or to a fixed limit value

Limit value AL relative to setpoint (x)


Fixed limit value AL

Ik7

lk8


ConF > AF

| Parameter | Value | Description |
| :---: | :---: | :---: |
| FnCt <br> type of control | 0 | 0 = Without function |
|  | 1 | $\mathrm{lk} 1=$ monitored input $\operatorname{lnP1}$ |
|  | 2 | $\mathrm{lk} 2=$ monitored input $\operatorname{lnP1}$ |
|  | 3 | IK3 $=$ monitored input InP1 |
|  | 4 | lk $4=$ monitored input InP1 |
|  | 5 | lk5 = monitored input InP1 |
|  | 7 | $1 \mathrm{k} 6=$ monitored input InP1 |
|  | 8 | 1k7 $=$ monitored input InP1 |
|  | 9 | 1k8 $=$ monitored input InP1 |
|  | 10 | 1k7 $=$ monitored input InP2 |
|  | 11 | 1k8 $=$ monitored input InP2 |
|  | 12 | $1 \mathrm{k} 7=$ monitored input $\operatorname{InP3}$ |
|  |  | $1 \mathrm{k} 8=$ monitored input $\operatorname{lnP} 3$ |
| Alarm value AL | -1999 ... | Limit value or deviation from setpoint to be monitored (see alarm functions lk1 to Ik8: limit value AL) <br> Limit value range for lk1 and Ik20 ... 9999 |
|  | 0 |  |
|  | 1999 |  |
| HySt <br> switching differential | 0... | Switching differential for limit value AL |
|  | 1... 9999 |  |
| ACrA response by out of range | 0 | Switched-off <br> ON <br> Switching state in the case of measuring range overshoot or undershoot (Out of Range) |
|  | 1 |  |
|  |  |  |

(bold = factory settings)

## ConF > OutP

For fuel-air ratio control purposes, the RWF55 has the binary outputs K2, K3 (terminals KQ,K2, K3) and the analog output (terminals A+, A-). The burner is released via relay K1 (terminals 1N, 1P) .
The binary outputs of the RWF55 offer no setting choices
The RWF55 has an analog output.
The analog output offers the following setting choices:

| Parameter | Value | Description |
| :---: | :---: | :---: |
| FnCt type of control | 1 | 1 = analog input 1 doubling with possibility to convert |
|  | 2 | $2=$ analog input 2 doubling with possibility to convert |
|  | 3 | 3 = analog input 3 doubling with possibility to convert |
|  | 4 | 4 = Controller's angular positioning is delivered (modulating controller) |
| SiGn type of output signal |  | physical output signal (terminals A+, A-) |
|  | 0 | $0=0 \div 20 \mathrm{~mA}$ |
|  | 1 | $1=4 \div 20 \mathrm{~mA}$ |
|  | 2 | $2=0 \div 10 \mathrm{VDC}$ |
| rOut value when out of input range | 0...101 | signal (in percent) when measurement range is crossed |
| oPnt zero point | -1999...0..+9999 | A value range of the output variable is assigned to a physical output signal (for $\mathrm{FnCt}=1,2,3$ ) |
| End end point | -1999...100..+9999 | A value range of the output variable is assigned to a physical output signal (for $\mathrm{FnCt}=1,2,3$ ) |

(bold = factory settings)

## ConF > binF

This setting decides on the use of the binary inputsD1, D2, DG
b

| Parameter | Value | Description |
| :---: | :---: | :---: |
| bin1 | 0 | 0 = without function |
| binary imput 1 (terminals DG | 1 | 1 = set-point changeover (SP1 / SP2) |
| -D1) | $\begin{aligned} & 2 \\ & 3 \end{aligned}$ | 2 = Iset-point shift (Opr > dSP parameter = value of set-point modify) 3 = input alarm |
| bin2 <br> binary imput 2 (terminalsk DG - D2) | 4 | $\begin{aligned} & \text { changeover of operating mode } \\ & \text { DG-D2 open = modulating operation } \\ & \text { DG-D2 close }=2 \text { stage operation } \end{aligned}$ |

(bold = factory settings)

## ConF > dISP

Both displays can be customized to suit your needs by configuring the displayed value, decimal, time out and blocking

| Parameter | Value | Description |
| :---: | :---: | :---: |
| diSU pper display (red) |  | Display value for upper display: |
|  | 0 | 0 = display power-off |
|  | 1 | 1 = analog input 1 ( $\mathrm{InP1}$ ) value |
|  | 2 | $2=$ analog input 2 ( InP 2 ) value |
|  | 3 | 3 = analog input 3 ( $\operatorname{lnP3}$ ) value |
|  | 6 | 4 = controller's angular positioning |
|  |  | 6 = set-point valueв |
|  |  | 7 = end value with thermal shock protection |
| diSL lower display (green) | 0123467 | Display value for lower display3: |
|  |  | 0 = display power-off |
|  |  | 1 = analog input 2 ( InP 2$)$ value |
|  |  | $2=$ analog input 2 ( InP 2$)$ value |
|  |  | 3 = analog input 2 ( InP 2 ) value |
|  |  | $4=$ controller's angular positioning |
|  |  | $6=$ set-point values |
|  |  | 7 = end value with thermal shock protection |
| tout <br> timeout | 0..180.. 250 | time (s) on completion of which the controller returns automatically to the basic display, if no button is pressed |
| dECP | 0 | $0=$ no decimal place |
| decimal point | 1 | 1 = one decimal place |
|  | 2 | 2 = two decimal place |
| CodE | 0 | 0 = no lockout |
| level lockout | 1 | 1 = configuration level lockout (ConF) |
|  | 2 | 2 = parameter and configuration level lockout (PArA \& ConF) |
|  | 3 | 3 = keyboard lockout |

(bold = factory settings)

## ConF > IntF

The controller can be integrated into a data network using an optional RS-485 (terminals R+ and R-) interface or an optional Profibus DP interface(only modeIRWF55.6x terminalsC1-C2-C3-C4)

| Parameter | Value | Description |
| :--- | :--- | :--- |
| bdrt | 0 | $0=4800$ baud |
| baudrate | 1 | $1=9600$ baud |
|  | 2 | $2=19200$ baud |
|  | 3 | $3=38400$ baud |
| Adr | $0 .$. | Address in the data network |
| Device address Modbus | $\mathbf{1 . .}$ |  |
|  | 254 | only withRWF55.6x |
| dP | $0 . .125$ | $0=$ swiched-off |
| Device address Profibus |  |  |
| dtt | $0 .$. |  |
| Remote detection time | $30 .$. |  |
|  | 7200 s |  |

(bold = factory settings)

## Manual control :

In order to manual change the burner load, while firing keep pushing the ESC button for more than 5 s ; on the lower green display Hand appears.
using the UP and DOWN arrows, the load varies.
Keep pushing the ESC button for getting the normal operation again.
NB: every time the device shuts the burner down (start led switched off - contact $1 \mathrm{~N}-1 \mathrm{P}$ open), the manual control is not active.

## Device self-setting (auto-tuning):

If the burner in the steady state does not respond properly to heat generator requests, you can activate the Device's self-setting function, which recalculates PID values for its operation, deciding which are most suitable for the specific kind of request


Follow the below instructions:
push the UP and DOWN arrows for more than 5 s ; on the green lower display tUnE appears. Now the device pushes the burner to increase and decrease its output. During this time, the device calculates PID parameters ( $\mathbf{P b 1} 1 \mathbf{d t}$ and $\mathbf{r t}$ ). After the calculations, the tUnE is automatically deactivated and the device has already stored them.
In order to stop the Auto-tuning function while it works, push again the UP and DOWN arrows for more than 5 s . The calculated PID parameters can be manually modified following the previously described instructions.

## Display of software version :

The software version is shown by pushing Enter + UP arrow on the upper display.


## Weather-compensated setpoint shifting(climatic regulation):

The RWF55 can be configured so that weather-compensated setpoint shifting is activated when an LG-Ni1000 outside sensor or a Pt 1000 is connected (see parameter $\operatorname{lnP} 3$ ).
To take into account the time response of a building, weather-compensated setpoint shifting uses the attenuated outside temperature rather than the current outside temperature
The minimum and maximum setpoints can be set using the lower setpoint limit SPL and the upper setpoint limit SPH of the menù Crtr. The system also prevents the lower working range limit oLLo and upper working range limit oLHi from exceeding/dropping below the system temperature limits.

The heating curve describes the relationship between the boiler temperature setpoint and the outside temperature. It is defined by 2 curve points. For 2 outside temperatures, the user defines the boiler temperature setpoint that is required in each case. The heating curve for the weather-compensated setpoint is calculated on this basis. The effective boiler temperature setpoint is limited by the upper setpoint limit SPH and the lower setpoint limit SPL.


For setting climatic regulation function set:
PArA > parametersAt1, Ht1, At2, Ht2
ConF $>\operatorname{InP}>\operatorname{lnP} 3$ parametersSEn3, FnC3 = 1 (Weather-compensated setpoint).

## Modbus interface

The tables that follow in this chapter specify the addresses of the readable and writable words that the customer is able to access. The customer may read and/or write the values using SCADA programs, PLCs, or similar.
The entries under Access have the following meanings:
R/O Read Only, value can only be read
R/W Read/Write, value can be read and written
The number of characters specified under Data type in the case of character strings includes the final $\backslash 0$.
Char10 means that the text is up to 9 characters long. The final $\backslash 0$ character is then added to this

## User level

| Address | Access | Data type | Signal reference | Parameter |
| :--- | :--- | :--- | :--- | :--- |
| $0 \times 0000$ | R/O | Float | X1 | Analog input InP1 |
| $0 \times 0002$ | R/O | Float | X2 | Analog input InP2 |
| $0 \times 0004$ | R/O | Float | X3 | Analog input InP2 |
| $0 \times 0006$ | R/O | Float | WR | Actual setpoint |
| $0 \times 0008$ | R/W | Float | SP1 | Setpoint 1 |
| $0 \times 000$ A | R/W | Float | SP2 (= dSP) | Setpoint 2 |
| $0 \times 1035$ | R/O | Float | --- | Analog input InP3 (unfiltered) |
| $0 \times 1043$ | R/O | Float | --- | Actual angular positioning |
| $0 \times 1058$ | R/O | Word | B1 | Burner alarm |

## Parameter level

| Address | Access | Data type | Signal reference | Parameter |
| :--- | :--- | :--- | :--- | :--- |
| $0 \times 3000$ | R/W | Float | Pb1 | Proportional range 1 |
| $0 \times 3004$ | R/W | Float | dt | Derivative action time |
| $0 \times 3006$ | R/W | Float | rt | Integral action time |
| $0 \times 300$ C | R/W | Float | db | Dead band |
| $0 \times 3012$ | R/W | Word | tt | Controlling element running time |
|  |  |  |  |  |
| $0 \times 3016$ | R/W | Float | HYS1 | Switch-on threshold |
| $0 \times 3018$ | R/W | Float | HYS2 | Switch-off threshold down |
| $0 \times 301$ A | R/W | Float | HYS3 | Switch-off threshold up |
| $0 \times 301$ C | R/W | Float | HYS4 | Switch-on threshold (cooling) |
| $0 \times 301 E$ | R/W | Float | HYS5 | Switch-off threshold down (cooling) |
| $0 \times 3020$ | R/W | Float | HYS6 | Switch-off threshold up (cooling) |
| $0 \times 3022$ | R/W | Float | q | Reaction threshold |
|  |  |  |  |  |
| $0 \times 3080$ | R/W | Float | At1 | Outside temperature 1 |
| $0 \times 3082$ | R/W | Float | Ht2 | Boiler temperature 1 |
| $0 \times 3084$ | R/W | Float | At2 | Outside temperature 2 |
| $0 \times 3086$ | R/W | Float | Ht2 | Boiler temperature 2 |

Configuration level

| Address | Access | Data type | Signal reference | Parameter |
| :--- | :--- | :--- | :--- | :--- |
| $0 \times 3426$ | R/W | Float | SCL1 | Start of display input 1 |
| $0 \times 3428$ | R/W | Float | SCH1 | End of display input 1 |
| $0 \times 3432$ | R/W | Float | SCL2 | Start value input 2 |
| $0 \times 3434$ | R/W | Float | SCH2 | End value input 2 |
| $0 \times 3486$ | R/W | Float | SPL | Start of setpoint limitation |
| $0 \times 3488$ | R/W | Float | SPH | End of setpoint limitation |
| $0 \times 342$ A | R/W | Float | OFFS1 | Offset input E1 |
| $0 \times 3436$ | R/W | Float | OFFS2 | Offset input E2 |
| $0 \times 343$ A | R/W | Float | OFFS3 | Offset input E3 |
|  |  |  |  |  |
| $0 \times 1063$ | R/W | Word | FnCt | Ramp function |
| $0 \times 1065$ | R/W | Float | rASL | Ramp slope |
| $0 \times 1067$ | R/W | Float | toLP | Tolerance band ramp |
| $0 \times 1069$ | R/W | Float | rAL | Limit value |
| $0 \times 1075$ | R/W | Float | dtt | Remote Detection Timer |
|  |  |  |  |  |
| $0 \times 1077$ | R/W | Float | dF1 | Filter constant input 1 |
| $0 \times 1079$ | R/W | Float | dF2 | Filter constant input 2 |
| $0 \times 107 B$ | R/W | Float | dF3 | Filter constant input 3 |
| $0 \times 107 D$ | R/O | Float | oLLo | Lower working range limit |
| $0 \times 107 F$ | R/O | Float | oLHi | Upper working range limit |
|  |  |  |  |  |
| $0 \times 106 D$ | R/W | Word | FnCt | Alarm relay function |
| $0 \times 106 F$ | R/W | Float | AL | Alarm relay limit value (limit value alarm) |
| $0 \times 1071$ | R/W | Float | HYSt | Alarm relay hysteresis |

## Remote operation

| Address | Access | Data type | Signal reference | Parameter |
| :--- | :--- | :--- | :--- | :--- |
| $0 \times 0500$ | R/W | Word | REM | Activation remote operation * |
| $0 \times 0501$ | R/W | Word | rOFF | Controller OFF in remote setpoint ** |
| $0 \times 0502$ | R/W | Float | rHYS1 | Switch-on threshold remote |
| $0 \times 0504$ | R/W | Float | rHYS2 | Switch-off threshold down remote |
| $0 \times 0506$ | R/W | Float | rHYS3 | Switch-off threshold up remote |
| $0 \times 0508$ | R/W | Float | SPr | Setpoint remote |
|  |  |  |  |  |
| $0 \times 050$ A | R/W | Word | RK1 | Burner release remote operation |
| 0x050B | R/W | Word | RK2 | Relay K2 remote operation |
| 0x050C | R/W | Word | RK3 | Relay K3 remote operation |
| 0x050D | R/W | Word | RK6 | Relay K6 remote operation |
| $0 \times 050 E$ | R/W | Word | rStEP | Step-by-step control remote operation |
| $0 \times 050 F$ | R/W | Float | rY | Angular positioning output remote operation |
| $0 \times 0511$ | R/W | Float | rHYS4 | Switch-on threshold remote (cooling) |
| $0 \times 0513$ | R/W | Float | rHYS5 | Switch-off threshold down remote (cooling) |
| $0 \times 0515$ | R/W | Float | rHYS6 | Switch-off threshold up remote (cooling) |

## Legend

* $=$ Local
** $=$ Controller OFF

Dati dell'apparecchio

| Address | Access | Data type | Signal reference | Parameter |
| :--- | :--- | :--- | :--- | :--- |
| $0 \times 8000$ | R/O | Char12 | --- | Software version |
| $0 \times 8006$ | R/O | Char14 | --- | VdN number |

## Stato dell'apparecchio

| Address | Access | Data type | Signal reference | Parameter |
| :---: | :---: | :---: | :---: | :---: |
| 0x0200 | R/O | Word | --- | Outputs and states |
|  |  |  | Bit 0 | Output 1 |
|  |  |  | Bit 1 | Output 3 |
|  |  |  | Bit 2 | Output 2 |
|  |  |  | Bit 3 | Output 4 |
|  |  |  | Bit 8 | Hysteresis limitation |
|  |  |  | Bit 9 | Control system |
|  |  |  | Bit 10 | Self-optimization |
|  |  |  | Bit 11 | Second setpoint |
|  |  |  | Bit 12 | Measuring range overshoot InP1 |
|  |  |  | Bit 13 | Measuring range overshoot InP2 |
|  |  |  | Bit 14 | Measuring range overshoot InP3 |
|  |  |  | Bit 15 | Calibration mode |
|  |  |  |  |  |
| 0x0201 | R/O | Word | --- | Binary signals and hardware detection |
|  |  |  | Bit 0 | Operation mode 2-stage |
|  |  |  | Bit 1 | Manual mode |
|  |  |  | Bit 2 | Binary input D1 |
|  |  |  | Bit 3 | Binary input D2 |
|  |  |  | Bit 4 | Thermostat function |
|  |  |  | Bit 5 | First controller output |
|  |  |  | Bit 6 | Second controller output |
|  |  |  | Bit 7 | Alarm relay |
|  |  |  | Bit 13 | Analog output available |
|  |  |  | Bit 14 | Interface available |

Electric connections :

With 7 pins connector version


With terminals version


Corrispondences bornes entre RWF55.5x y RWF40.0x0Matches terminals betweenRWF55.5x and RWF40.0x0

| 0 | SIEMENS RWF55.5x |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\begin{aligned} & k a \\ & \varnothing \end{aligned}$ | $\begin{aligned} & \text { K2 } \\ & \varnothing \end{aligned}$ | $\begin{aligned} & \text { K3 } \\ & \varnothing \end{aligned}$ | $\begin{aligned} & 1 \mathrm{~N} \\ & \varnothing \end{aligned}$ | $\begin{aligned} & 1 P \\ & \varnothing \end{aligned}$ | $\begin{aligned} & \mathrm{L} 1 \\ & \varnothing \end{aligned}$ | $\stackrel{N}{\varnothing}$ |  | $\varnothing_{\varnothing}^{13}$ | $\varnothing$ | $\stackrel{\square}{\varnothing}+$ | $\begin{aligned} & 14 \\ & \varnothing \end{aligned}$ | $\stackrel{12}{\varnothing}$ | $\begin{aligned} & 11 \\ & \varnothing \end{aligned}$ |
| SIEMENS RWF 40.0 xx |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 0 | $\stackrel{Q}{\varnothing}$ | $\begin{aligned} & Y 1 \\ & \varnothing \end{aligned}$ | $\begin{aligned} & Y 2 \\ & \varnothing \end{aligned}$ | $\begin{aligned} & \text { Q13 } \\ & \varnothing \end{aligned}$ | $\begin{aligned} & Q 14 \\ & \varnothing \end{aligned}$ | $\stackrel{\mathrm{L1}}{\varnothing}$ | $\stackrel{N}{\varnothing}$ | $\stackrel{P E}{\varnothing}$ | $\begin{aligned} & \text { U1 } \\ & \varnothing \end{aligned}$ | $\stackrel{\text { G- }}{\varnothing}$ | $\stackrel{G+}{\varnothing}$ | $\begin{aligned} & \text { M1 } \\ & \varnothing \end{aligned}$ | $\stackrel{11}{\varnothing}$ | $\begin{aligned} & \text { G1+ } \\ & \varnothing \end{aligned}$ |

Parameters summarising for RWF55.xx :

| Navigation menù <br> Types of probe | ConF |  |  |  |  | ConF |  |  | PArA |  |  |  |  |  | Opr |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Inp |  |  |  |  | Cntr |  | diSP |  |  |  |  |  |  |  |
|  | Inp1 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | SEn1 | OFF1 | SCL | SCH | Unit | SPL | SPH | dECP | Pb. 1 | dt | rt | tt | HYS1 (*) | HYS3 (*) | SP1 (*) |
| Siemens QAE2120... | 6 | 0 | needless | needless | 1 | 30 | 95 | 1 | 10 | 80 | 350 | (\#) | -5 | 5 | $80^{\circ} \mathrm{C}$ |
| Siemens QAM2120.. | 6 | 0 | needless | needless | 1 | 0 | 80 | 1 | 10 | 80 | 350 | (\#) | -2,5 | 2,5 | $40^{\circ} \mathrm{C}$ |
| Pt1000 ( $130^{\circ} \mathrm{C}$ max.) | 4 | 0 | needless | needless | 1 | 30 | 95 | 1 | 10 | 80 | 350 | (\#) | -5 | 5 | $80^{\circ} \mathrm{C}$ |
| Pt1000 (350 ${ }^{\circ} \mathrm{C}$ max.) | 4 | 0 | needless | needless | 1 | 0 | 350 | 1 | 10 | 80 | 350 | (\#) | -5 | 10 | $80^{\circ} \mathrm{C}$ |
| Pt100 ( $130^{\circ} \mathrm{C}$ max.) | 1 | 0 | needless | needless | 1 | 0 | 95 | 1 | 10 | 80 | 350 | (\#) | -5 | 5 | $80^{\circ} \mathrm{C}$ |
| Pt100 ( $350^{\circ} \mathrm{C}$ max) | 1 | 0 | needless | needless | 1 | 0 | 350 | 1 | 10 | 80 | 350 | (\#) | -5 | 10 | $80^{\circ} \mathrm{C}$ |
| Probe4 $\div 20 \mathrm{~mA} \mathrm{/} \mathrm{0} ~ 1,6 \mathrm{bar}$ | 16 | 0 | 0 | 160 | needless | 0 | 160 | 0 | 5 | 20 | 80 | (\#) | 0 | 20 | 100 kPa |
| Probe $4 \div 20 \mathrm{~mA} \mathrm{/} \mathrm{0} \div 3$ bar | 16 | 0 | 0 | 300 | needless | 0 | 300 | 0 | 5 | 20 | 80 | (\#) | 0 | 20 | 200 kPa |
| Probe $4 \div 20 \mathrm{~mA} \mathrm{/} \mathrm{0} ~+10 \mathrm{bar}$ | 16 | 0 | 0 | 1000 | needless | 0 | 1000 | 0 | 5 | 20 | 80 | (\#) | 0 | 50 | 600 kPa |
| Probe 4 $\div 20 \mathrm{~mA} \mathrm{/} \mathrm{0} ~+16 \mathrm{bar}$ | 16 | 0 | 0 | 1600 | needless | 0 | 1600 | 0 | 5 | 20 | 80 | (\#) | 0 | 80 | 600 kPa |
| Probe 4 $\div 20 \mathrm{~mA} / 0 \div 25$ bar | 16 | 0 | 0 | 2500 | needless | 0 | 2500 | 0 | 5 | 20 | 80 | (\#) | 0 | 125 | 600 kPa |
| Probe 4 $\div 20 \mathrm{~mA} \mathrm{/} \mathrm{0} ~+40$ bar | 16 | 0 | 0 | 4000 | needless | 0 | 4000 | 0 | 5 | 20 | 80 | (\#) | 0 | 200 | 600 kPa |
| Probe $4 \div 20 \mathrm{~mA} / 0 \div 60 \mathrm{PSI}$ | 16 | 0 | 0 | 600 | needless | 0 | 600 | 0 | 5 | 20 | 80 | (\#) | 0 | 30 | 300 (30PSI) |
| Probe4 $\div 20 \mathrm{~mA} \mathrm{/} \mathrm{0} \div 200 \mathrm{PSI}$ | 16 | 0 | 0 | 2000 | needless | 0 | 2000 | 0 | 5 | 20 | 80 | (\#) | 0 | 75 | 600 (60PSI) |
| Probe4 $\div 20 \mathrm{~mA} \mathrm{/} \mathrm{0} \div 300 \mathrm{PSI}$ | 16 | 0 | 0 | 3000 | needless | 0 | 3000 | 0 | 5 | 20 | 80 | (\#) | 0 | 120 | 600 (60PSI) |
| Siemens QBE2002 P4 | 17 | 0 | 0 | 400 | needless | 0 | 400 | 0 | 5 | 20 | 80 | (\#) | 0 | 20 | 200 kPa |
| Siemens QBE2002 P10 | 17 | 0 | 0 | 1000 | needless | 0 | 1000 | 0 | 5 | 20 | 80 | (\#) | 0 | 50 | 600 kPa |
| Siemens QBE2002 P16 | 17 | 0 | 0 | 1600 | needless | 0 | 1600 | 0 | 5 | 20 | 80 | (\#) | 0 | 80 | 600 kPa |
| Siemens QBE2002 P25 | 17 | 0 | 0 | 2500 | needless | 0 | 2500 | 0 | 5 | 20 | 80 | (\#) | 0 | 125 | 600 kPa |
| Siemens QBE2002 P40 | 17 | 0 | 0 | 4000 | needless | 0 | 4000 | 0 | 5 | 20 | 80 | (\#) | 0 | 200 | 600 kPa |
| Signal 0 $\div 10 \mathrm{~V}$ | 17 | 0 | needless | needless | needless | needless | needless | needless | 5 | 20 | 80 | (\#) |  |  |  |
| Signal 4 $\div 20 \mathrm{~mA}$ | 16 | 0 | needless | needless | needless | needless | needless | needless | 5 | 20 | 80 | (\#) |  |  |  |

## NOTE:

(\#) tt - servo control run time
SQL33 ; STM30; SQM10; SQM40; SQM50; SQM54 = 30 (secondi) $\quad-\quad$ STA12B3.41; SQN30.251; SQN72.4A4A20 = 12 (secondi)
$\left(^{*}\right)$ These values are factory set - values must be set during operation at the plant based on the real working temperature/pressure value.

## WARNING

With pressure probes in bar the parameters SP1, SCH, SCL, HYS1, HYS3 must be set and displayed in kPa (kilo Pascal); 1bar $=100,000 \mathrm{~Pa}=100 \mathrm{kPa}$. With pressure probes in PSI the parameters SP1, SCH, SCL, HYS1, HYS3 must be set and displayed in PSI x10 (example: 150PSI > I display 1500).

To assure the utmost comfort, the control system needs reliable information, which can be obtained provided the sensors have been installed correctly. Sensors measure and transmit all variations encountered at their location.
Measurement is taken based on design features (time constant) and according to specific operating conditions.With wiring run in raceways, the sheath (or pipe) containing the wires must be plugged at the sensor's terminal board so that currents of air cannot affect the sensor's measurements.

## Ambient probes (or ambient thermostats)

## Installation

The sensors (or room thermostats) must be located in reference rooms in a position where they can take real temperature measurements without being affected by foreign factors.


It's good to be admired ...even better to be effective
Heating systems: the room sensor must not be installed in rooms with heating units complete with thermostatic valves. Avoid all sources of heat foreign to the system.


## Location

On an inner wall on the other side of the room to heating unitsheight above floor 1.5 m , at least 1.5 m away from external sources of heat (or cold).


## Installation position to be avoided

near shelving or alcoves and recesses, near doors or win-dows, inside outer walls exposed to solar radiation or currents of cold air, on inner walls with heating system pipes, domestic hot water pipes, or cooling system pipes running through them.


Outside probes (weather)Installation
In heating or air-conditioning systems featuring adjustment in response to outside temperature, the sensor's positioning is of paramount importance.


General rule: en on the outer wall of the building where the living rooms are, never on the south-facing wall or in a position where they will be affected by morning sun. If in any doubt, place them on the north or north-east façade.

## Positions to be avoidedH



Avoid installing near windows, vents, outside the boiler room, on chimney breasts or where they are protected by balconies, cantilever roofs.
The sensor must not be painted (measurement error).

## Duct or pipe sensors

## Installing temperature sensors

For measuring outlet air:
"after delivery fan or
"after coil to be controlled, at a distance of at least 0,5 m
For measuring room temperature:
"before return air intake fan and near room's return airintake.
For measuring saturation temperature: after mist eliminator.


Bend 0.4 m sensor by hand (never use tools) as illustrated .


Use whole cross-section of duct, min. distance from walls 50 mm , radius of curvature 10 mm for 2 m or 6 m sensors

## Installing pressure sensors

A - installation on ducts carrying fluids at max. temperature $80^{\circ} \mathrm{C}$
B - installation on ducts at temperature over $80^{\circ} \mathrm{C}$ and for refrigerants
C - installation on ducts at high temperatures :
"increase length of siphon
"place sensor at side to prevent it being hit by hot air coming from the pipe.


Installing differential pressure sensors for water
Installation with casing facing down not allowed.
With temperature over $80^{\circ} \mathrm{C}$, siphons are needed.
To avoid damaging the sensor, you must comply with the following instructions:
when installing: make sure pressure difference is not greater than the value permitted by the sensor
when there are high static pressures, make sure you insert shutoff valves A-B-C.

## Putting into operation

Start disable
1=open C1=open C
2=open A2=close B
3=open B3=close A
4= close C


## Immersion or strap-on sensors



Placing the probes (QAD22.../QAE21.../QAP21.../RCA...)

With pumps on outlet
with 3 ways valves / with 4 ways valves


## With pumps on return

with 3 ways valves / with 4 ways valves


## Immersion probes installation

Sensors must be installed on the stretch of pipe in which fluid circulates all the time.
The rigid stem (sensing element doing the measuring) must be inserted by at least 75 mm and must face the direction of flow.
Recommended locations: on a bend or on a straight stretch of pipe but tilted by $45^{\circ}$ and against the flow of fluid.
Protect them to prevent water from infiltrating (dripping gates, condensation from pipes etc.).

## Installing QAD2.. strap-on sensors

Make sure fluid is circulating in the chosen location.
Eliminate insulation and paintwork (including rust inhibitor) on a min. 100 mm length of pipe.
Sensors come with straps for pipes up to 100 mm in diameter.

## Strap-on or immersion sensors?

## QAD2.. strap-on sensors

Advantages :

- 10 sec. time constant
- Installed with system running (no plumbing work)
- Installation can be changed easily if it proves incorrect

ПLimits:

- Suitable for pipe diameters max. 100 mm
- Can be affected by currents of air etc.


## QAE2... immersion sensors

Advantages:

- Measure "mean" fluid temperature
- No external influence on measurement such as: currents of air, nearby pipes etc.


## Limits:

- Time constant with sheath: 20 sec.
- Hard to change installation position if it proves incorrect

Installing differential pressure probes for air


A - Control a filter (clogging)


B - Control a fan (upstream/downstream)


## Legend

y $\quad \mathrm{Kg} / \mathrm{m} 3$, specific weight of air
q $\mathrm{m} / \mathrm{s}$, air speed
g $\quad 9.81 \mathrm{~m} / \mathrm{s} 2$ gravity acceleration
Pd mm C.A., dynamic pressure

## Measuring total pressure



C - Measurement of difference in pressure between two ducts


D - Measurement of difference in pressure between two rooms or of inside of duct and outside

Note: Specifications and data subject to change. Errors and omissions excepted.


[^0]:    *** See "NETWORK PRESSURE - RATE CURVES" on page 10

[^1]:    *** See "NETWORK PRESSURE - RATE CURVES" on page 10

[^2]:    * In this case insert an RC filter (see Fig. 64)

[^3]:    (bold = factory settings)

[^4]:    (bold = factory settings)

